CMOS 8-Bit Microcontroller

TMP86CM41F

The TMP86CM41F is the high-speed, high-performance and low power consumption 8-bit microcomputer, including large-capacity ROM, RAM driver, multi-function timer/counter, serial interface (UART/SIO), a 10bit AD converter and two clock generators on chip.

Product No.	oduct No. ROM RAM		Package	Flash
TMP86CM41F	32K × 8 bits	1K × 8 bits	P-QFP64-1414-0.80A	TMP86FS41F

Features

◆ 8-bit single chip microcomputer TLCS-870/C series

 Instruction execution time: 0.25 μs (at 16 MHz) $122 \mu s$ (at 32.768 kHz)

◆ 132 types and 731 basic instructions

21 interrupt sources (External: 6, Internal: 15)

◆ Input/Output ports (55 pins) High current output: 8 pins (typ. 20 mA)

◆ 16-bit timer counter: 2 ch

- Timer, Event counter, Pulse width measurement, Programmable pulse Generator (PPG), External-triggered timer, Window modes
- ◆ 8-bit timer counter: 4 ch
 - Timer, Event counter, Pulse Width Modulation (PWM) output, Programmable Divider Output (PDO), PPG modes
- ◆ Time Base Timer (TBT)
- ◆ Divider output function

TMP86CM41F

For a discussion of how the reliability of microcontrollers can be predicted, please refer to Section 1.3 of the chapter entitled Quality and Reliability Assurance / Handling Precautions.

Quality and Reliability Assurance / Handling Precautions.

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The TOSHIBA products listed in this document are intended for usage in general electronics applications (computer, processors) and continuous applications (computer, processors) and continuous applications (computer, processors) and continuous applications (computer, processors). These

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The information contained herein is subject to change without notice.

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P-QFP64-1414-0.80A

- ◆ Watchdog Timer
 - Interrupt source/reset output (programmable)
- ♦ Serial interface
 - 8-bit SIO: 1ch
 - 8-bit UART: 1ch (IrDA output, selection of used pin)
- ◆ 10-bit successive approximation type AD converter
 - Analog input: 16 ch
- ♦ Key on wake up: 4 ch
- ♦ Dual clock operation
 - Single/Dual-clock mode
- ♦ Nine power saving operating modes
 - STOP mode: Oscillation stops. Battery/Capacitor back-up. Port output hold/High-impedance.
 - SLOW 1, 2 mode: Low power consumption operation using low-frequency clock (32.768 kHz)
 - IDLE 0 mode: CPU stops, and peripherals operate using high-frequency clock of Time-Base-
 - Timer. Release by INTTBT interrupt.
 - IDLE 1 mode: CPU stops, and peripherals operate using high-frequency clock. Release by
 - interrupts.
 - IDLE 2 mode: CPU stops, and peripherals operate using high and low frequency clock. Release
 - by interrupts.
 - SLEEP 0 mode: CPU stops, and peripherals operate using low-frequency clock of Time-Base-
 - Timer. Release by INTTBT interrupt.
 - SLEEP 1 mode: CPU stops, and peripherals operate using low-frequency clock. Release by
 - interrupts.
 - SLEEP 2 mode: CPU stops, and peripherals operate using high and low frequency clock. Release
 - by interrupts.
- ♦ Wide operating voltage: 4.5 to 5.5 V at 16 MHz/32.768 kHz

Difference between TMP86CM41F, TMP86CS41F, TMP86FS41F

The functions and the electrical characteristics between above products have some difference. Please refer the notice below.

1. Functions

a) Memory size

Product No.	ROM	RAM
TMP86CM41F	32 kbyte	1 kbyte
TMP86CS41F	60 kbyte	2 kbyte
TMP86FS41F	60 kbyte	2 kbyte

b) Clock gear

Product No.	Clock gear
TMP86CM41F	Support
TMP86CS41F	Not support
TMP86FS41F	Support

When developing a software for TMP86CS41F by using TMP86FS41F, CGCR < FCGCK > must be set to "000".

TMP86CM41F/TMP86FS41F



c) Port5

Product No.	Input
TMP86CM41F	CMOS
TMP86CS41F TMP86FS41F	Schmitt Schmitt

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2. Electrical Characteristics

The some electrical characteristics except below are different. Please refer the technical data book of TMP86CM41F, TMP86CS41F and TMP86FS41F.

a) Absolute maximum ratings (VSS = 0)

Damamakan	Cl1	D:		Rating				
Parameter	Symbol	Pin	TMP86CM41F	TMP86CS41F	TMP86FS41F	Unit		
Output current (Total)	Σ IOUT1		80	60	80			
	Σ IOUT2	P5 (Large current)	120	60	120	mA		
Operating Temperature	Topr		-40 to 85	-40 to 85	-20 to 70	°C		

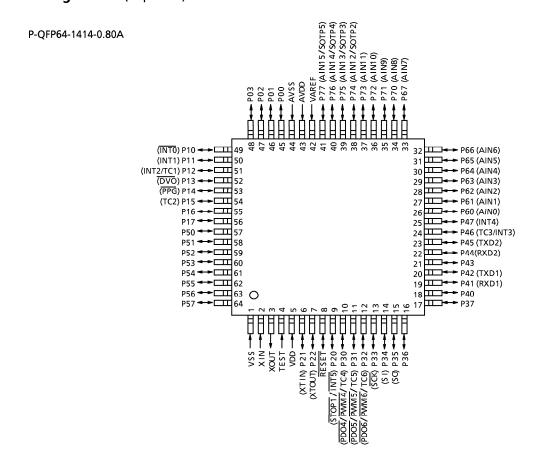
b) Recommended operating condition

The supply voltage and the clock frequency have difference.

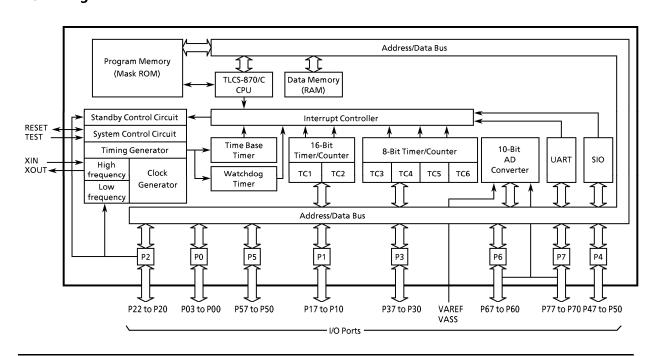
Recommended operating condition (Vss=0 V, Topr=-40 to 85°C (Except TMP86FS41F))

- ·	Parameter Symbol Pin Condition		TMP86CM41F		TMP86CS41F		TMP86FS41F		TT:4		
Parameter	Symbol	Pin		Condition		Max	Min	Max	Min	Max	Unit
			fc = 1 to 16 MHz	NOMAL1, 2 mode			4.5				
		fc=1 to 8 MHz	IDLE0, 1, 2 mode								
Supply	VDD		f. 20 760 LH	SLOW1, 2 mode	4.5	5.5	2.7	5.5	4.5	5.5	v
voltage			fs = 32.768 kHz	SLEEP0, 1, 2 mode							
				STOP mode	2.0		2.0				
	fc	XIN,	VDD=	4.5 to 5.5 V	1.0	16.0	1.0	16.0	1.0	16.0	MHz
Clock	16	XOUT	VDD=	2.7 to 5.5 V	_	_	1.0	8.0	_	ı	MITIZ
frequency	£	XIN,	VDD=	4.5 to 5.5 V	30.0	34.0	20.0	24.0	30.0	34.0	kHz
	fs XOUT		VDD=2.7 to 5.5 V		_	_	30.0	34.0	_		KIIZ

Pin Assignments (Top View)



Block Diagram



Pin Names and Functions (1/2)

Pin Name	Input/Output	Function					
P00 P01 P02 P03	I/O	4-bit I/O port. Each bit of these ports can be individually configured as an input or an output under software control.	-				
P10 (INTO) P11 (INT1) P12 (INT2/TC1) P13 (DVO) P14 (PPG) P15 (TC2) P16 P17	I/O (Input) I/O (Output) I/O (Input) I/O	8-bit I/O port with latch. Each bit of these ports can be individually configured as an input or an output under software control. When used as divider output, PPG output, the latch of used bit must be set to "1", and used bits are configured outputs.	External Interrupt input External Interrupt input External interrupt input, Timer/Counter input Divider output PPG output Timer/Counter input -				
P20 (ĪNT5/STOP1) P21 (XTIN) P22 (XTOUT)	I/O (Input) I/O (Input/Output)	3-bit I/O port with latch. When used as input port, external interrupt input, and STOP mode release signal input, the latch must be set to "1".	External interrupt input, STOP mode release signal input Low Frequency Clock input Low Frequency Clock output				
P30 (TC4/PWM4/PDO4) P31 (TC5/PWM5/PDO5) P32 (TC6/PWM6/PDO6) P33 (SCK) P34 (SI) P35 (SO) P36	I/O (Input/Output/ Output) I/O (I/O) I/O (Input) I/O (Output)	8-bit I/O port with latch. Each bit of these ports can be individually configured as an input or an output under software control. When used as timer/Counter input, SI, used bits are configured inputs. When used as PWM output, PDO output, and SO, used bits are configured outputs.	Timer/Counter input PWM output PDO output SIO input/output				
P40 P41 (RXD1) P42 (TXD1) P43 P44 (RXD2) P45 (TXD2) P46 (TC3/INT3)	I/O I/O (Input) I/O (Output) I/O I/O (Input) I/O (Output) I/O (Output)	8-bit I/O port with latch. Each bit of these ports can be individually configured as an input or an output under software control. When used as UART mode, the latch must be set to "1". When used as Open-Drain output, P4ODE and P4CR must be set to "1".	UART Data input UART Data output UART Data output UART Data input UART Data output Timer/Counter input External Interrupt input External Interrupt input				
P50 P51 P52 P53 P54 P55 P56 P57	1/0	8-bit I/O port. Each bit of these ports can be individually configured as an input or output under software control. These ports are High current output ports, can be drive LED direct.	—				

Pin Names and Functions (2/2)

Pin Name	Input/Output	Function					
P60 (AIN0) P61 (AIN1) P62 (AIN2) P63 (AIN3) P64 (AIN4) P65 (AIN5) P66 (AIN6) P67 (AIN7)	I/O (Input)	8-bit I/O port. Each bit of these ports can be individually configured as an input or output under software control.	AD Convertor analog inputs				
P70 (AIN8) P71 (AIN9) P72 (AIN10) P73 (AIN11) P74 (AIN12/STOP2) P75 (AIN13/STOP3) P76 (AIN14/STOP4) P77 (AIN15/STOP5)	I/O (Input)	8-bit I/O port. Each bit of these ports can be individually configured as an input or output under software control.	AD Convertor analog inputs AD Convertor analog input STOP mode release signal input				
TEST	Input	Test pin for out-going test. Be fixed to Lo	ow.				
RESET	I/O	Reset signal input or watchdog timer out	put/address-trap-reset output.				
XIN	Input Output	Resonator connecting pins for high-fre XIN is used and XOUT is opened.	quency clock. For inputting external clock,				
VSS VDD AVSS AVDD VAREF	Power Supply	0.0 [V] (GND) + 5.0 [V] 0.0 [V] (GND) + 5.0 [V] AD circuit power supply Analog reference voltage inputs (High, Low)					

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Operational Description

1. CPU Core Functions

The CPU core consists of a CPU, a system clock controller, and an interrupt controller.

This section provides a description of the CPU core, the program memory, the data memory, and the reset circuit.

1.1 Memory Address Map

The TMP86CM41 memory consist of 4 blocks: ROM, RAM, DBR (Data Buffer Register) and SFR (Special Function Register). They are all mapped in 64 Kbyte address space. Figure 1-1 shows the TMP86CM41 memory address map. The general-purpose register banks are not assigned to the RAM address space.

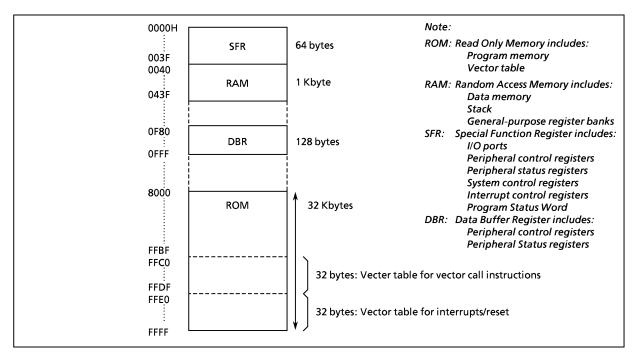


Figure 1-1. Memory Address Maps

1.2 Program Memory (ROM)

The TMP86CM41 has a $32K \times 8$ -bit (address 8000H to FFFFH) of program memory (mask programmed ROM). However, placing program memory on the internal RAM is deregulated if a certain procedure is executed (See 2.4.5 Address Trap).

1.3 Data Memory (RAM)

Data memory consists of internal data memory (internal ROM or RAM). The TMP86CM41 has 1 Kbytes of internal RAM. The first 192 bytes (0040H to 00FFH) of the internal RAM are located in the direct area; instructions with shorten operations are available against such an area.

Electrical Characteristics

Absolute Maximum Ratings $(V_{SS} = 0 V)$

Parameter	Symbol	Pins	Rating	Unit
Supply Voltage	V _{DD}		- 0.3 to 6.5	
Input Voltage	V _{IN}		- 0.3 to V _{DD} + 0.3] v
Output Voltage	V _{OUT}		- 0.3 to V _{DD} + 0.3]
	louth	P0, P1, P3, P4, P5, P6, P7 Port	-3.2	
Output Current (Per 1 pin)	I _{OUT1}	P0, P1, P2, P3, P4, P6, P7 Port	3.2]
	I _{OUT2}	P5 Port	30	mA
Output Current (Total)	Σl _{OUT1}	P0, P1, P2, P3, P4, P6, P7 Port	80]
Output Current (Total)	Σl _{OUT2}	P5 Port	120]
Power Dissipation [T _{opr} = 85℃]	PD		350	mW
Soldering Temperature (time)	Tsld		260 (10 s)	
Storage Temperature	Tstg		– 55 to 125	ີ
Operating Temperature	Topr		- 40 to 85	

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant. Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

Recommended Operating Condition

 $(V_{SS} = 0 \text{ V, Topr} = -40 \text{ to } 85^{\circ}\text{C})$

Parameter	Symbol	Pins	c	ondition	Min	Max	Unit
			6 46 8411	NORMAL1, 2 mode			
			fc = 16 MHz	IDLE0, 1, 2 mode	4.5		
Supply Voltage	V _{DD}		fs =	SLOW1, 2 mode	4.5	5.5	
			32.768 kHz	SLEEP0, 1, 2 mode			
				STOP mode	2.0		V
Input high Level	V _{IH1}	Except Hysteresis input	V _{DD} ≧ 4.5 V		$V_{DD} \times 0.70$	V _{DD}	
Imput mgm Level	V _{IH2}	Hysteresis input			$V_{DD} \times 0.75$	V DD	
Input low Level	V _{IL1}	Except Hysteresis input	$V_{DD} \ge 4.5 V$		0	$V_{DD} \times 0.30$	
Imput low Level	V _{IL2}	Hysteresis input			0	$V_{DD} \times 0.25$	
Clock Frequency	fc	XIN, XOUT	V _{DD} = 4.5 to 5.5 V		1.0	16.0	MHz
Clock Frequency	fs	XTIN, XTOUT			30.0	34.0	kHz

Note: The recommended operating conditions for a device are operating conditions under which it can be guaranteed that the device will operate as specified. If the device is used under operating conditions other than the recommended operating conditions (supply voltage, operating temperature range, specified AC/DC values etc.), malfunction may occur. Thus, when designing products which include this device, ensure that the recommended operating conditions for the device are always adhered to.

DC Characteristics $(V_{SS} = 0 \text{ V}, \text{Topr} = -40 \text{ to } 85^{\circ}\text{C})$

Parameter	Symbol	Pins	Condition	Min	Тур.	Max	Unit
Hysteresis Voltage	V _{HS}			T -	0.9	_	V
, ,	I _{IN1}	TEST					
Input Current	I _{IN2}	Open Drain port Tri-state port	$V_{DD} = 5.5 \text{ V}, V_{IN} = 5.5 \text{ V}/0 \text{ V}$	_	-	± 2	μΑ
	I _{IN3}	RESET, STOP1					ĺ
Input Resistance	R _{IN1}	RESET		100	220	450	kΩ
	Rfx	XIN-XOUT		_	1.2	_	NAO
	Rfxt	XTIN-XTOUT		_	6	_	ΜΩ
Output Leakage	I _{LO1}	Open Drain port	V _{DD} = 5.5 V, V _{OUT} = 5.5 V	_	-	2	
Current	I _{LO2}	Tri-state port	port $V_{DD} = 5.5 \text{ V}, V_{OUT} = 5.5 \text{ V}/0 \text{ V}$		-	± 2	μΑ
Output High Voltage	V _{OH}	Tri-state port $V_{DD} = 4.5 \text{ V}, I_{OH} = -0.7 \text{ mA}$		4.1	-	_	
Output Low Voltage	V _{OL1}	Except XOUT and P5 Port $V_{DD} = 4.5 \text{ V}, I_{OL} = 1.6 \text{ mA}$		_	-	0.4	\
	I _{OL1}	Except XOUT and P5 Port	V _{DD} = 4.5 V, V _{OL} = 0.4 V	_	1.6	_	
Output Low Current	I _{OL2}	P5 (High current port)	V _{DD} = 4.5 V, V _{OL} = 1.0 V	_	20	-	
Supply Current in			V _{DD} = 5.5 V		12	18	
Normal 1, 2 mode			V _{IN} = 5.3 V/0.2 V	_	12	10	mA
Supply Current in			fc = 16 MHz	_	9	13	
IDLE 0, 1, 2 mode			fs = 32.768 kHz			'	
Supply Current in	I _{DD}		V _{DD} = 5.5 V	_	30	60	
SLOW mode			$V_{IN} = 5.3 \text{ V}/0.2 \text{ V}$				
Supply Current in			fs = 32.768 kHz	_	20	30	μA
SLEEP 0, 1 mode			13 - 32.7 00 KHZ				"
Supply Current in			$V_{DD} = 5.5 V$	_	0.5	10	
Stop mode			$V_{IN} = 5.3 \text{ V}/0.2 \text{ V}$		"."	.0	

Note 1: Typical values show those at Topr = 25°C, V_{DD} = 5 V

Note 2: Input current (I_{IN1} , I_{IN2}); The current through pull-up or pull-down resistor is not included.

Note 3: IDD does not include IREF current.

AD Conversion Characteristics

 $(V_{SS} = 0.0 \text{ V, Topr} = -40 \text{ to } 85^{\circ}\text{C})$

Parameter	Symbol	Condition	Min	Тур.	Max	Unit
Analog Reference Voltage	V _{AREF}		4.5	-	V_{DD}	
Power Supply Voltage of	A _{VDD}			V_{DD}]
Analog Control Circuit	A _{VSS}			V_{SS}		v
Analog Reference of Voltage Range	$\triangle V_{AREF}$	V _{AREF} - A _{VSS}	4.5	-	_] "
Analog Input Voltage	V _{AIN}		V _{SS}	_	V _{AREF}]
Power Supply Current of Analog Reference Voltage	I _{REF}	$V_{DD} = A_{VDD} = V_{AREF} = 5.5 \text{ V}$ $V_{SS} = A_{VSS} = 0.0 \text{ V}$	-	0.6	1.0	mA
Non linearity Error		V 454-55V	_	-	± 2	
ero Point Error		$V_{DD} = 4.5 \text{ to } 5.5 \text{ V}$ $V_{SS} = 0.0 \text{ V}$	_	-	± 2	
Full Scale Error		$A_{VDD} = V_{AREF} = V_{DD}$		-	± 2	LSB
Total Error		$A_{VSS} = 0.0 \text{ V}$	_	-	± 4	1

Note 1: Total errors includes all errors, except quantization error.

Note 2: Conversion time is different in recommended value by power supply voltage.

About conversion time, please refer to "2.10.2 Register Framing".

Note 3: Please use input voltage to AIN input Pin in limit of V_{AREF} - V_{SS}.

When voltage of range outside is input, conversion value becomes unsettled and gives affect to other channel

conversion value.

AC Characteristics

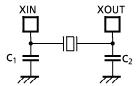
 $(V_{SS} = 0 \text{ V}, V_{DD} = 4.5 \text{ to } 5.5 \text{ V}, Topr = -40 \text{ to } 85^{\circ}\text{C})$

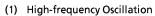
Parameter	Symbol	Condition	Min	Тур.	Max	Unit
Machine Cycle Time	tcy	NORMAL 1, 2 mode	0.35	_	4	μS
		IDLE 0, 1, 2 mode	0.25			
		SLOW 1, 2 mode	117.6	-	133.3	
		SLEEP 0, 1, 2 mode	117.6			
High Level Clock Pulse Width	t _{WCH}	For external clock operation (XIN input)		24.25		
Low Level Clock Pulse Width	t_{WCL}	fc = 16 MHz	_	31.25	_	ns
High Level Clock Pulse Width	t _{WSH}	For external clock operation (XTIN input)	-	15.26	-	
Low Level Clock Pulse Width	t _{WSL}	fc = 32.768 kHz				μS

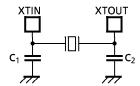
Recommended Oscillating Conditions

 $(V_{SS} = 0 \text{ V}, V_{DD} = 4.5 \text{ to } 5.5 \text{ V}, \text{ Topr} = -40 \text{ to } 85^{\circ}\text{C})$

Doromotor	Oscillator	Oscillation	Recommended Oscillator		Recommended Constant		
Parameter		Frequency			C ₁	C ₂	
High-frequency Oscillation	Ceramic Resonator	16 MHz	MURATA	CSA16.00MXZ040	10 pF	10 pF	
		8 MHz	MURATA	CSA8.00MTZ	30 pF	30 pF	
				CST8.00MTW	30 pF (built-in)	30 pF (built-in)	
		4.19 MHz	MURATA	CSA4.19MG	30 pF	30 pF	
				CST4.19MGW	30 pF (built-in)	30 pF (built-in)	
Low-frequency Oscillation	Crystal Oscillator	32.768 kHz	SII	VT-200	6 pF	6 pF	







(2) Low-frequency Oscillation

- Note 1: An electrical shield by metal shield plate on the surface of IC package is recommended in order to protect the device from the high electric field stress applied from CRT (Cathodic Ray Tube) for continuous reliable operation.
- Note 2: The product numbers and specifications of the resonators by Murata Manufacturing Co., Ltd. are subject to change. For up-to-date information, please refer to the following URL; http://www.murata.co.jp/search/index.html