

TOSHIBA Bi-CMOS INTEGRATED CIRCUIT SILICON MONOLITHIC

TB6528P

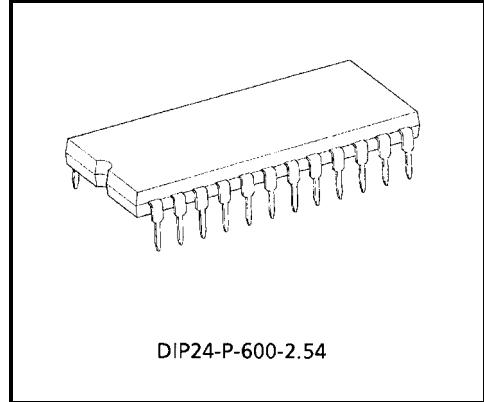
FIVE-PHASE STEPPING MOTOR DRIVE CONTROLLER

The TB6528P universal controller for stepping motor drives is a Bi-CMOS monolithic-type IC for controlling five-phase stepping motors.

This IC enables five-phase stepping motor drive units to be configured simply by preparing a pulse oscillator, a switching element and a direct current power source. This IC was developed in order to simplify the use of stepping motors.

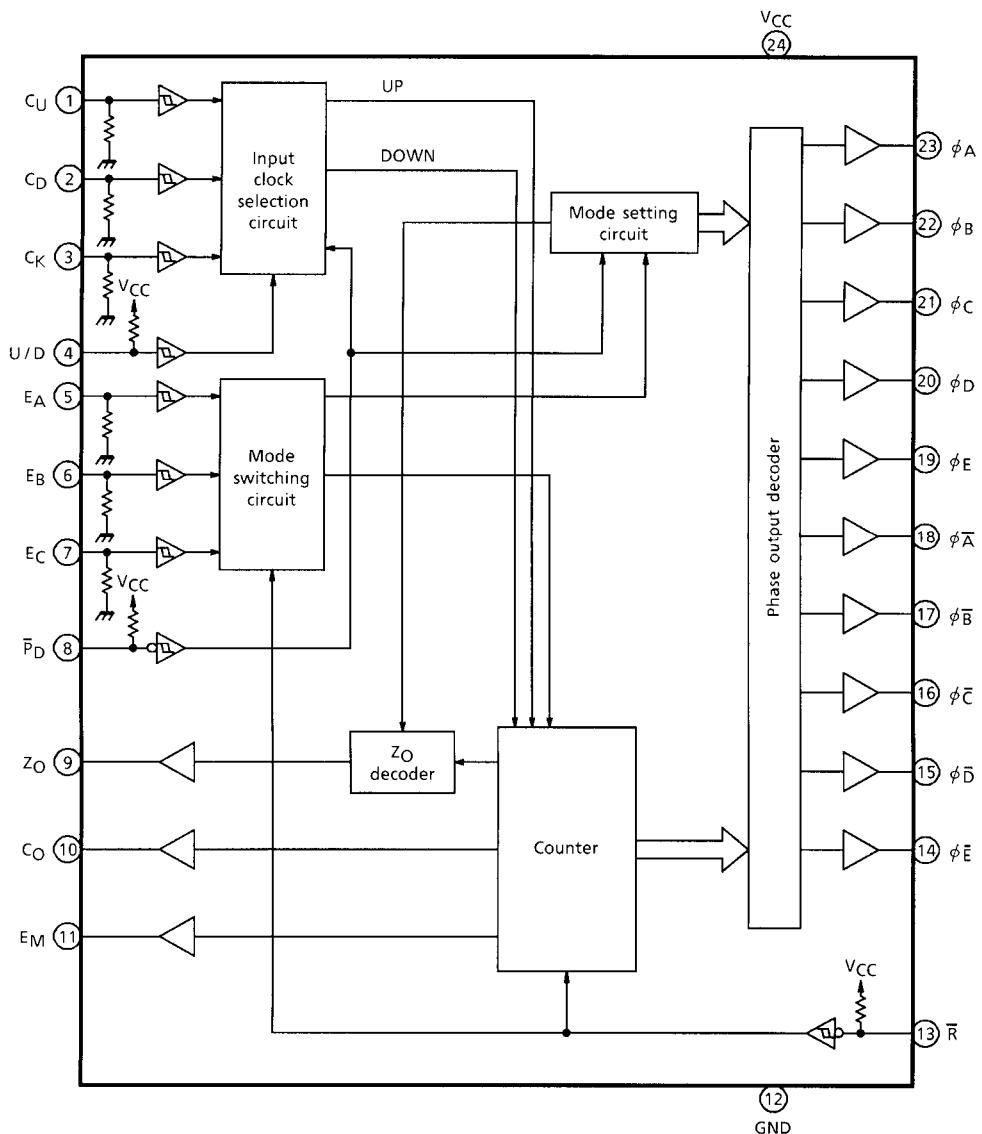
FEATURES

- Universal controller : The excitation mode switching terminal enables the selection of the following eight modes.
 - Uni-polar type: 2 excitation,
2-3 excitation,
3 excitation
 - Bi-polar type : 2-3 excitation, 3 excitation, 4 excitation, 4-5 excitation, 5 excitation
- Operating supply voltage range : VCC = 4~16 V
- High-output current : 20 mA min (source)
- High noise margin : All input pin are equipped with a Schmidt circuit.
- Two types of pulse input : 2 input pin method
 - (CW and CCW input modes).
 - 1 input / 1 switching pin method
 - (CK and U / D input modes).
- Power down function : All output is at the "L" level
- Excitation mode protection function : No fluctuations in output even when switching excitation modes such as 2Ex ↔ 2-3Ex ↔ 3Ex, 4Ex ↔ 4-5Ex ↔ 5Ex.
- Reset function : Moves the phase home position across to the excitation status.
- Phase home position monitor : "H" level is output when at the phase home position (output in the reset mode).
- Excitation status identification monitor : The controller's operating status is output as a monitor signal.
- Input pulse monitor : The input is output as a monitor signal.



Weight: 3.38 g (Typ.)

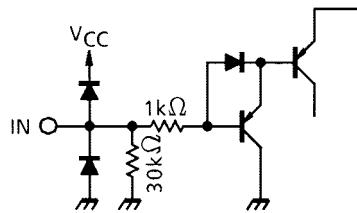
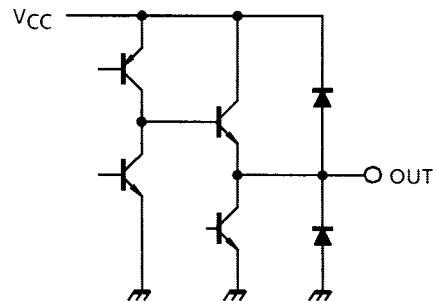
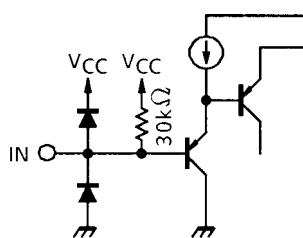
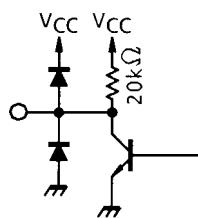
BLOCK DIAGRAM



PIN FUNCTION

PIN No.	PIN SYMBOL	PIN FUNCTION	
1	C _U	Input pulse UP clock	Truth table A
2	C _D	Input pulse DOWN clock	
3	C _K	Input pulse clock	
4	U / D	Converts rotation directions "0" is DOWN, "1" is UP	
5	E _A	Excitation mode switching input	Truth table B
6	E _B		
7	E _C		
8	P _D	All output becomes "L" when power down is "L"	
9	Z _O	Phase home position monitor	
10	C _O	Input pulse monitor	
11	E _M	Excitation monitor	
12	GND	GND	
13	̄R	Reset when the reset input is "L"	
14	φ _E	φ _E Output	
15	φ _D	φ _D Output	
16	φ _C	φ _C Output	
17	φ _B	φ _B Output	
18	φ _A	φ _A Output	
19	φ _E	φ _E Output	
20	φ _D	φ _D Output	
21	φ _C	φ _C Output	
22	φ _B	φ _B Output	
23	φ _A	φ _A Output	
24	V _{CC}	V _{CC}	

EQUIVALENT I / O CIRCUIT

C_U, C_D, C_K**φ_A~φ_E and φ̄_A~φ̄_E****U / D, P̄_D, ̄R****Z_O, C_O, E_M**

TRUTH TABLE A

C _U	C _D	C _K	U / D	FUNCTION
	L	L	(*)	CW
L		L	(*)	CCW
L	L		H	CW
L	L		L	CCW

Note 1: * means Don't Care

Note 2: The C_U pin is an input pin when counting up, and the C_D pin is an input pin when counting down.

Note 3: The C_K pin is the count pulse input pin, and count-up and count-down is determined by the U / D pin.

TRUTH TABLE B

E _A	E _B	E _C	\bar{R}	\bar{P}_D	FUNCTION	EXCITATION TYPE
L	H	H	H	H	2 Excitation	Uni-polar type
L	L	H	H	H	2-3 Excitation	
H	L	H	H	H	3 Excitation	
H	H	L	H	H	2-3 Excitation	Bi-polar type
H	H	H	H	H	3 Excitation	
L	H	L	H	H	4 Excitation	
L	L	L	H	H	4-5 Excitation	
H	L	L	H	H	5 Excitation	

Note 4: The output enters the initial status when \bar{R} is set at the LOW level, and the Z_O output indicates the High level.

Note 5: The input clock signal is prohibited and the phase output terminals ($\phi A \sim \phi E$ and $\phi \bar{A} \sim \phi \bar{E}$) enter the LOW level when \bar{P}_D is set at the LOW level.

Z_O, C_O and E_M output is not prohibited.

FUNCTION 1 (Uni-polar type)**2 EXCITATION**

PULSE PHASE \	0 (RESET)	1	2	3	4	5
φ_A	H	L	L	L	H	H
φ_B	H	H	L	L	L	H
φ_C	L	H	H	L	L	L
φ_D	L	L	H	H	L	L
φ_E	L	L	L	H	H	L
$\varphi_{\bar{A}}$	L	L	L	L	L	L
$\varphi_{\bar{B}}$	L	L	L	L	L	L
$\varphi_{\bar{C}}$	L	L	L	L	L	L
$\varphi_{\bar{D}}$	L	L	L	L	L	L
$\varphi_{\bar{E}}$	L	L	L	L	L	L
Z_O	H	L	L	L	L	H
E_M	L	L	L	L	L	L
UP	►					
DOWN	◀					

2-3 EXCITATION

PULSE PHASE \	0 (RESET)	1	2	3	4	5	6	7	8	9	10
φ_A	H	H	L	L	L	L	L	H	H	H	H
φ_B	H	H	H	H	L	L	L	L	H	H	H
φ_C	L	H	H	H	H	H	L	L	L	L	L
φ_D	L	L	L	H	H	H	H	H	L	L	L
φ_E	L	L	L	L	L	H	H	H	H	H	L
$\varphi_{\bar{A}}$	L	L	L	L	L	L	L	L	L	L	L
$\varphi_{\bar{B}}$	L	L	L	L	L	L	L	L	L	L	L
$\varphi_{\bar{C}}$	L	L	L	L	L	L	L	L	L	L	L
$\varphi_{\bar{D}}$	L	L	L	L	L	L	L	L	L	L	L
$\varphi_{\bar{E}}$	L	L	L	L	L	L	L	L	L	L	L
Z_O	H	L	L	L	L	L	L	L	L	L	H
E_M	L	H	L	H	L	H	L	H	L	H	L
UP	►										
DOWN	◀										

3 EXCITATION

PULSE PHASE	0 (RESET)	1	2	3	4	5
φ_A	H	H	L	L	H	H
φ_B	H	H	H	L	L	L
φ_C	L	H	H	H	L	L
φ_D	L	L	H	H	H	H
φ_E	H	L	L	H	H	L
$\varphi_{\bar{A}}$	L	L	L	L	L	L
$\varphi_{\bar{B}}$	L	L	L	L	L	L
$\varphi_{\bar{C}}$	L	L	L	L	L	L
$\varphi_{\bar{D}}$	L	L	L	L	L	L
$\varphi_{\bar{E}}$	L	L	L	L	L	L
Z_O	H	L	L	L	L	H
E_M	H	H	H	H	H	H
UP	→					
DOWN	◀					

FUNCTION 2 (Bi-polar type)**2-3 EXCITATION**

PULSE PHASE	0 (RESET)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
φ_A'	L	L	L	L	L	L	L	L	L	L	H	H	H	H	H	L	L	L	L	L	
φ_B'	H	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	H	H	H	H	
φ_C'	L	L	L	H	H	H	H	H	L	L	L	L	L	L	L	L	L	L	L	L	
φ_D'	L	L	L	L	L	L	L	L	H	H	H	H	H	H	L	L	L	L	L	L	
φ_E'	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	H	H	H	H	H	
$\varphi_{\bar{A}'}$	L	H	H	H	H	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
$\varphi_{\bar{B}'}$	L	L	L	L	L	L	H	H	H	H	H	H	L	L	L	L	L	L	L	L	
$\varphi_{\bar{C}'}$	L	L	L	L	L	L	L	L	L	L	L	L	H	H	H	H	H	H	L	L	
$\varphi_{\bar{D}'}$	H	H	H	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	H	H	
$\varphi_{\bar{E}'}$	L	L	L	L	H	H	H	H	H	H	L	L	L	L	L	L	L	L	L	L	
Z_O	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	H	
E_M	L	H	L	H	L	H	L	H	L	H	L	H	L	H	L	H	L	H	L	H	
UP	→																				
DOWN	◀																				

3 EXCITATION

PULSE PHASE \	0 (RESET)	1	2	3	4	5	6	7	8	9	10
$\Phi A'$	L	L	L	L	L	H	H	H	L	L	
$\Phi B'$	H	H	L	L	L	L	L	L	H	H	
$\Phi C'$	L	L	H	H	H	L	L	L	L	L	
$\Phi D'$	L	L	L	L	L	H	H	H	L	L	
$\Phi E'$	H	L	L	L	L	L	L	L	H	H	
$\phi \bar{A}'$	L	H	H	H	L	L	L	L	L	L	
$\phi \bar{B}'$	L	L	L	L	H	H	H	L	L	L	
$\phi \bar{C}'$	L	L	L	L	L	L	H	H	H	L	
$\phi \bar{D}'$	H	H	H	L	L	L	L	L	L	H	
$\phi \bar{E}'$	L	L	L	H	H	H	L	L	L	L	
Z_O	H	L	L	L	L	L	L	L	L	H	
E_M	H	H	H	H	H	H	H	H	H	H	
UP	►										
DOWN	◀										

4 EXCITATION

PULSE PHASE \	0 (RESET)	1	2	3	4	5	6	7	8	9	10
ΦA	H	L	L	L	L	L	H	H	H	H	
ΦB	H	H	L	L	L	L	L	H	H	H	
ΦC	H	H	H	L	L	L	L	L	H	H	
ΦD	H	H	H	H	L	L	L	L	L	H	
ΦE	L	H	H	H	H	L	L	L	L	L	
$\phi \bar{A}$	L	L	H	H	H	H	L	L	L	L	
$\phi \bar{B}$	L	L	L	H	H	H	L	L	L	L	
$\phi \bar{C}$	L	L	L	H	H	H	H	L	L	L	
$\phi \bar{D}$	L	L	L	L	H	H	H	H	L	L	
$\phi \bar{E}$	L	L	L	L	L	H	H	H	H	L	
Z_O	H	L	L	L	L	L	L	L	L	H	
E_M	L	L	L	L	L	L	L	L	L	L	
UP	►										
DOWN	◀										

4-5 EXCITATION

PULSE PHASE \	0 (RESET)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
φ_A	H	H	L	L	L	L	L	L	L	L	L	L	H	H	H	H	H	H	H	H	
φ_B	H	H	H	H	L	L	L	L	L	L	L	L	L	H	H	H	H	H	H	H	
φ_C	H	H	H	H	H	H	L	L	L	L	L	L	L	L	L	H	H	H	H	H	
φ_D	H	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	L	L	H	H	
φ_E	L	H	H	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	L	L	
$\varphi_{\bar{A}}$	L	L	L	H	H	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	
$\varphi_{\bar{B}}$	L	L	L	L	L	H	H	H	H	H	H	H	H	H	H	L	L	L	L	L	
$\varphi_{\bar{C}}$	L	L	L	L	L	L	L	H	H	H	H	H	H	H	H	L	L	L	L	L	
$\varphi_{\bar{D}}$	L	L	L	L	L	L	L	L	L	H	H	H	H	H	H	H	H	H	L	L	
$\varphi_{\bar{E}}$	L	L	L	L	L	L	L	L	L	L	H	H	H	H	H	H	H	H	H	L	
Z_O	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	H	
E_M	L	H	L	H	L	H	L	H	L	H	L	H	L	H	L	H	L	H	L	H	
UP	—	►																			
DOWN	◀																				

5 EXCITATION

PULSE PHASE \	0 (RESET)	1	2	3	4	5	6	7	8	9	10
φ_A	H	H	L	L	L	L	L	H	H	H	H
φ_B	H	H	H	L	L	L	L	H	H	H	H
φ_C	H	H	H	H	L	L	L	L	H	H	H
φ_D	H	H	H	H	H	L	L	L	L	L	H
φ_E	L	H	H	H	H	H	L	L	L	L	L
$\varphi_{\bar{A}}$	L	L	H	H	H	H	H	L	L	L	L
$\varphi_{\bar{B}}$	L	L	L	H	H	H	H	H	L	L	L
$\varphi_{\bar{C}}$	L	L	L	L	H	H	H	H	H	L	L
$\varphi_{\bar{D}}$	L	L	L	L	L	H	H	H	H	H	L
$\varphi_{\bar{E}}$	H	L	L	L	L	L	H	H	H	H	H
Z_O	H	L	L	L	L	L	L	L	L	L	H
E_M	H	H	H	H	H	H	H	H	H	H	H
UP	—	►									
DOWN	◀										

MAXIMUM RATINGS (Ta = 25°C)

CHARACTERISTIC		SYMBOL	RATING	UNIT
Power Supply Voltage		V _{CC}	-0.5~20	V
Output Current φn	"H" LEVEL	I _{OH} φ	-30	mA
	"L" LEVEL	I _{OL} φ	2	
Output Current (C _O , E _M , Z _O)	"H" LEVEL	I _{OH}	-50	μA
	"L" LEVEL	I _{OL}	2	mA
Input Voltage		V _{IN}	-0.5~V _{CC}	V
Input Current		I _{IN}	±1	mA
Power Dissipation		P _D	1000	mW
Operating Temperature		T _{opr}	-20~85	°C
Storage Temperature		T _{stg}	-55~150	°C

RECOMMENDED OPERATING CONDITIONS (Ta = -30~85°C)

CHARACTERISTIC		SYMBOL	TEST CONDITION	MIN	TYP.	MAX	UNIT
Power Supply Voltage		V _{CC}	—	4	—	13	V
Output Current φn	"H" LEVEL	I _{OH} φ	—	—	—	-10	mA
	"L" LEVEL	I _{OL} φ	—	—	—	1.6	
Output Current (C _O , E _M , Z _O)	"H" LEVEL	I _{OH}	—	—	—	-40	μA
	"L" LEVEL	I _{OL}	—	—	—	1.6	mA
Input Voltage		V _{IN}	—	0	—	V _{CC}	V
Clock Frequency		—	—	0	—	250	kHz

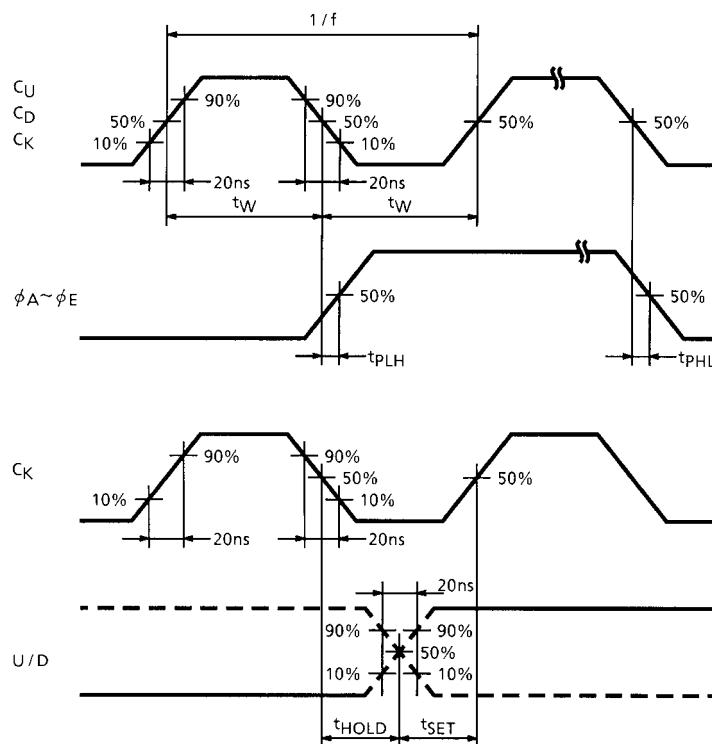
ELECTRICAL CHARACTERISTICS ($T_a = 25^\circ C$)

CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN	TYP.	MAX	UNIT	
Output Current $\Phi_A \sim \Phi_E$	“H” level	I_{OH}	—	$V_{CC} = 5 V, V_O = V_{CC}-2.0$	-20	—	—	mA	
			—	$V_{CC} = 10 V, V_O = V_{CC}-2.0$	-20	—	—		
	“L” level	I_{OL}	—	$V_{CC} = 5 V, V_O = 0.3 V$	1.6	—	—	mA	
			—	$V_{CC} = 10 V, V_O = 0.3 V$	1.6	—	—		
Output Current C_O, E_M, Z_O	“H” level	V_{OH}	—	$V_{CC} = 5 V, I_O = -40 \mu A$	3.6	—	—	V	
			—	$V_{CC} = 10 V, I_O = -40 \mu A$	8.6	—	—		
	“L” level	V_{OL}	—	$V_{CC} = 5 V, I_O = 1.6 mA$	—	—	0.4	V	
			—	$V_{CC} = 10 V, I_O = 1.6 mA$	—	—	0.6		
Input Voltage	“H” level	V_{IH}	—	$V_{CC} = 5 V$	3.0	2.5	—	V	
			—	$V_{CC} = 10 V$	6.0	5.0	—		
	“L” level	V_{IL}	—	$V_{CC} = 5 V$	—	2.0	1.5	V	
			—	$V_{CC} = 10 V$	—	4.0	3.0		
Input Current C_U, C_D, C_K E_A, E_B, E_{EC}	“H” level	I_{IH}	—	$V_{CC} = 5 V, V_{IN} = V_{CC}-0.5 V$	—	—	0.4	mA	
			—	$V_{CC} = 10 V, V_{IN} = V_{CC}-0.5 V$	—	—	0.7		
	“L” level	I_{IL}	—	$V_{CC} = 5 V, V_{IN} = 0 V$	—	—	± 10	μA	
			—	$V_{CC} = 10 V, V_{IN} = 0 V$	—	—	± 10		
Input Current $U / D, \bar{P}_D, \bar{R}$	“H” level	I_{IH}	—	$V_{CC} = 5 V, V_{IN} = V_{CC}-0.5 V$	—	—	-100	μA	
			—	$V_{CC} = 10 V, V_{IN} = V_{CC}-0.5 V$	—	—	-100		
	“L” level	I_{IL}	—	$V_{CC} = 5 V, V_{IN} = 0 V$	—	—	-0.4	mA	
			—	$V_{CC} = 10 V, V_{IN} = 0 V$	—	—	-0.7		
Static Current Consumption		I_{CC}	—	$V_{CC} = 5 V, \text{ all pins open}$	—	—	25	mA	
			—	$V_{CC} = 10 V, \text{ all pins open}$	—	—	35		

SWITCHING CHARACTERISTICS ($T_a = 25^\circ\text{C}$)

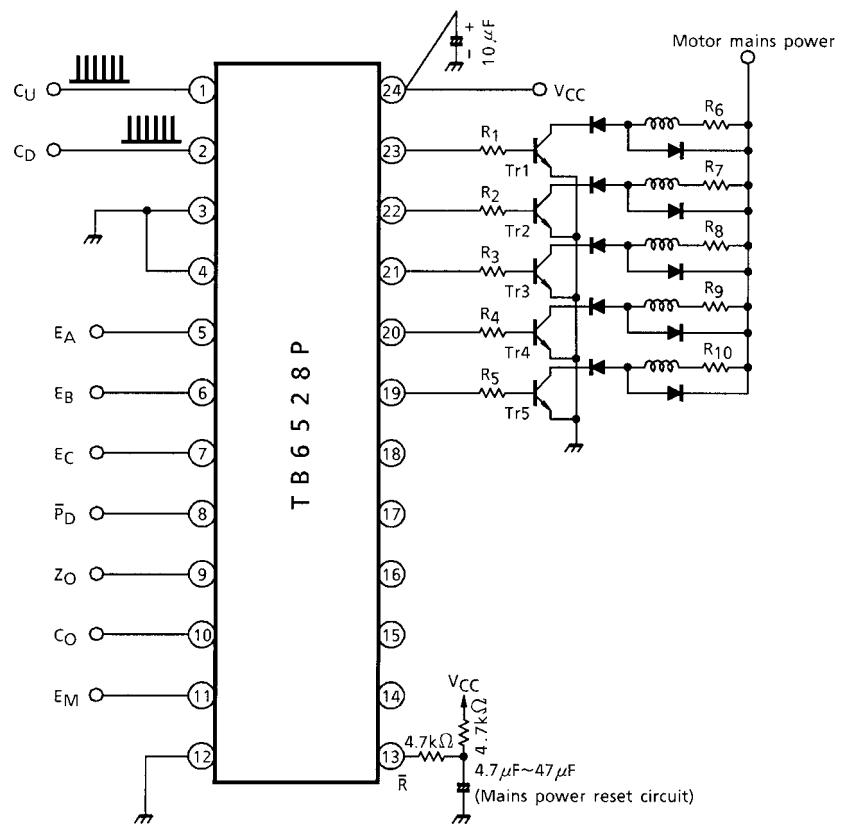
CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN	TYP.	MAX	UNIT
Maximum Clock Frequency	f_{MAX}	—	$V_{CC} = 5 \text{ V}$	250	300	—	kHz
		—	$V_{CC} = 10 \text{ V}$	270	350	—	
Minimum Clock Pulse Width	t_W	—	$V_{CC} = 5 \text{ V}$	—	300	500	ns
		—	$V_{CC} = 10 \text{ V}$	—	300	500	
Minimum Reset Pulse Width	t_{WR}	—	$V_{CC} = 5 \text{ V}$	—	200	500	ns
		—	$V_{CC} = 10 \text{ V}$	—	200	500	
Delay Time (ϕ output from clock input)	t_{PLH}	—	$V_{CC} = 5 \text{ V}$	—	2500	3500	ns
	t_{PHL}	—	$V_{CC} = 10 \text{ V}$	—	2500	3500	
Delay Time (each monitor from clock input)	t_{PLH}	—	$V_{CC} = 5 \text{ V}$	—	3000	4000	ns
	t_{PHL}	—	$V_{CC} = 10 \text{ V}$	—	3000	4000	
Setting Time	t_{SET}	—	$V_{CC} = 5 \text{ V}$	4000	3000	—	ns
		—	$V_{CC} = 10 \text{ V}$	4000	3000	—	
Storage Time	t_{HOLD}	—	$V_{CC} = 5 \text{ V}$	500	0	—	ns
		—	$V_{CC} = 10 \text{ V}$	500	0	—	

MEASURED WAVE-FORM FOR SWITCHING TIME



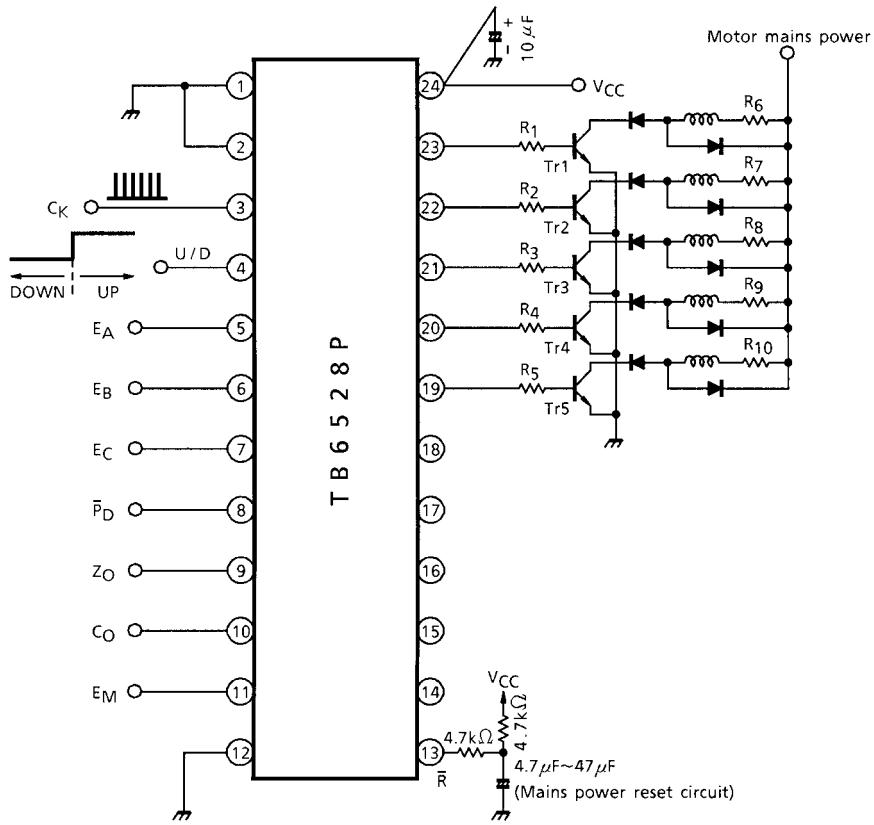
APPLICATION CIRCUIT 1

2 input pin method



APPLICATION CIRCUIT 2

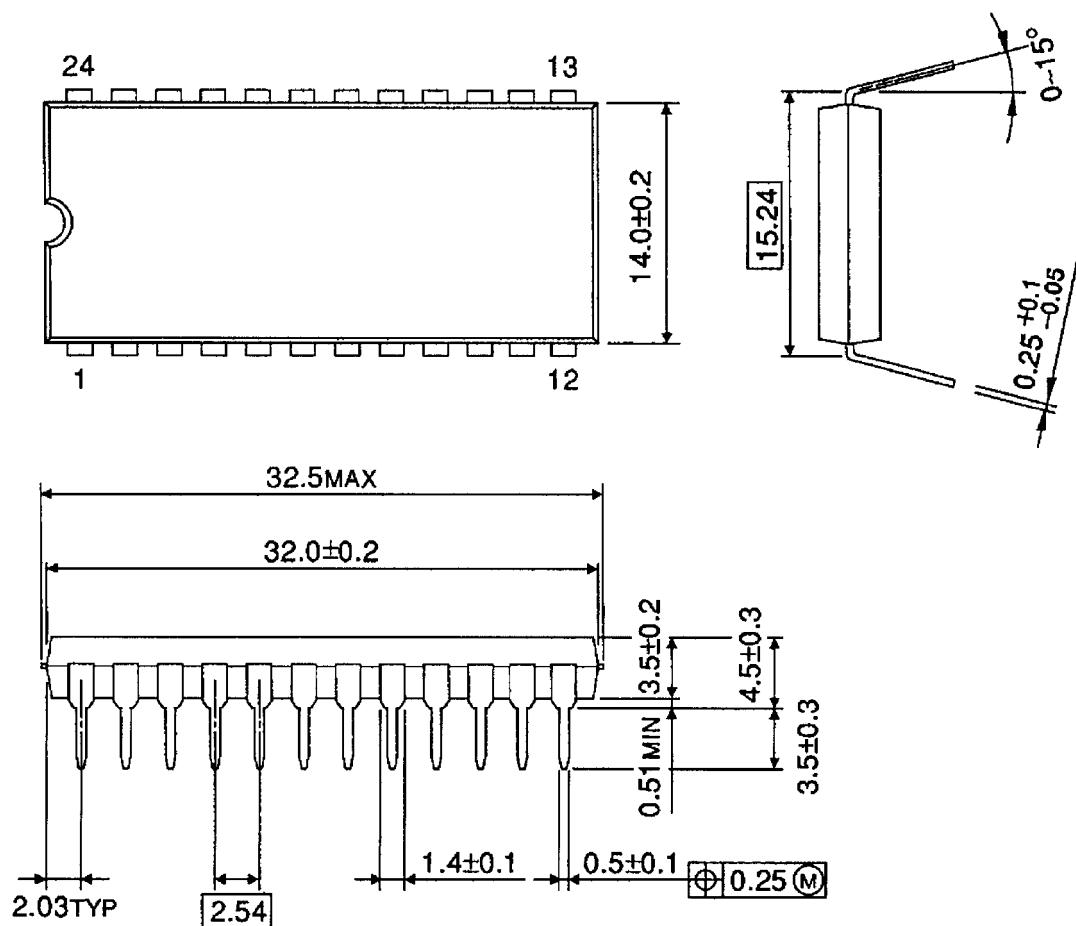
1 input / switting pin method



PACKAGE DIMENSIONS

DIP24-P-600-2.54

Unit: mm



Weight: 3.38 g (Typ.)

RESTRICTIONS ON PRODUCT USE

000707EBA

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