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# 5-V CAN TRANSCEIVER WITH I/O LEVEL SHIFTING AND LOW-POWER MODE SUPPLY OPTIMIZATION

#### **FEATURES**

- Qualified for Automotive Applications
- Meets or Exceeds the Requirements of ISO 11898
- GIFT/ICT Compliant
- ESD Protection up to ±12 kV (Human-Body Model) on Bus Pins
- Level Adapting I/O Voltage Range to Support MCUs With Digital I/Os From 3 V to 5.25 V
- Low-Power Standby Mode <15 μA max</li>
  - SN65HVDA540: No Wake Up
  - SN65HVDA541: Wake Up Powered By V<sub>IO</sub> Supply So V<sub>CC</sub> (5 V) Supply May Be Shut Down to Save System Power
- High Electromagnetic Immunity (EMI)
- Low Electromagnetic Emissions (EME)
- Protection
  - Undervoltage Protection on V<sub>IO</sub> and V<sub>CC</sub>
  - Bus-Fault Protection of –27 V to 40 V
  - Dominant Time-Out Function
  - Thermal Shutdown Protection
  - Power-Up/Down Glitch-Free Bus Inputs and Outputs

#### APPLICATIONS

- SAE J2284 High-Speed CAN for Automotive Applications
- SAE J1939 Standard Data Bus Interface
- ISO 11783 Standard Data Bus Interface
- NMEA 2000 Standard Data Bus Interface

#### DESCRIPTION

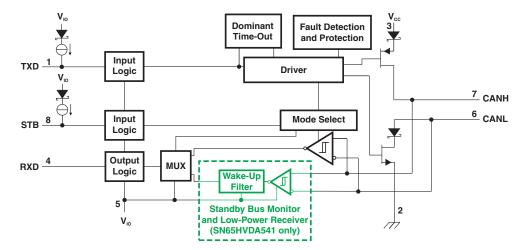
The SN65HVDA540/SN65HVDA541 meets or exceeds the specifications of the ISO 11898 standard for use in applications employing a Controller Area Network (CAN). The device is qualified for use in automotive applications.

As a CAN transceiver, this device provides differential transmit capability to the bus and differential receive capability to a CAN controller at signaling rates up to 1 megabit per second (Mbps)<sup>(1)</sup>.

Designed for operation in especially harsh environments, the SN65HVDA540/SN65HVDA541 features cross-wire, bus over voltage, loss of ground protection, over temperature thermal shut down protection, and a wide common-mode range.

(1) The signaling rate of a line is the number of voltage transitions that are made per second, expressed in the units bps (bits per second).

#### **FUNCTIONAL BLOCK DIAGRAM**





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### **DESCRIPTION (CONTINUED)**

The SN65HVDA540/SN65HVDA541 has an I/O supply voltage input pin ( $V_{IO}$ , pin 5) to ratiometrically level shift the digital logic input and output levels with repsect to  $V_{IO}$  for compatibility with protocol controllers having I/O supply voltages between 3 V and 5.25 V. The  $V_{IO}$  supply also powers the low-power bus monitor and wake-up receiver of the SN65HVDA541 allowing the 5 V ( $V_{CC}$ ) supply to be switched off for additional power savings at the system level during standby mode for either the SN65HVDA540 or SN65HVDA541. The 5 V ( $V_{CC}$ ) supply needs to be reactivated by the local protocol controller at any time to resume high speed operation if it has been turned off for low-power standby operation. Both of the supply pins have undervoltage detection which place the device in standby mode to protect the bus during an undervoltage event on either the  $V_{CC}$  or  $V_{IO}$  supply pins. If  $V_{IO}$  is undervoltage the RXD pin is 3-statedn and the device does not pass any wake-up signals from the bus to the RXD pin.

STB (pin 8) provides for two different modes of operation: normal mode or low-power standby mode. The normal mode of operation is selected by applying a low logic level to STB. If a high logic level is applied to STB, the device enters standby mode (see Figure 1 and Figure 2). In standby mode, the SN65HVDA541 provides a wake-up receiver and monitor that remains active supplied via the  $V_{IO}$  pin so that  $V_{CC}$  may be removed allowing a system level reduction in standby current. A dominant signal on the bus longer than the wake-up signal time ( $t_{BUS}$ ) is passed to the receiver output (RXD, pin 4) by the wake-up bus monitor circuit. The local protocol controller may then return the device to normal mode when the system needs to transmit or fully monitor the messages on the bus. If the bus has a fault condition where it is stuck dominant while the SN65HVDA541 is placed into standby mode, the device locks out the wake-up receiver output to RXD until the fault has been removed to prevent false wake-up signals in the system. Because the SN65HVDA540 does not have a low-power bus monitor and wake-up receiver, it provides a logic high output (recessive) on RXD while in standby mode.

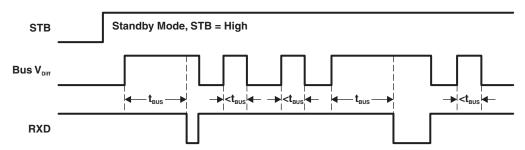


Figure 1. SN65HVDA541 Entering Standby Mode With Bus Recessive Condition

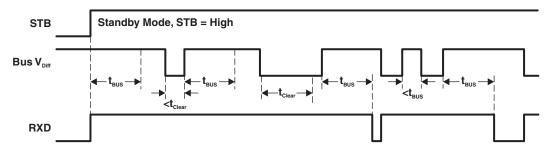
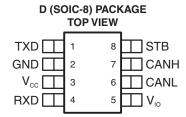


Figure 2. SN65HVDA541 Entering Standby Mode With Bus Dominant Condition

A dominant time-out circuit prevents the driver from blocking network communication in event of a hardware or software failure. The dominant time out circuit is triggered by a falling edge on TXD (pin 1). If no rising edge is seen before the time-out constant of the circuit expires, the driver is disabled. The circuit is reset by the next rising edge on TXD.





#### **TERMINAL FUNCTIONS**

TERM	IINAL	TYPE	DECEDIDATION
NAME	NO.	ITPE	DESCRIPTION
TXD	1	I	CAN transmit data input (low for dominant bus state, high for recessive bus state)
GND	2	GND	Ground connection
V <sub>CC</sub>	3	Supply	Transceiver 5-V supply voltage
RXD	4	0	CAN receive data output (low in dominant bus state, high in recessive bus state)
V <sub>IO</sub>	5	Supply	Transceiver logic-level supply voltage
CANL	6	I/O	Low-level CAN bus line
CANH	7	I/O	High-level CAN bus line
STB	8	I	Standby mode select pin (active high)

#### ORDERING INFORMATION(1)

T <sub>A</sub>	PACK	AGE <sup>(2)</sup>	ORDERABLE PART NUMBER	TOP-SIDE MARKING
40°C +- 40°C	colo D	Dark of 0500	SN65HVDA540QDR	A540Q
–40°C to 125°C	SOIC – D	Reel of 2500	SN65HVDA541QDR	A541Q

<sup>(1)</sup> For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.

#### **ABSOLUTE MAXIMUM RATINGS**(1)(2)

1.1	$V_{CC}$	Supply voltage range	–0.3 V to 6 V
1.2	V <sub>IO</sub>	I/O supply voltage range	–0.3 V to 6 V
1.3		Voltage range at bus terminals (CANH, CANL)	–27 V to 40 V
1.4	Io	Receiver output current	20 mA
1.5	VI	Voltage input range (TXD, STB)	-0.3 V to 6 V and V <sub>I</sub> ≤ V <sub>IO</sub> + 0.3 V
1.6	TJ	Operating virtual-junction temperature range	-40°C to 150°C
1.7	T <sub>LEAD</sub>	Lead temperature (soldering, 10 seconds)	260°C

<sup>(1)</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.

<sup>(2)</sup> Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.



## **INSTRUMENTS**

#### **ELECTROSTATIC DISCHARGE PROTECTION**

	PARAMETER	TEST CONDITIONS		VALUE
2.1		Lluman Bady Madal(1)	Bus terminals (CANH, CANL) and GND <sup>(2)</sup>	±12 kV
2.2	Electrostatic discharge	Human-Body Model (1)	All pins	±4 kV
2.3	Electrostatic discharge	Charged-Device Model (3)	All pins	±1 kV
2.4		Machine Model <sup>(4)</sup>	±200 V	

- Tested in accordance JEDEC Standard 22, Test Method A114-E (1)
- Test method based upon JEDEC Standard 22 Test Method A114-E, CANH and CANL bus pins stressed with respect to each other and
- Tested in accordance JEDEC Standard 22, Test Method C101 Tested in accordance JEDEC Standard 22, Test Method A115-A

#### RECOMMENDED OPERATING CONDITIONS

				MIN	MAX	UNIT
3.1	V <sub>CC</sub>	Supply voltage		4.75	5.25	V
3.2	V <sub>IO</sub>	I/O supply voltage		3	5.25	V
3.3	V <sub>I</sub> or V <sub>IC</sub>	Voltage at any bus terminal (separately	or common mode)	-12	12	V
3.4	V <sub>IH</sub>	High-level input voltage	TXD, STB	0.7 × V <sub>IO</sub>	$V_{IO}$	V
3.5	$V_{IL}$	Low-level input voltage	TXD, STB	0	$0.3 \times V_{IO}$	V
3.6	$V_{ID}$	Differential input voltage, bus	Between CANH and CANL	-6	6	V
3.7	I <sub>OH</sub>	High-level output current	RXD	-2		mA
3.8	I <sub>OL</sub>	Low-level output current	RXD		2	mA
3.9	T <sub>A</sub>	Operating ambient free-air temperature	See Thermal Characteristics table	-40	125	°C



#### SUPPLY CHARACTERISTICS

**NSTRUMENTS** 

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER		TEST CONDITIONS	MIN TYP <sup>(1)</sup>	MAX	UNIT
4.1			Standby mode	STB at $V_{IO}$ , $V_{CC}$ = 5.25 V, $V_{IO}$ = 3 V, TXD at $V_{IO}$ <sup>(2)</sup>		5	μΑ
4.2	I <sub>CC</sub>	5-V supply current	Normal mode: Dominant	TXD at 0 V, 60-Ω load, STB at 0 V	50	70	mA
4.3			Normal mode: Recessive	TXD at V <sub>IO</sub> , No load, STB at 0 V	6	10	IIIA
4.4			Standby mode	STB at $V_{IO}$ , $V_{CC}$ = 5.25 V or 0 V, RXD floating, TXD at $V_{IO}$	7	15	
4.5	I <sub>IO</sub>	I/O supply current	Normal mode (recessive or dominant)	STB at 0 V, V <sub>CC</sub> = 5.25 V, RXD floating, TXD at 0 V or V <sub>IO</sub>	75	300	μΑ
4.6	UV <sub>VCC</sub>	Undervoltage detection standby mode	on V <sub>CC</sub> for forced		3.6		٧
4.7	V <sub>HYS(UVVCC)</sub>	Hystersis voltage for un detection on UV <sub>VCC</sub> for			200		mV
4.8	UV <sub>VIO</sub>	Undervoltage detection on V <sub>IO</sub> for forced standby mode			2.5		V
4.9	V <sub>HYS(UVVIO)</sub>	Hystersis voltage for un detection on UV <sub>VIO</sub> for f mode			100		mV

#### **DEVICE SWITCHING CHARACTERISTICS**

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER	TEST CONDITIONS	MIN	TYP <sup>(1)</sup> MAX	UNIT
5.1	t <sub>d(LOOP1)</sub>	Total loop delay, driver input to receiver output, recessive to dominant		70	230	
5.2	t <sub>d(LOOP2)</sub>	Total loop delay, driver input to receiver output, dominant to recessive	Figure 11, STB at 0 V	70	230	ns

(1) All typical values are at 25°C and supply voltages of  $V_{CC}$  = 5 V and  $V_{IO}$  = 3.3 V.

All typical values are at 25°C and supply voltages of  $V_{CC}$  = 5 V and  $V_{IO}$  = 3.3 V. The  $V_{CC}$  supply is not needed during standby mode so in the application  $I_{CC}$  in standby mode may be zero. If the  $V_{CC}$  supply remains, then  $I_{CC}$  is per specification with  $V_{CC}$ .

## TEXAS INSTRUMENTS

#### **DRIVER ELECTRICAL CHARACTERISTICS**

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER		TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
6.1	V	Bus output voltage	CANH	$V_I = 0 \text{ V}, \text{ STB at } 0 \text{ V}, \text{ R}_L = 60 \Omega,$	2.9		4.5	<b>V</b>
6.2	V <sub>O(D)</sub>	(dominant)	CANL	See Figure 3 and Figure 4	0.8		1.75	٧
6.3	V <sub>O(R)</sub>	Bus output voltage (recess	sive)	$V_I = V_{IO}, \ V_{IO} = 3 \ V, \ STB \ at \ 0 \ V, \ R_L = 60 \ \Omega, \ See \ Figure \ 3 \ and \ Figure \ 4$	2	2.5	3	٧
6.4	Vo	Bus output voltage (stand	by mode)	STB at $V_{IO}$ , $R_L = 60 \Omega$ , See Figure 3 and Figure 4	-0.1		0.1	٧
6.5	V	Differential output voltage	(dominant)	$V_I = 0 \text{ V}, R_L = 60 \Omega, \text{ STB at } 0 \text{ V}, \\ \text{See Figure 3, Figure 4, and} \\ \text{Figure 5}$	1.5		3	٧
6.6	V <sub>OD(D)</sub>	$V_{\mathrm{OD(D)}}$ Differential output voltage (		$V_I = 0 \text{ V}, R_L = 45 \Omega, \text{ STB at } 0 \text{ V}, \\ \text{See Figure 3, Figure 4, and} \\ \text{Figure 5}$	1.4		3	V
6.7	V <sub>OD(R)</sub>	Differential output voltage	(recessive)	$V_I = 3 \text{ V}$ , STB at 0 V, $R_L = 60 \Omega$ , See Figure 3 and Figure 4	-0.012		0.012	٧
6.8				V <sub>I</sub> = 3 V, STB at 0 V, No load	-0.5		0.05	
6.9	V <sub>SYM</sub>	Output symmetry (domina recessive) (V <sub>O(CANH)</sub> + V <sub>O</sub>		STB at 0 V, $R_L = 60 \Omega$ , See Figure 15	0.9 V <sub>CC</sub>	$V_{CC}$	1.1 V <sub>CC</sub>	٧
6.10	V <sub>OC(ss)</sub>	Steady-state common-mo voltage	de output	STB at 0 V, $R_L = 60 \Omega$ ,	2	2.5	3	٧
6.11	$\Delta V_{OC(ss)}$	Change in steady-state common-mode output volt	tage	See Figure 10 ge		30		mV
6.12	I <sub>IH</sub>	High-level input current, T	XD input	TXD at V <sub>IO</sub>	-2		2	μΑ
6.13	I <sub>IL</sub>	Low-level input current, TX	XD input	TXD at 0 V	-100		-7	μΑ
6.14	I <sub>O(off)</sub>	Power-off TXD output curi	rent	V <sub>CC</sub> = 0 V, V <sub>IO</sub> = 0V, TXD at 5.25 V			1	μΑ
6.15				V <sub>CANH</sub> = -12 V, CANL open, See Figure 13	-120	-85		
6.16		Short-circuit steady-state	output	V <sub>CANH</sub> = 12 V, CANL open, See Figure 13		0.5	1	A
6.17	I <sub>OS(ss)</sub>	current	•	V <sub>CANL</sub> = -12 V, CANH open, See Figure 13	-1	-0.6		mA
6.18				V <sub>CANL</sub> = 12 V, CANH open, See Figure 13		75	120	
6.19	Co	Output capacitance		See receiver input capacitance		-		

<sup>(1)</sup> All typical values are at 25°C and supply voltages of  $V_{CC}$  = 5 V and  $V_{IO}$  = 3.3 V.

#### **DRIVER SWITCHING CHARACTERISTICS**

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER	TEST CONDITIONS	MIN -	TYP <sup>(1)</sup>	MAX	UNIT
7.1	t <sub>PLH</sub>	Propagation delay time, low-to-high level output	STB at 0 V, See Figure 6		65	120	
7.2	t <sub>PHL</sub>	Propagation delay time, high-to-low level output	STB at 0 V, See Figure 6		50	120	
7.3	t <sub>r</sub>	Differential output signal rise time	STB at 0 V, See Figure 6		25		ns
7.4	t <sub>f</sub>	Differential output signal fall time	STB at 0 V, See Figure 6		45		
7.5	t <sub>en</sub>	Enable time from standby mode to dominant	See Figure 9			10	μs
7.6	t <sub>(dom)</sub>	Dominant time out	See Figure 12	300	400	700	μs

<sup>(1)</sup> All typical values are at 25°C and supply voltages of  $V_{CC}$  = 5 V and  $V_{IO}$  = 3.3 V.



#### RECEIVER ELECTRICAL CHARACTERISTICS

**NSTRUMENTS** 

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER	TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
8.1	V <sub>IT+</sub>	Positive-going input threshold voltage, normal mode	STB at 0 V, See Differential Input Voltage Threshold Test		800	900	mV
8.2	V <sub>IT</sub>	Negative-going input threshold voltage, normal mode	STB at 0 V, See Differential Input Voltage Threshold Test	500	650		mV
8.3	V <sub>hys</sub>	Hysteresis voltage (V <sub>IT+</sub> – V <sub>IT-</sub> )		100	125		mV
8.4	V <sub>IT</sub>	Input threshold voltage, standby mode (SN65HVDA541 only)	STB at V <sub>IO</sub>	400		1150	mV
8.5	V <sub>OH</sub>	High-level output voltage, RXD	I <sub>O</sub> = -2 mA, See Figure 8	$0.8 \times V_{IO}$			٧
8.6	V <sub>OL</sub>	Low-level output voltage, RXD	I <sub>O</sub> = 2 mA, See Figure 8			$0.2 \times V_{IO}$	٧
8.7	I <sub>I(off)</sub>	Power-off bus input current	CANH = CANL = 5 V, V <sub>CC</sub> at 0 V, V <sub>IO</sub> at 0 V, TXD at 0 V			3	μΑ
8.8	I <sub>O(off)</sub>	Power-off RXD leakage current	V <sub>CC</sub> at 0 V, V <sub>IO</sub> at 0 V, RXD at 5.25 V			20	μΑ
8.9	Cı	Input capacitance to ground (CANH or CANL)	TXD at $V_{IO}$ , $V_{IO}$ at 3.3 V, $V_{I} = 0.4 \sin (4E6\pi t) + 2.5 V$		13		pF
8.10	C <sub>ID</sub>	Differential input capacitance	TXD at $V_{IO}$ , $V_{IO} = 3.3 \text{ V}$ , $V_{I} = 0.4 \sin(4E6\pi t)$		6		pF
8.11	R <sub>ID</sub>	Differential input resistance	TXD at $V_{IO}$ , $V_{IO}$ = 3.3 V, STB at 0 V	29		80	kΩ
8.12	R <sub>IN</sub>	Input resistance (CANH or CANL)	TXD at $V_{IO}$ , $V_{IO}$ = 3.3 V, STB at 0 V	14.5	25	40	kΩ
8.13	R <sub>I(m)</sub>	Input resistance matching [1 – (R <sub>IN(CANH)</sub> /R <sub>IN(CANL)</sub> )] × 100%	$V_{(CANH)} = V_{(CANL)}$	-3	0	3	%

<sup>(1)</sup> All typical values are at 25°C and supply voltages of  $V_{CC}$  = 5 V and  $V_{IO}$  = 3.3 V.

#### RECEIVER SWITCHING CHARACTERISTICS

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER	TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
9.1	t <sub>PLH</sub>	Propagation delay time, low-to-high-level output			85	150	ns
9.2	t <sub>PHL</sub>	Propagation delay time, high-to-low-level output	STB at 0 V , See Figure 8		55	130	ns
9.3	t <sub>r</sub>	Output signal rise time	STB at 0 V , See Figure 8		8		ns
9.4	t <sub>f</sub>	Output signal fall time			8		ns
9.5	t <sub>BUS</sub>	Dominant time required on bus for wake-up from standby (SN65HVDA541 only)	STB at V <sub>IO</sub> , See Figure 14	1.5		5	μs
9.6	t <sub>CLEAR</sub>	Recessive time on the bus to clear the standby mode receiver output (RXD) if standby mode is entered while bus is dominant (SN65HVDA541 only)		1.5		5	μs

<sup>(1)</sup> All typical values are at 25°C and supply voltages of  $V_{CC}$  = 5 V and  $V_{IO}$  = 3.3 V.

#### STB PIN CHARACTERISTICS

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER	TEST CONDITIONS	MIN TYP <sup>(1)</sup>	MAX	UNIT
10.1	I <sub>IH</sub>	High-level input current	STB at V <sub>IO</sub>		15	
10.2	I <sub>IL</sub>	Low-level input current	STB at 0 V	-20		μΑ

(1) All typical values are at 25°C and supply voltages of  $V_{CC}$  = 5 V and  $V_{IO}$  = 3.3 V.

## NSTRUMENTS

#### THERMAL CHARACTERISTICS

over recommended operating conditions,  $T_J = -40$ °C to 150°C (unless otherwise noted)

		PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
11.1	0	Junction-to-air thermal	Low-K thermal resistance <sup>(2)</sup>		140		°C/W
11.2	$\theta_{JA}$	resistance <sup>(1)</sup>	High-K thermal resistance (2)		109		C/VV
11.3	$\theta_{JB}$	Junction-to-board thermal resistance			50		°C/W
11.4	$\theta_{\text{JC}}$	Junction-to-case thermal resistance			56		°C/W
11.5	P <sub>D</sub>	Average power dissipation	$V_{CC}$ = 5 V, $V_{IO}$ = 3.3V, $T_J$ = 27°C, $R_L$ = 60 $\Omega$ , STB at 0 V, Input to TXD at 500 kHz, 50% duty cycle square wave, $C_L$ at RXD = 15 pF		112		mW
11.6			$V_{CC}$ = 5.5 V, $V_{IO}$ = 3.3V, $T_J$ = 130°C, $R_L$ = 45 $\Omega$ , STB at 0 V, Input to TXD at 500 kHz, 50% duty cycle square wave, $C_L$ at RXD = 15 pF			170	
11.7		Thermal shutdown temperature			185		°C

#### **OPERATING MODE SELECTION**

V <sub>CC</sub>	V <sub>IO</sub>	STB <sup>(1)</sup>	BUS STATE	RXD STATE
V <sub>CC</sub> ≥ UV <sub>VCC</sub>	V <sub>IO</sub> ≥ UV <sub>VIO</sub>	L	Normal Mode	Mirrors bus state
V <sub>CC</sub> ≥ UV <sub>VCC</sub>	V <sub>IO</sub> ≥ UV <sub>VIO</sub>	Н	Standby Mode	Mirrors bus state via wake-up filter (2)
V <sub>CC</sub> ≤ UV <sub>VCC</sub>	V <sub>IO</sub> ≥ UV <sub>VIO</sub>	Х	Standby Mode (Forced)	Mirrors bus state via wake-up filter <sup>(2)</sup>
V <sub>CC</sub> ≥ UV <sub>VCC</sub>	V <sub>IO</sub> ≤ UV <sub>VIO</sub>	Х	Standby Mode (Forced) (3)	3-state

<sup>(1)</sup> H = high level, L = low level, X = irrelevant

The junction temperature  $(T_J)$  is calculated using the following  $T_J = T_A + (P_D \times \theta_{JA})$ Tested in accordance with the Low-K (EIA/JESD51-3) or High-K (EIA/JESD51-7) thermal metric definitions for leaded surface-mount packages.

SN65HVDA541 only. SN65HVDA540 RXD state is recessive.

When V<sub>IO</sub> is undervoltage, the device is forced into standby mode with respect to the CAN bus since there is not a valid digitial reference to determine the digital I/O states or power the wake-up receiver.



#### **FUNCTION TABLES**

#### **DRIVER**

IN	PUTS	TUO	BUS STATE	
TXD <sup>(1)</sup>	TXD <sup>(1)</sup> STB <sup>(1)</sup>			
L	L	Н	L	DOMINANT
Н	L	Z	Z	RECESSIVE
Open	L	Z	Z	RECESSIVE
Х	H or Open	Υ	Y	RECESSIVE

(1) H = high level, L = low level, X = irrelevant, ? = indeterminate, Y = weak pull down to GND, Z = high impedance

#### **RECEIVER**

DIFFERENTIAL INPUTS V <sub>ID</sub> = V(CANH) - V(CANL)	STB <sup>(1)</sup>	OUTPUT RXD <sup>(1)</sup>		BUS STATE
X	H or Open	SN65HVDA540 <sup>(2)</sup>	Н	X
V <sub>ID</sub> ≥ 1.15 V		SN65HVDA541 (3)	L	DOMINANT
0.4 V < V <sub>ID</sub> < 1.15 V			?	?
V <sub>ID</sub> ≤ 0.4 V			Н	RECESSIVE
V <sub>ID</sub> ≥ 0.9 V	L	L		DOMINANT
0.5 V < V <sub>ID</sub> < 0.9 V	L	?		?
V <sub>ID</sub> ≤ 0.5 V	L	Н		RECESSIVE
Open	Х	Н		RECESSIVE

- (1) H = high level, L = low level, X = irrelevant, ? = indeterminate, Y = weak pull down to GND, Z = high impedance
- (2) While STB is high (standby mode) the RXD output of the SN65HVDA540 is always high (recessive) because it has no wake-up receiver
- (3) While STB is high (standby mode) the RXD output of the SN65HVDA541 functions according to the levels above and the wake-up conditions shown in Figure 1 and Figure 2.

#### PARAMETER MEASUREMENT INFORMATION

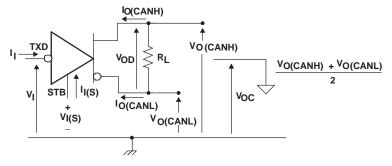


Figure 3. Driver Voltage, Current, and Test Definition

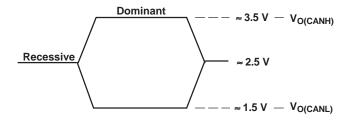


Figure 4. Bus Logic-State Voltage Definitions

**NSTRUMENTS** 

#### PARAMETER MEASUREMENT INFORMATION (continued)

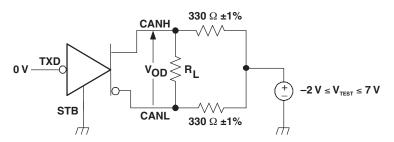
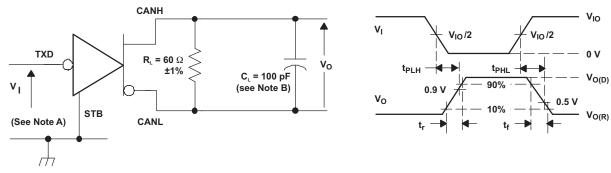


Figure 5. Driver  $V_{\text{OD}}$  Test Circuit



- A. The input pulse is supplied by a generator having the following characteristics: PRR  $\leq$  125 kHz, 50% duty cycle,  $t_f \leq$  6 ns,  $t_f \leq$  6 ns,  $t_G =$  50  $\Omega$ .
- B. C<sub>L</sub> includes instrumentation and fixture capacitance within ±20%.

Figure 6. Driver Test Circuit and Voltage Waveforms

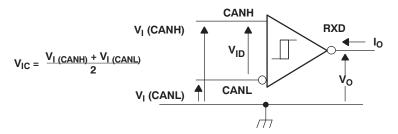
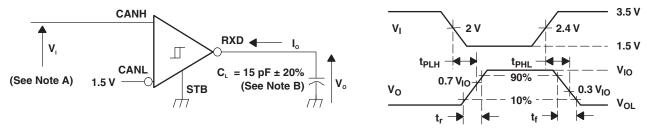


Figure 7. Receiver Voltage and Current Definitions



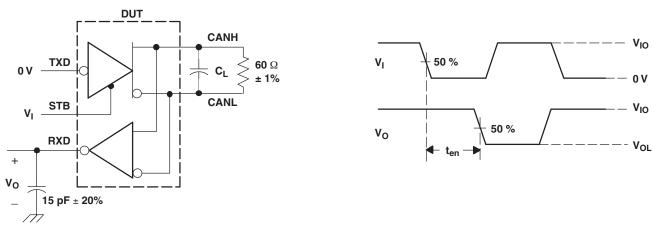
- A. The input pulse is supplied by a generator having the following characteristics: PRR  $\leq$  125 kHz, 50% duty cycle,  $t_f \leq$  6 ns,  $t_f \leq$  6 ns,  $Z_O = 50 \Omega$ .
- B. C<sub>L</sub> includes instrumentation and fixture capacitance within ±20%.

Figure 8. Receiver Test Circuit and Voltage Waveforms



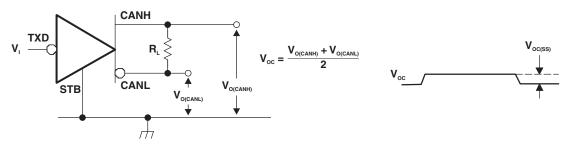
#### **Differential Input Voltage Threshold Test**

	INPUT	OUTPUT			
V <sub>CANH</sub>	V <sub>CANL</sub>	V <sub>ID</sub>	R		
–11.1 V	-12 V	900 mV	L		
12 V	11.1 V	900 mV	L	.,	
-6 V	-12 V	6 V	L	V <sub>OL</sub>	
12 V	6 V	6 V	L		
–11.5 V	-12 V	500 mV	Н		
12 V	11.5 V	500 mV	Н		
–12 V	−6 V	6 V	Н	V <sub>OH</sub>	
6 V	12 V	6 V	Н		
Open	Open	Х	Н		



- A.  $C_L = 100 \text{ pF}$  includes instrumentation and fixture capacitance within  $\pm 20\%$ .
- B. All  $V_1$  input pulses are from 0 V to  $V_{IO}$  and supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 6$  ns. Pulse Repetition Rate (PRR) = 25 kHz, 50% duty cycle.

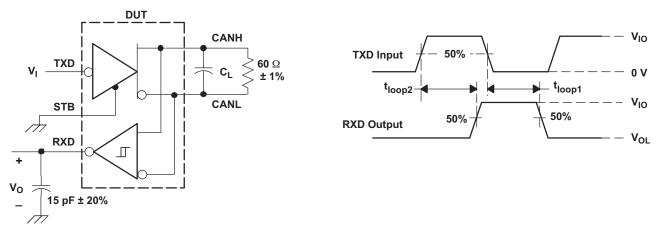
Figure 9. ten Test Circuit and Waveforms



A. All  $V_1$  input pulses are from 0 V to  $V_{1O}$  and supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 6$  ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

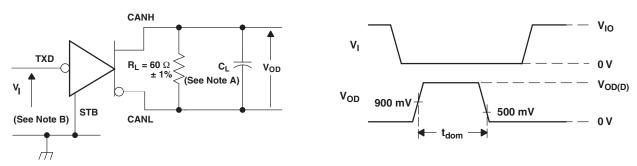
Figure 10. Common-Mode Output Voltage Test and Waveforms





- A.  $C_L = 100 \text{ pF}$  includes instrumentation and fixture capacitance within  $\pm 20\%$ .
- B. All  $V_I$  input pulses are from 0 V to  $V_{IO}$  and supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 6$  ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

Figure 11. t<sub>(LOOP)</sub> Test Circuit and Waveform



- A.  $C_L = 100 \text{ pF}$  includes instrumentation and fixture capacitance within ±20%.
- B. All  $V_1$  input pulses are from 0 V to  $V_{1O}$  and supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 6$  ns. Pulse Repetition Rate (PRR) = 500 Hz, 50% duty cycle.

Figure 12. Dominant Time-Out Test Circuit and Waveforms

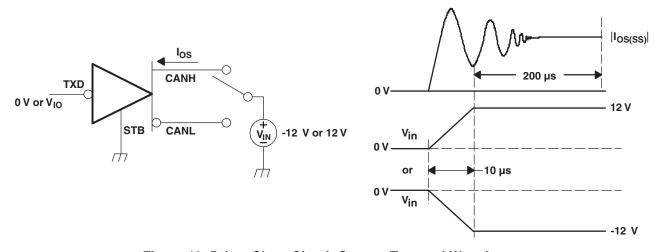
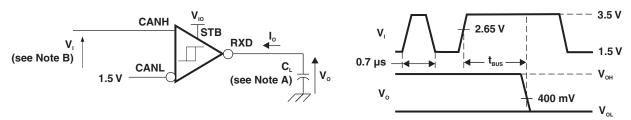


Figure 13. Driver Short-Circuit Current Test and Waveforms



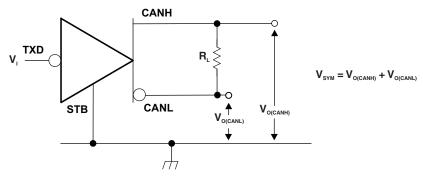


A. C<sub>L</sub> = 15 pF and includes instrumentation and fixture capacitance within ±20%.

**INSTRUMENTS** 

B. For  $V_I$  bit width  $\leq 0.7~\mu s$ ,  $V_O = V_{OH}$ . For  $V_I$  bit width  $\geq 5~\mu s$ ,  $V_O = V_{OL}$ .  $V_I$  input pulses are supplied from a generator with the following characteristics:  $t_r/t_f < 6~n s$ .

Figure 14. t<sub>BUS</sub> Test Circuit and Waveforms

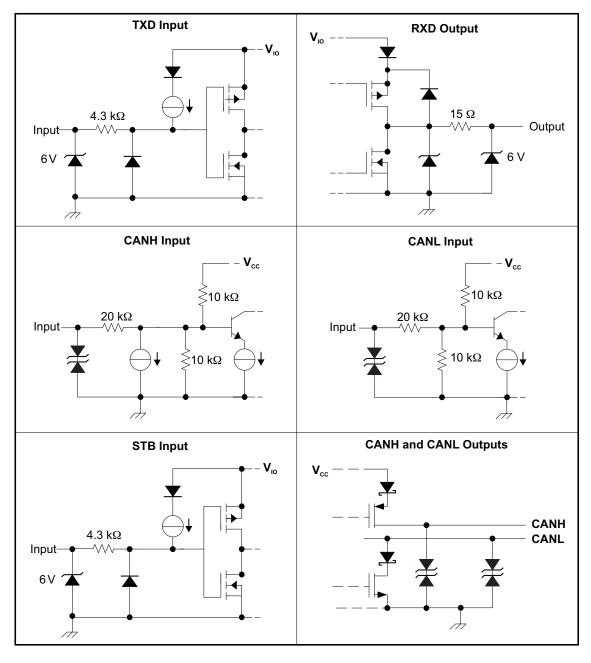


A. All  $V_l$  input pulses are from 0 V to  $V_{lO}$  and supplied by a generator having the following characteristics:  $t_r/t_f \le 6$  ns, Pulse Repetition Rate (PRR) = 250 kHz, 50% duty cycle.

Figure 15. Driver Output Symmetry Test Circuit

## TEXAS INSTRUMENTS

### **Equivalent Input and Output Schematic Diagrams**





#### **APPLICATION INFORMATION**

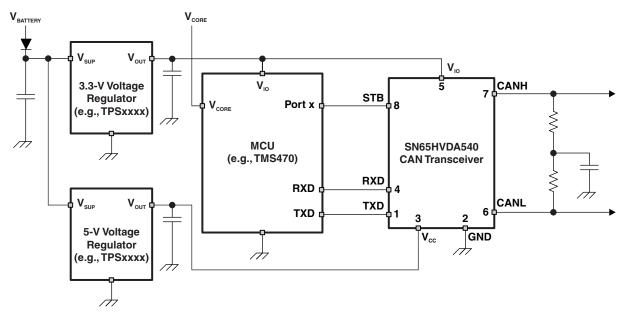


Figure 16. Typical Application Using 3.3 V I/O voltage level

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#### **PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/ Ball Finish	MSL Peak Temp <sup>(3)</sup>	Samples (Requires Login)
SN65HVDA540QDR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Request Free Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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#### OTHER QUALIFIED VERSIONS OF SN65HVDA540:

Automotive: SN65HVDA540-Q1

NOTE: Qualified Version Definitions:

Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

### D (R-PDSO-G8)

#### PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.



### D (R-PDSO-G8)

### PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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