



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

PACKAGE/ORDERING INFORMATION⁽¹⁾

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	PACKAGE MARKING
AFE031AIRGZT	QFN-48 PowerPAD	RGZ	AFE031A
AFE031AIRGZR	QFN-48 PowerPAD	RGZ	AFE031A

(1) For the most current package and ordering information see the Package Option Addendum at the end of this document, or visit the device product folder at www.ti.com.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

Over operating free-air temperature range (unless otherwise noted).

		VALUE	UNIT
Supply voltage, PA_V _S		+26	V
Signal input terminal, pins 18,19	Voltage ⁽²⁾	PA_GND – 0.4 to PA_V _S + 0.4	V
	Current ⁽²⁾	±10	mA
Supply voltage, AV _{DD}		+5.5	V
Signal input terminal, pins 13, 15, 16, 21, 23, 24, 25, 28, 32, 34, 35, 38, 39, 46	Voltage ⁽²⁾	AGND – 0.4 to AV _{DD} + 0.4	V
	Current ⁽²⁾	±10	mA
Signal input terminal, pin 27	Voltage limit	±10	V
Signal input terminal, pin 10	Current limit	±10	mA
Supply voltage, DV _{DD}		+5.5	V
Signal input terminal, pins 3, 4, 6, 7, 8	Voltage ⁽²⁾	DGND – 0.4 to DV _{DD} + 0.4	V
	Current ⁽²⁾	±10	mA
Signal output terminal, pins 5, 9, 14, 17, 20, 22, 26, 31, 33, 36, 37, 47, 48	Current ⁽²⁾	Continuous	
Output short-circuit (PA), pins 42,43 ⁽²⁾⁽³⁾⁽⁴⁾		Continuous	
Operating temperature, T _A ⁽⁴⁾		–40 to +150	°C
Storage temperature, T _A		–55 to +150	°C
Junction temperature, T _J		+150	°C
ESD ratings	Human body model (HBM)	3000	V
	Machine model (MM)	200	V
	Charged device model (CDM)	500	V

- (1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.
- (2) Input terminals are diode-clamped to the power-supply rails. Input signals that can swing more than 0.4 V beyond the supply rails should be current limited to 10 mA or less. Output terminals are diode-clamped to the power-supply rails. Output signals that can swing more than 0.4 V beyond the supply rails should be current limited to 10 mA or less.
- (3) Short-circuit to ground.
- (4) The AFE031 automatically goes into shutdown at junction temperatures that exceed +150°C.

ELECTRICAL CHARACTERISTICS: Transmitter (Tx)

 At $T_J = +25^\circ\text{C}$, $PA_{V_S} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT	
		MIN	TYP	MAX		
Tx_DAC						
Output range		GND + 0.1		$AV_{DD} - 0.1$	V	
Resolution	1,024 steps, 10-bit DAC		3.2		mV	
Total harmonic distortion at 62.5 kHz ⁽¹⁾	THD					
Second harmonic distortion			-73		dB	
Third harmonic distortion			-56		dB	
Fourth harmonic distortion			-94		dB	
Data rate			1.5		MSPS	
Tx_PGA						
Input						
Input voltage range		GND - 0.1		$AV_{DD} + 0.1$	V	
Input resistance	R_I	$G = 1\text{ V/V}$		58	k Ω	
		$G = 0.707\text{ V/V}$		68	k Ω	
		$G = 0.5\text{ V/V}$		77	k Ω	
		$G = 0.25\text{ V/V}$		92	k Ω	
Frequency Response						
Bandwidth	BW	DAC mode enabled				
		$G = 1\text{ V/V}$		8	MHz	
		$G = 0.707\text{ V/V}$		9	MHz	
		$G = 0.5\text{ V/V}$		10	MHz	
		$G = 0.25\text{ V/V}$		12	MHz	
Output						
Voltage output swing from AGND or AV_{DD}	V_O	$R_{LOAD} = 10\text{ k}\Omega$, connected to $AV_{DD}/2$		10	100	mV
Maximum continuous current, dc	I_O	Sourcing		25		mA
		Sinking		25		mA
Output resistance	R_O	$f = 100\text{ kHz}$		1		Ω
Gain						
Gain error		For all gains	-1	± 0.1	+1	%
Gain error drift		$T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$		6		ppm/ $^\circ\text{C}$

 (1) Total harmonic distortion measured at output of Tx_PGA configured in a gain of 1 V/V with an amplitude of 3 V_{PP} , at a 1-MHz sample rate.

ELECTRICAL CHARACTERISTICS: Transmitter (Tx) (continued)

At $T_J = +25^\circ\text{C}$, $PA_{V_S} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT	
		MIN	TYP	MAX		
Tx_FILTER						
Input						
Input voltage range		GND – 0.1		$AV_{DD} + 0.1$	V	
Input resistance (Tx_F_IN1 and Tx_F_IN2)	R_I		43		$\text{k}\Omega$	
Frequency Response						
CENELEC A Mode						
Passband frequency	–3 dB		95		kHz	
Stop band attenuation		–50	–60		dB	
Stop band frequency			910		kHz	
Filter gain			0		dB	
CENELEC B/C/D Modes						
Passband frequency	–3 dB		145		kHz	
Stop band attenuation		–50	–60		dB	
Stop band frequency			870		kHz	
Filter gain			0		dB	
Output						
Voltage output swing from AGND or AV_{DD}	V_O	$R_{LOAD} = 10\text{ k}\Omega$, connected to $AV_{DD}/2$		10	100	mV
Maximum continuous current, dc	I_O	Sourcing		25		mA
		Sinking		25		mA
Output resistance	R_O	$f = 100\text{ kHz}$		1		Ω
Transmitter Noise						
Integrated noise at PA output ⁽²⁾						
CENELEC Band A (40 kHz to 90 kHz)	Noise-reducing capacitor = 1 nF from pin 19 to ground			435		μV_{RMS}
CENELEC Bands B/C/D (95 kHz to 140 kHz)	Noise-reducing capacitor = 1 nF from pin 19 to ground			460		μV_{RMS}

(2) Includes DAC, Tx_PGA, Tx_Filter, PA, and REF1 bias generator.

ELECTRICAL CHARACTERISTICS: Power Amplifier (PA)

 At $T_J = +25^\circ\text{C}$, $PA_{VS} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT	
		MIN	TYP	MAX		
Input						
Input voltage range		GND – 0.1		$PA_{VS} + 0.1$	V	
Input resistance	R_I		20		$\text{k}\Omega$	
Frequency Response						
Bandwidth	BW	$I_{LOAD} = 0$		670	kHz	
Slew rate	SR	10-V step		19	$\text{V}/\mu\text{s}$	
Full-power bandwidth		$V_{OUT} = 10\text{ V}_{PP}$		300	kHz	
AC PSRR		$f = 50\text{ kHz}$		14	dB	
Output						
Voltage output swing from PA_{VS}	V_O	$I_O = 300\text{ mA}$, sourcing		0.3	1	V
		$I_O = 1.5\text{ A}$, sourcing		1.7	2	V
Voltage output swing from PA_{Gnd}	V_O	$I_O = 300\text{ mA}$, sinking		0.3	1	V
		$I_O = 1.5\text{ A}$, sinking		1.3	2	V
Maximum continuous current, dc	I_O	$7.5\text{ k}\Omega$ connected to PA_{ISET}	1.5			A
Maximum peak current, ac		$T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$; $f = 50\text{ kHz}$		1.7		A
Output resistance	R_O	$I_O = 1.5\text{ A}$		0.1		Ω
PA disabled						
Output impedance		$f = 100\text{ kHz}$, REF1 enabled		$145\text{ }\parallel\text{ }120$		$\text{k}\Omega\text{ }\parallel\text{ }\mu\text{F}$
Output current limit range				± 0.4 to ± 1.5		A
Current limit equation				$I_{LIM} = 20\text{ k}\Omega \cdot [1.2\text{ V}/(R_{SET} + 5\text{ k}\Omega)]$		A
		Solved for R_{SET} (Current Limit)		$R_{SET} = [(20\text{ k}\Omega \cdot 1.2\text{ V}/I_{LIM}) - 5\text{ k}\Omega]$		Ω
Gain $R_{LOAD} = 1\text{ k}\Omega$						
Nominal gain	G			6.5		V/V
Gain error			-1	0.1	+1	%
Gain error drift		$T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$		± 1		$\text{ppm}/^\circ\text{C}$
TSense Diode						
Diode ideality factor	η			1.033		
Thermal Shutdown						
Junction temperature at shutdown				+160		$^\circ\text{C}$
Hysteresis				15		$^\circ\text{C}$
Return to normal operation				+145		$^\circ\text{C}$

ELECTRICAL CHARACTERISTICS: Receiver (Rx)

At $T_J = +25^\circ\text{C}$, $PA_{V_S} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT	
		MIN	TYP	MAX		
Rx PGA1						
Input						
Input voltage range			10		V_{PP}	
Input resistance	R_I	$G = 2\text{ V/V}$	10		$\text{k}\Omega$	
		$G = 1\text{ V/V}$	15		$\text{k}\Omega$	
		$G = 0.5\text{ V/V}$	20		$\text{k}\Omega$	
		$G = 0.25\text{ V/V}$	24		$\text{k}\Omega$	
Frequency Response						
Bandwidth	BW	$G = 2\text{ V/V}$	6		MHz	
		$G = 1\text{ V/V}$	10		MHz	
		$G = 0.5\text{ V/V}$	13		MHz	
		$G = 0.25\text{ V/V}$	15		MHz	
Output						
Voltage output swing from AGND or AV_{DD}	V_O	$R_{LOAD} = 6\text{ k}\Omega$, connected to $AV_{DD}/2$	10	100	mV	
Maximum continuous current, dc	I_O	Sourcing	25		mA	
		Sinking	25		mA	
Output resistance	R_O	$G = 1$, $f = 100\text{ kHz}$	1		Ω	
Gain						
Gain error		$G = 0.25\text{ V/V}$	-1	± 0.1	+1	%
		$G = 0.5\text{ V/V}$	-1	± 0.1	+1	%
		$G = 1\text{ V/V}$	-1	± 0.1	+1	%
		$G = 2\text{ V/V}$	-2	± 0.2	+2	%
Gain error drift		$T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$	1		ppm/ $^\circ\text{C}$	
Rx Filter						
Input						
Input voltage range		GND - 0.1		$AV_{DD} + 0.1$	V	
Input resistance	R_{IN}		6		$\text{k}\Omega$	
Frequency Response						
CENELEC A Mode		$Rx_C1 = 680\text{ pF}$, $Rx_C2 = 680\text{ pF}$				
Passband frequency		-3 dB		90	kHz	
Stop band attenuation			-25	-33	dB	
Stop band frequency				270	kHz	
Filter gain				0	dB	
CENELEC B/C/D Modes		$Rx_C1 = 270\text{ pF}$, $Rx_C2 = 560\text{ pF}$				
Passband frequency		-3 dB		145	kHz	
Stop band attenuation			-23	-27	dB	
Stop band frequency				350	kHz	
Filter gain				0	dB	
Output						
Voltage output swing from AGND or AV_{DD}	V_O	$R_{LOAD} = 10\text{ k}\Omega$, connected to $AV_{DD}/2$	10	100	mV	
Maximum continuous current, dc	I_O	Sourcing	25		mA	
		Sinking	25		mA	
Output resistance	R_O	$f = 100\text{ kHz}$	5		Ω	

ELECTRICAL CHARACTERISTICS: Receiver (Rx) (continued)

 At $T_J = +25^\circ\text{C}$, $PA_{V_S} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT	
		MIN	TYP	MAX		
Rx PGA2						
Input						
Input voltage range		GND – 0.1		$AV_{DD} + 0.1$	V	
Input impedance	R_I	$G = 64\text{ V/V}$		1.7	k Ω	
		$G = 16\text{ V/V}$		6.3	k Ω	
		$G = 4\text{ V/V}$		21	k Ω	
		$G = 1\text{ V/V}$		53	k Ω	
Frequency Response						
Bandwidth	BW	$G = 64\text{ V/V}$		300	kHz	
		$G = 16\text{ V/V}$		800	kHz	
		$G = 4\text{ V/V}$		1.4	MHz	
		$G = 1\text{ V/V}$		4	MHz	
Output						
Voltage output swing from AGND or AV_{DD}	V_O	$R_{LOAD} = 10\text{ k}\Omega$, connected to $AV_{DD}/2$		10	100	mV
Maximum continuous current, dc	I_O	Sourcing		25		mA
		Sinking		25		mA
Output impedance	R_O	$G = 1$, $f = 100\text{ kHz}$		1		Ω
Gain						
Gain error		$G = 1\text{ V/V}$	–2	± 1	2	%
		$G = 4\text{ V/V}$	–2	± 1	2	%
		$G = 16\text{ V/V}$	–2	± 1	2	%
		$G = 64\text{ V/V}$	–4	± 1	4	%
Gain error drift		$T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$		6		ppm/ $^\circ\text{C}$
Rx Sensitivity						
Integrated noise, $RTI^{(1)}$						
CENELEC Band A (40 kHz to 90 kHz)		Noise-reducing capacitor = $1\text{ }\mu\text{F}$ from pin 28 to ground		14		μV_{RMS}
CENELEC Bands B/C/D (95 kHz to 140 kHz)		Noise-reducing capacitor = $1\text{ }\mu\text{F}$ from pin 28 to ground		11		μV_{RMS}

(1) Includes Rx PGA1, Rx_Filter, Rx PGA2, and REF2 bias generator.

ELECTRICAL CHARACTERISTICS: Digital

At $T_J = +25^\circ\text{C}$, $PA_{V_S} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT
		MIN	TYP	MAX	
Digital Inputs (SCLK, DIN, $\overline{\text{CS}}$, DAC, SD)					
Leakage input current	$0 \leq V_{IN} \leq DV_{DD}$	-1	0.01	1	μA
Input logic levels					
High-level input voltage V_{IH}		$0.7 \cdot DV_{DD}$			V
Low-level input voltage V_{IL}				$0.3 \cdot DV_{DD}$	V
SD pin high	$SD > 0.7 \cdot DV_{DD}$	AFE031 in shutdown			
SD pin low	$SD < 0.3 \cdot DV_{DD}$	AFE031 in normal operation			
DAC pin high	$DAC > 0.7 \cdot DV_{DD}$	SPI access to DAC Register			
DAC pin low	$DAC < 0.3 \cdot DV_{DD}$	SPI access to Command and Data Registers			
Digital Outputs (DO, ZC_OUT)					
High-level output voltage V_{OH}	$I_{OH} = 3\text{ mA}$	$DV_{DD} - 0.4$		DV_{DD}	V
Low-level output voltage V_{OL}	$I_{OL} = -3\text{ mA}$	GND		$GND + 0.4$	V
Digital Outputs (INT, Tx_Flag, Rx_Flag)					
High-level output current I_{OH}	$V_{OH} = 3.3\text{ V}$			1	μA
Low-level output voltage V_{OL}	$I_{OL} = 4\text{ mA}$			0.4	V
Low-level output current I_{OL}	$V_{OL} = 400\text{ mV}$	4			mA
INT pin high (open drain)	INT sink current $< 1\ \mu\text{A}$	Normal operation			
INT pin low (open drain) ⁽¹⁾	INT $< 0.4\text{ V}$	Indicates an interrupt has occurred			
Tx_Flag high (open drain)	Tx_Flag sink current $< 1\ \mu\text{A}$	Indicates Tx block is ready			
Tx_Flag low (open drain)	Tx_Flag $< 0.4\text{ V}$	Indicates Tx block is not ready			
Rx_Flag high (open drain)	Rx_Flag sink current $< 1\ \mu\text{A}$	Indicates Rx block is ready			
Rx_Flag low (open drain)	Rx_Flag $< 0.4\text{ V}$	Indicates Rx block is not ready			
DIGITAL TIMING					
Gain Timing					
Gain select time			0.2		μs
Shutdown Mode Timing					
Enable time			4.0		μs
Disable time			2.0		μs
POR Timing					
Power-On Reset power-up time	$DV_{DD} \geq 2\text{ V}$		50		μs

(1) When an interrupt is detected (INT pin low), the contents of the I_Flag and T_Flag Registers can be read to determine the reason for the interrupt.

ELECTRICAL CHARACTERISTICS: Two-Wire Interface

 At $T_J = +25^\circ\text{C}$, $PA_{V_S} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT
		MIN	TYP	MAX	
TWO-WIRE TRANSMITTER					
Frequency range ⁽¹⁾			50		kHz
Leakage input current (E_{Tx_In} , E_{Tx_Clk})	$0 \leq V_{IN} \leq DV_{DD}$	-1	0.01	1	μA
Input logic levels (E_{Tx_In} , E_{Tx_Clk})					
High-level input voltage	V_{IH}	$0.7 \cdot DV_{DD}$			V
Low-level input voltage	V_{IL}			$0.3 \cdot DV_{DD}$	V
Output logic levels (E_{Tx_Out})					
High-level output voltage	V_{OH} $I_{OH} = 3\text{ mA}$	$AV_{DD} - 0.4$		AV_{DD}	V
Low-level output voltage	V_{OL} $I_{OL} = -3\text{ mA}$	GND		$GND + 0.4$	V
TWO-WIRE RECEIVER					
Gain			-4.5		dB
Frequency range			300		kHz
Max sink current			25		mA
Max source current			25		mA
Input terminal offset	Referenced to $V_{AVDD}/2$	-100	10	100	mV
Input impedance			78		k Ω
ZERO CROSSING DETECTOR					
Input voltage range		$AV_{DD} - 0.4$		$AV_{DD} + 0.4$	V
Input current range		-10		+10	mA
Input capacitance			3		pF
Rising threshold		0.45	0.9	1.35	V
Falling threshold		0.25	0.5	0.75	V
Hysteresis		0.20	0.4	0.60	V
Jitter	50 Hz, 240 V_{RMS}		10		ns

 (1) The two-wire transmitter circuit is tested at $Tx_CLK = 10\text{ MHz}$.

ELECTRICAL CHARACTERISTICS: Internal Bias Generator

 At $T_J = +25^\circ\text{C}$, $PA_{V_S} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT
		MIN	TYP	MAX	
REF1 (Pin 19)					
Bias voltage			$PA_{V_S}/2$		V
Input resistance	R_I		4		k Ω
Turn-on time	Noise-reducing capacitor = 1 nF from pin 19 to ground		20		ms
Turn-off time	Noise-reducing capacitor = 1 nF from pin 19 to ground		20		ms
REF2 (Pin 28)					
Bias voltage			$V_{AVDD}/2$		V
Input resistance	R_I		4		k Ω
Turn-on time	Noise-reducing capacitor = 1 μF from pin 28 to ground		20		ms
Turn-off time	Noise-reducing capacitor = 1 μF from pin 28 to ground		20		ms

ELECTRICAL CHARACTERISTICS: Power Supply

At $T_J = +25^\circ\text{C}$, $PA_V_S = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_ISET (pin 46), unless otherwise noted.

PARAMETER	CONDITIONS	AFE031			UNIT	
		MIN	TYP	MAX		
Operating Supply Range						
Power amplifier supply voltage	PA_V_S	+7		+24	V	
Digital supply voltage	DV_{DD}	+3.0		+3.6	V	
Analog supply voltage	AV_{DD}	+3.0		+3.6	V	
Quiescent Current SD pin low						
Power amplifier current	I_{QPA_VS}	$I_O = 0$, PA = On ⁽¹⁾		49	61	mA
		$I_O = 0$, PA = Off ⁽²⁾		10		μA
Digital supply current	I_{QDVDD}	Tx configuration ⁽³⁾		1.2		mA
		Rx configuration ⁽⁴⁾		5		μA
		All blocks disabled ⁽⁵⁾		5		μA
Analog supply current	I_{QAVDD}	Tx configuration ⁽³⁾		2.8	3.7	mA
		Rx configuration ⁽⁴⁾		3.6	5.3	mA
		All blocks disabled ⁽⁵⁾		30		μA
Shutdown (SD)						
Power amplifier supply voltage	PA_V_S	SD pin high		75	150	μA
Digital supply voltage	DV_{DD}	SD pin high		5	10	μA
Analog supply voltage	AV_{DD}	SD pin high		15	40	μA
Temperature						
Specified range			-40		+125	$^\circ\text{C}$

(1) Enable1 Register = 00100011, Enable2 Register = 00001110.

(2) Enable1 Register = 00000100, Enable2 Register = 00000110.

(3) In the Tx configuration, the following blocks are enabled: DAC, Tx, PA, REF1, and REF2. All other blocks are disabled. Enable1 Register = 00100011, Enable2 Register = 00001110.

(4) In the Rx configuration, the following blocks are enabled: Rx, REF1, and REF2. All other blocks are disabled. Enable1 Register = 00000100, Enable2 Register = 00000110.

(5) Enable1 Register = 00000000, Enable2 Register = 00000000.

THERMAL INFORMATION

THERMAL METRIC ⁽¹⁾		AFE031	UNITS
		RGZ (QFN)	
		48 PINS	
θ_{JA}	Junction-to-ambient thermal resistance	27.8	$^\circ\text{C}/\text{W}$
θ_{JCTop}	Junction-to-case (top) thermal resistance	12.1	
θ_{JB}	Junction-to-board thermal resistance	7.5	
Ψ_{JT}	Junction-to-top characterization parameter	0.4	
Ψ_{JB}	Junction-to-board characterization parameter	7.4	
θ_{JCbott}	Junction-to-case (bottom) thermal resistance	1.7	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

SPI TIMING REQUIREMENTS

PARAMETER	CONDITION	MIN	TYP	MAX	UNIT
Input capacitance			1		pF
Input rise/fall time	t_{RFI} \overline{CS} , DIN, SCLK			2	ns
Output rise/fall time	t_{RFO} DOUT			10	ns
\overline{CS} high time	t_{CSH} \overline{CS}	20			ns
SCLK edge to \overline{CS} fall setup time	t_{CS0}	10			ns
\overline{CS} fall to first SCLK edge setup time	t_{CSSC}	10			ns
SCLK frequency	f_{SCLK}			20	MHz
SCLK high time	t_{HI}	20			ns
SCLK low time	t_{LO}	20			ns
SCLK last edge to \overline{CS} rise setup time	t_{SCCS}	10			ns
\overline{CS} rise to SCLK edge setup time	t_{CS1}	10			ns
DIN setup time	t_{SU}	10			ns
DIN hold time	t_{HD}	5			ns
SCLK to DOUT valid propagation delay	t_{DO}			20	ns
\overline{CS} rise to DOUT forced to Hi-Z	t_{SOZ}			20	ns

TIMING DIAGRAMS

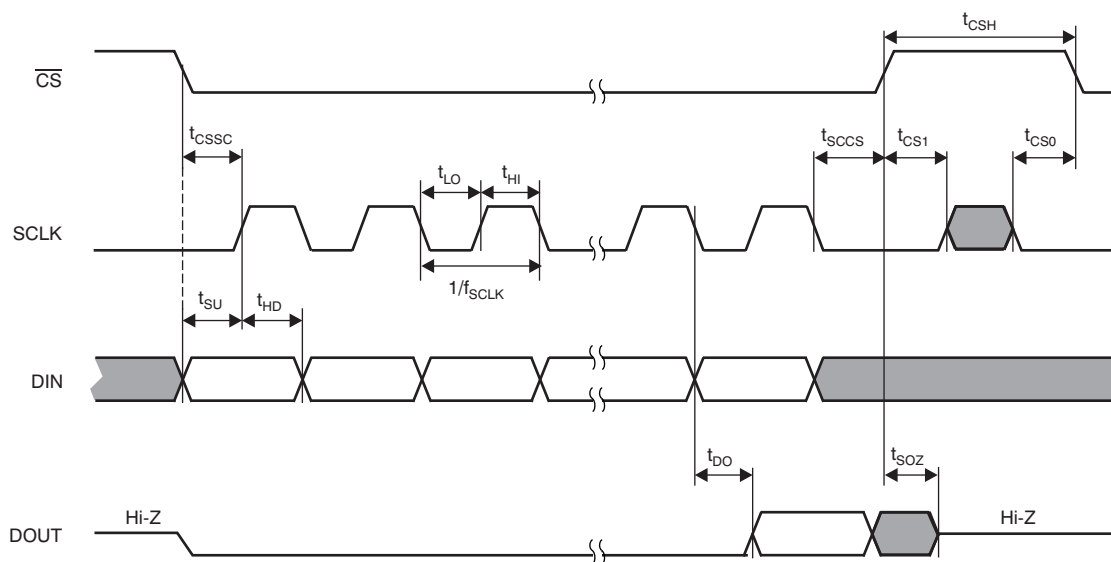


Figure 1. SPI Mode 0,0

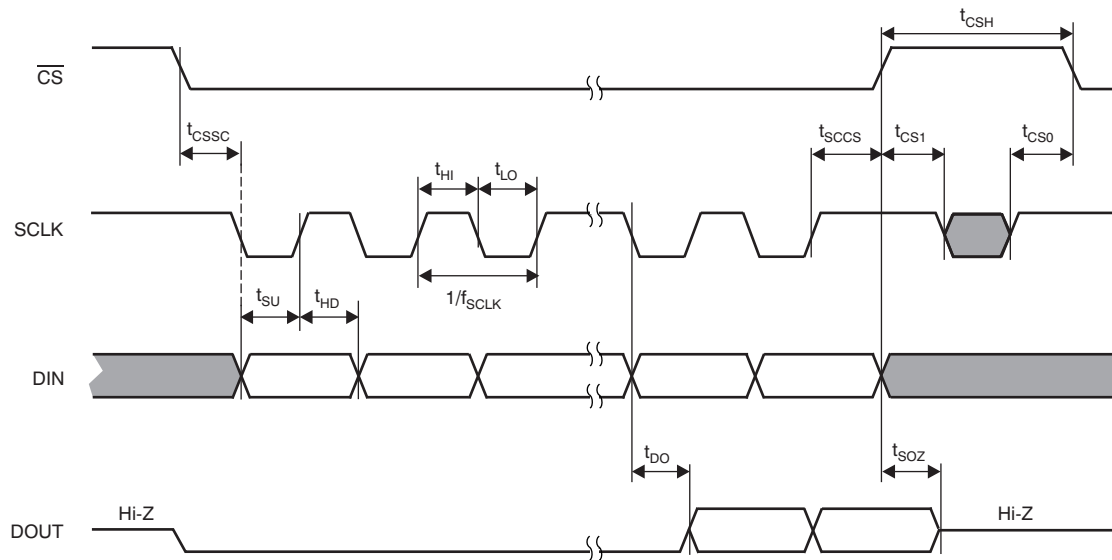
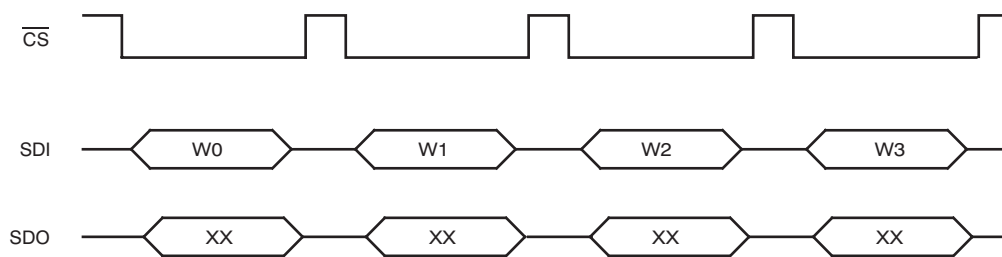
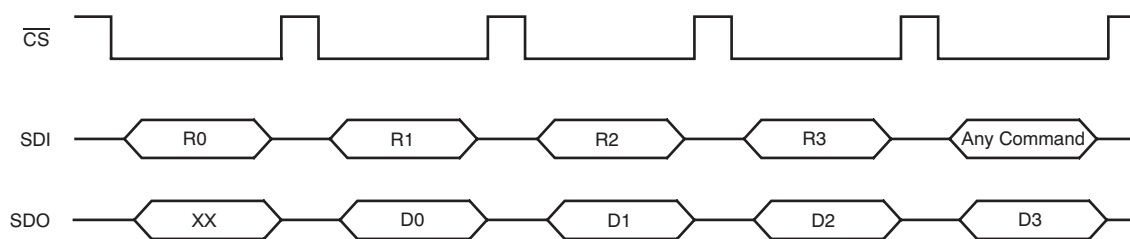


Figure 2. SPI Mode 1,1



W - Command of Write Register *N*
 XX - Don't care; undefined.

Figure 3. Write Operation in Stand-Alone Mode

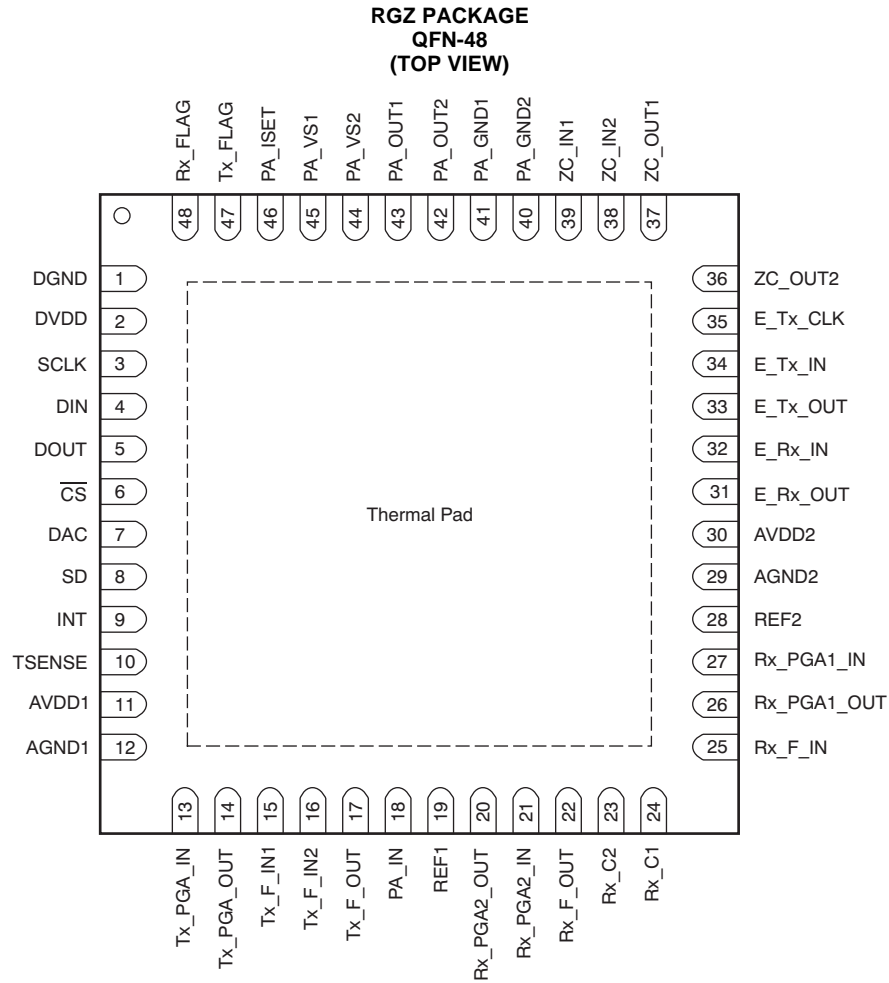


R - Command of Read Register *N* Read
 D - Data from Register *N*
 XX - Don't care; undefined.

Figure 4. Read Operation in Stand-Alone Mode

DEVICE INFORMATION

PIN ASSIGNMENTS

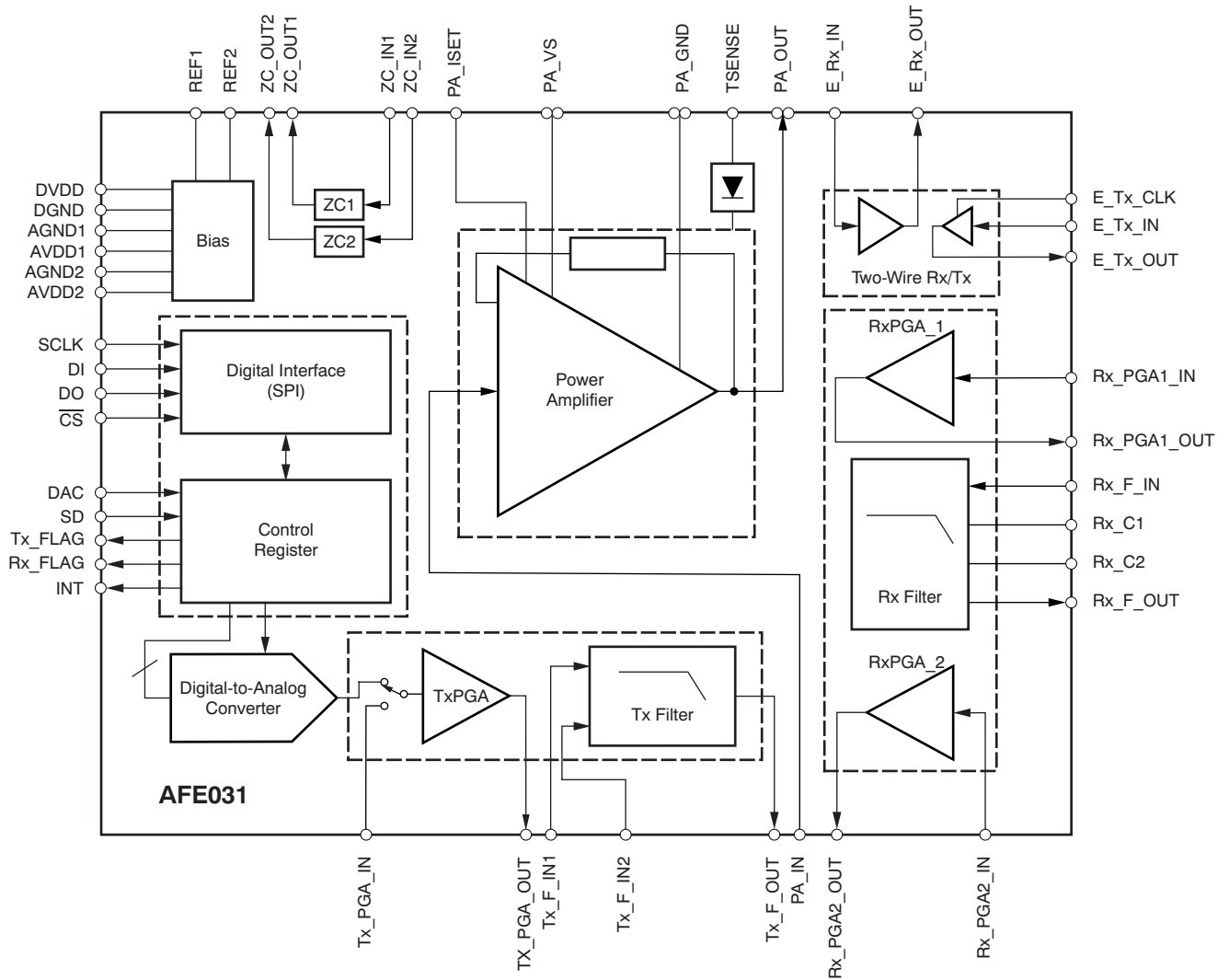


NOTE: Exposed thermal pad is connected to ground.

PIN DESCRIPTIONS

AFE031		DESCRIPTION
PIN NO.	NAME	
1	DGND	Digital ground
2	DVDD	Digital supply
3	SCLK	SPI serial clock
4	DIN	SPI digital input
5	DOUT	SPI digital output
6	\overline{CS}	SPI digital chip select
7	DAC	DAC mode select
8	SD	System shutdown
9	INT	Interrupt on overcurrent or thermal limit
10	TSENSE	Temp sensing diode (anode)
11	AVDD1	Analog supply
12	AGND1	Analog ground
13	Tx_PGA_IN	Transmit PGA Input
14	Tx_PGA_OUT	Transmit PGA output
15	Tx_F_IN1	Transmit filter input 1
16	Tx_F_IN2	Transmit filter input 2
17	Tx_F_OUT	Transmit filter output
18	PA_IN	Power Amplifier input
19	REF1	Power Amplifier noise reducing capacitor
20	Rx_PGA2_OUT	Receiver PGA(2) output
21	Rx_PGA2_IN	Receiver PGA(2) input
22	Rx_F_OUT	Receiver filter output
23	Rx_C2	Receiver external frequency select
24	Rx_C1	Receiver external frequency select
25	Rx_F_IN	Receiver filter input
26	Rx_PGA1_OUT	Receiver PGA(1) output
27	Rx_PGA1_IN	Receiver PGA(1) input
28	REF2	Receiver noise reducing capacitor
29	AGND2	Analog ground
30	AVDD2	Analog supply
31	E_Rx_OUT	Two-wire receiver output
32	E_Rx_IN	Two-wire receiver input
33	E_Tx_OUT	Two-wire transmitter output
34	E_Tx_IN	Two-wire transmitter input
35	E_Tx_CLK	Two-wire transmitter clock input
36	ZC_OUT2	Zero crossing detector output
37	ZC_OUT1	Zero crossing detector output
38	ZC_IN2	Zero crossing detector input
39	ZC_IN1	Zero crossing detector input
40	PA_GND2	Power Amplifier ground
41	PA_GND1	Power Amplifier ground
42	PA_OUT2	Power Amplifier output
43	PA_OUT1	Power Amplifier output
44	PA_VS2	Power Amplifier supply
45	PA_VS1	Power Amplifier supply
46	PA_ISET	Power Amplifier current limit set
47	Tx_FLAG	Transmitter ready flag
48	Rx_FLAG	Receiver ready flag

FUNCTIONAL BLOCK DIAGRAM



TYPICAL CHARACTERISTICS

At $T_J = +25^\circ\text{C}$, $PA_{VS} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

Tx Filter GAIN vs FREQUENCY

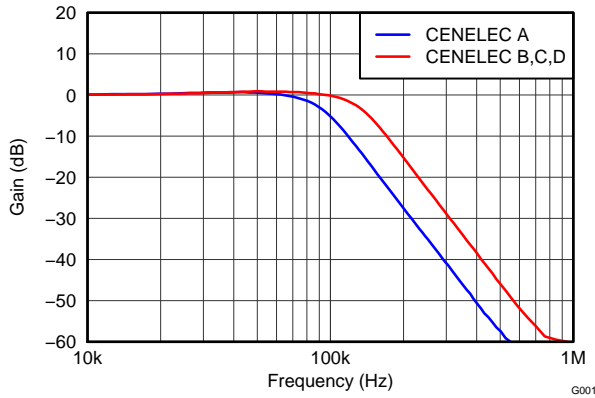


Figure 5.

Rx Filter GAIN vs FREQUENCY

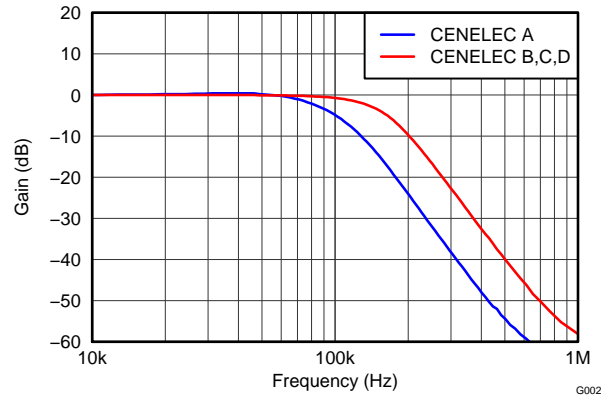


Figure 6.

PA GAIN vs FREQUENCY

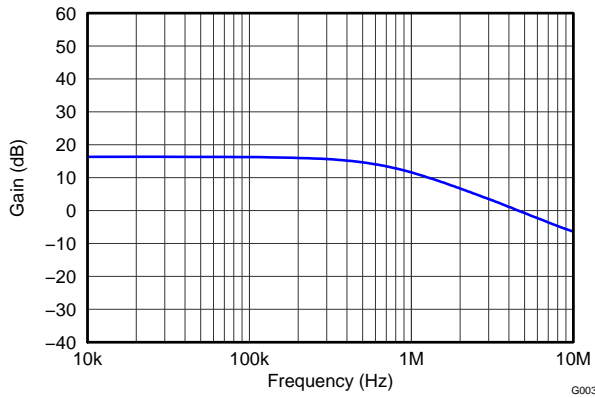


Figure 7.

MAXIMUM PA OUTPUT VOLTAGE vs FREQUENCY

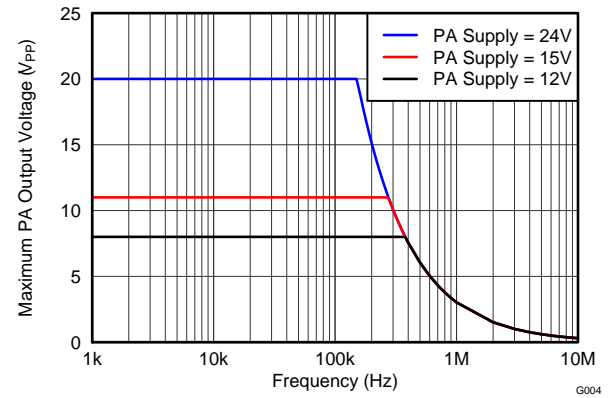


Figure 8.

Tx PGA GAIN vs FREQUENCY

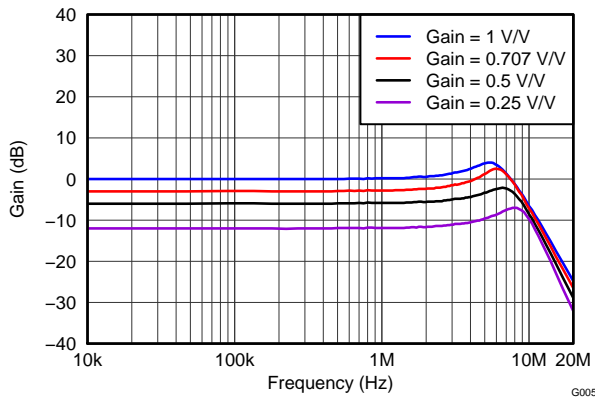


Figure 9.

Rx PGA1 GAIN vs FREQUENCY

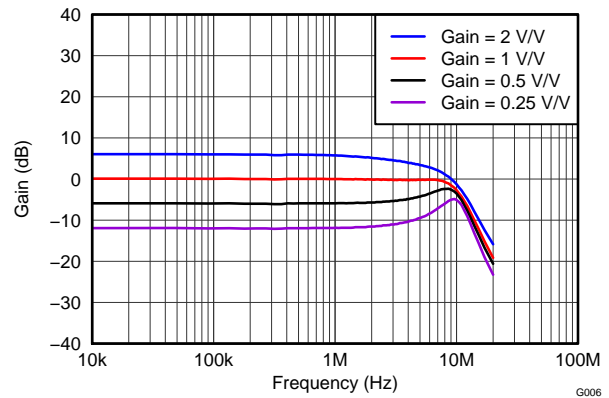


Figure 10.

TYPICAL CHARACTERISTICS (continued)

At $T_J = +25^\circ\text{C}$, $PA_V_S = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_ISET (pin 46), unless otherwise noted.

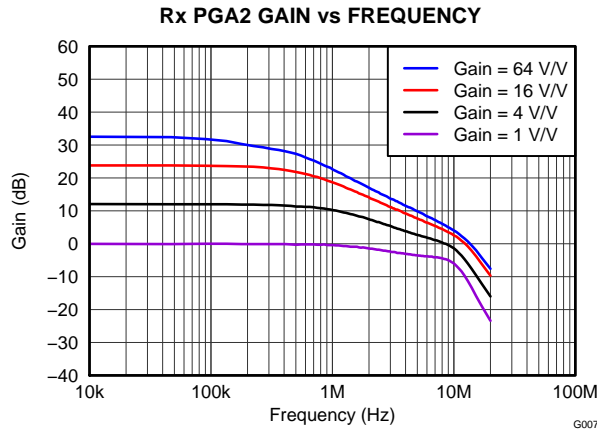


Figure 11.

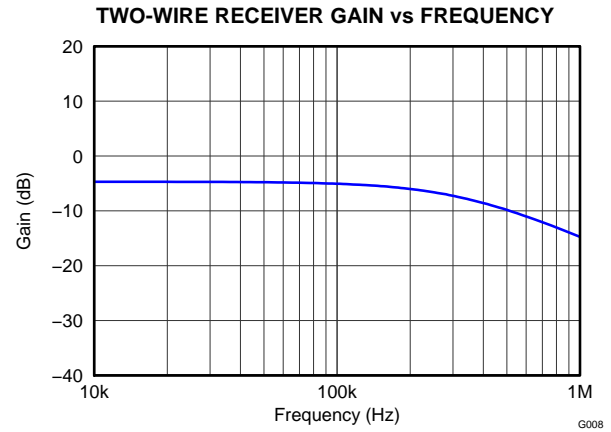


Figure 12.

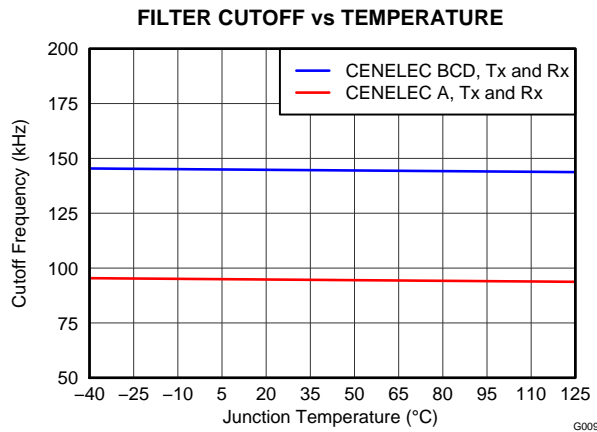


Figure 13.

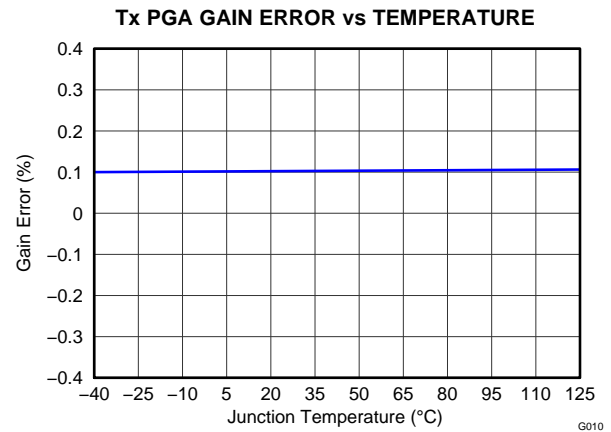


Figure 14.

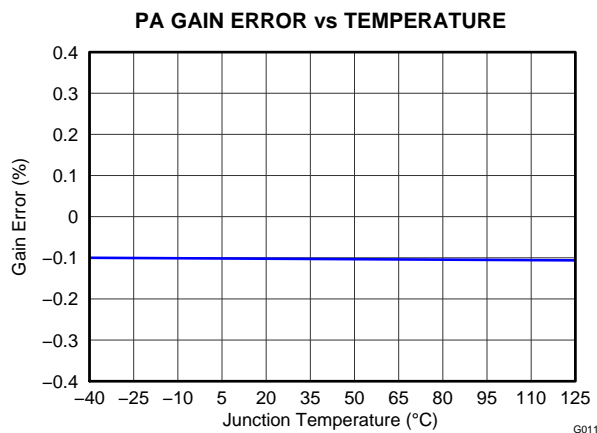


Figure 15.

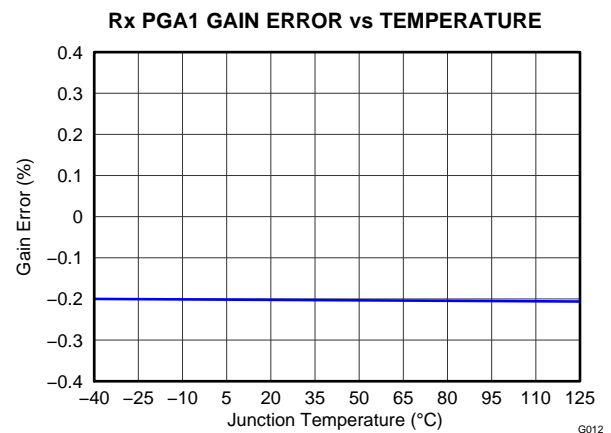


Figure 16.

TYPICAL CHARACTERISTICS (continued)

At $T_J = +25^\circ\text{C}$, $PA_V_S = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_ISET (pin 46), unless otherwise noted.

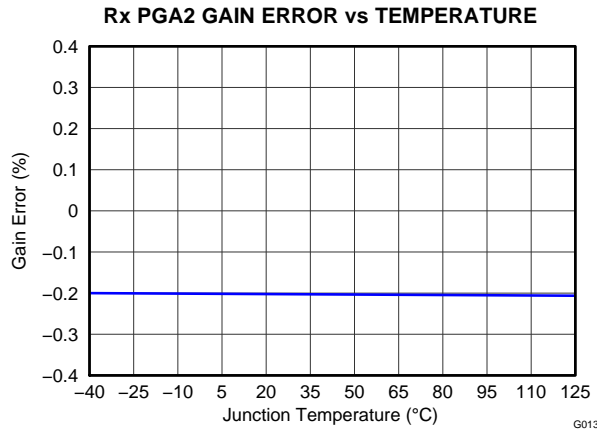


Figure 17.

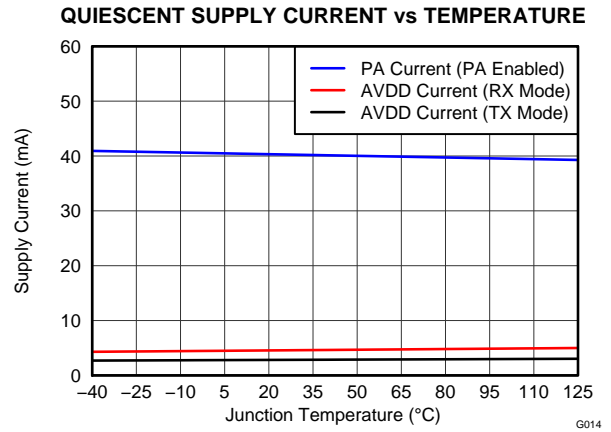


Figure 18.

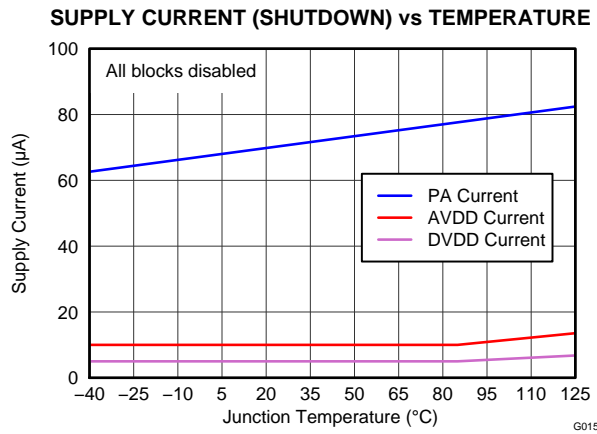


Figure 19.

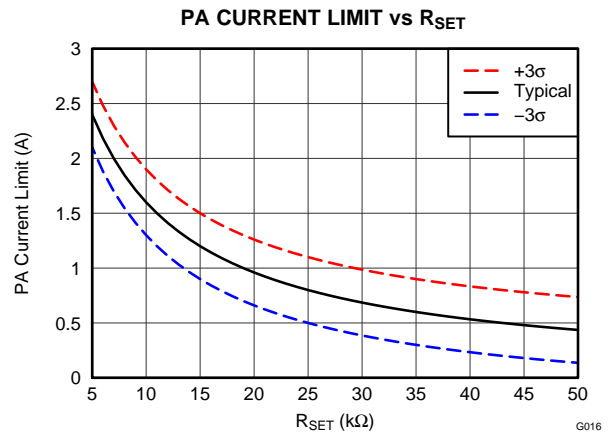


Figure 20.

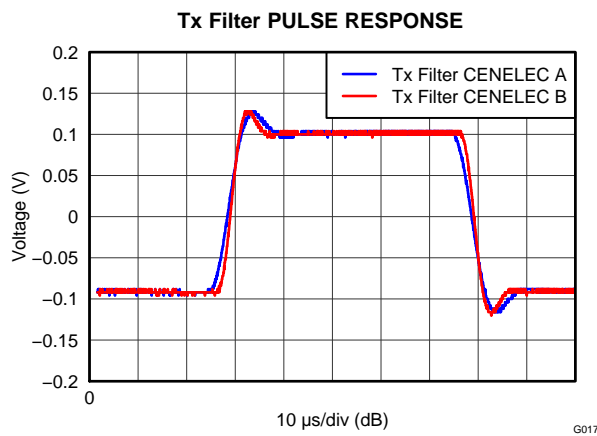


Figure 21.

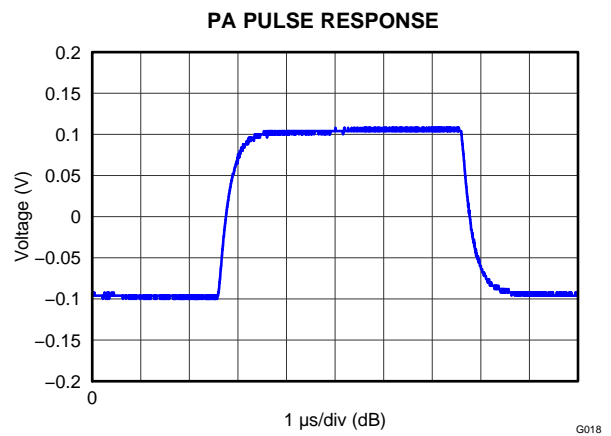


Figure 22.

TYPICAL CHARACTERISTICS (continued)

At $T_J = +25^\circ\text{C}$, $PA_{VS} = 16\text{ V}$, $V_{AVDD} = V_{DVDD} = 3.3\text{ V}$, and $10\text{ k}\Omega$ connected to PA_{ISET} (pin 46), unless otherwise noted.

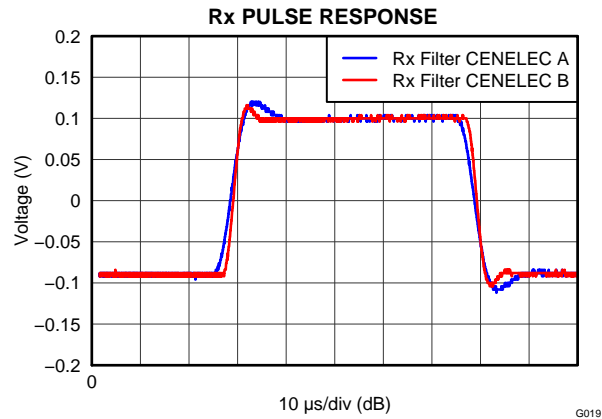


Figure 23.

APPLICATION INFORMATION

GENERAL DESCRIPTION

The AFE031 is an integrated powerline communication analog front-end (AFE) device built from a variety of functional blocks that work in conjunction with a microcontroller. The AFE031 provides the interface between the microcontroller and a line coupling circuit. The AFE031 delivers high performance and is designed to work with a minimum number of external components. Consisting of a variety of functional and configurable blocks, the AFE031 simplifies design efforts and reduces the time to market of many applications.

The AFE031 includes three primary functional blocks:

- Power Amplifier (PA)
- Transmitter (Tx)
- Receiver (Rx)

The AFE031 also consists of other support circuitry blocks that provide zero crossing detection, an additional two-wire communications channel, and power-saving biasing blocks (see the [Functional Block Diagram](#)). All of these functional blocks are digitally controlled by the microcontroller through the serial interface (SPI).

[Figure 24](#) shows a typical powerline communications application system diagram. [Table 1](#) is a complete list of the sections within the AFE031.

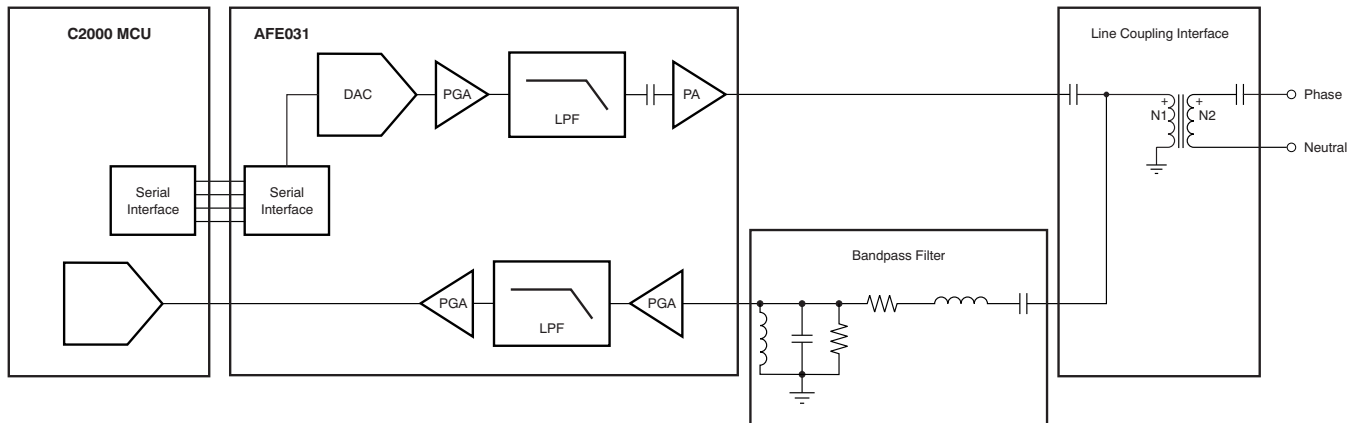


Figure 24. Typical Powerline Communications System Diagram

Table 1. Block Descriptions

BLOCK	DESCRIPTION
PA	The PA block includes the power amplifier and associated pedestal biasing circuitry
Tx	The Tx block includes the Tx_Filter and the Tx_PGA
Rx	The Rx block includes the Rx PGA1, the Rx Filter, and the Rx PGA2
ERx	The ER block includes the two-wire receiver
ETx	The ETx block includes the two-wire transmitter
DAC	The DAC block includes a digital-to-analog converter
ZC	The ZC block includes both zero crossing detectors
REF1	The REF1 block includes the internal bias generator for the PA block
REF2	The REF2 block includes the internal bias generators for the Tx, Rx, ERx, and ETx blocks

BLOCK DESCRIPTIONS

PA Block

The Power Amplifier (PA) block consists of a high slew rate, high-voltage, and high-current operational amplifier. The PA is configured with an inverting gain of 6.5 V/V, has a low-pass filter response, and maintains excellent linearity and low distortion. The PA is specified to operate from 7 V to 24 V and can deliver up to ± 1.5 A of continuous output current over the specified junction temperature range of -40°C to $+125^{\circ}\text{C}$. Figure 25 illustrates the PA block.

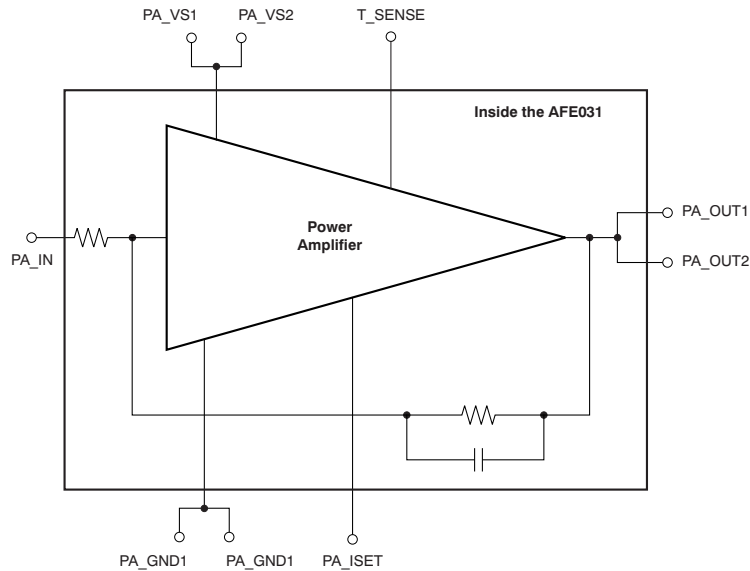


Figure 25. PA Block Equivalent Circuit

Connecting the PA in a typical PLC application requires only two additional components: an ac coupling capacitor, C_{IN} , and the current limit programming resistor, R_{SET} . Figure 26 shows the typical connections to the PA block.

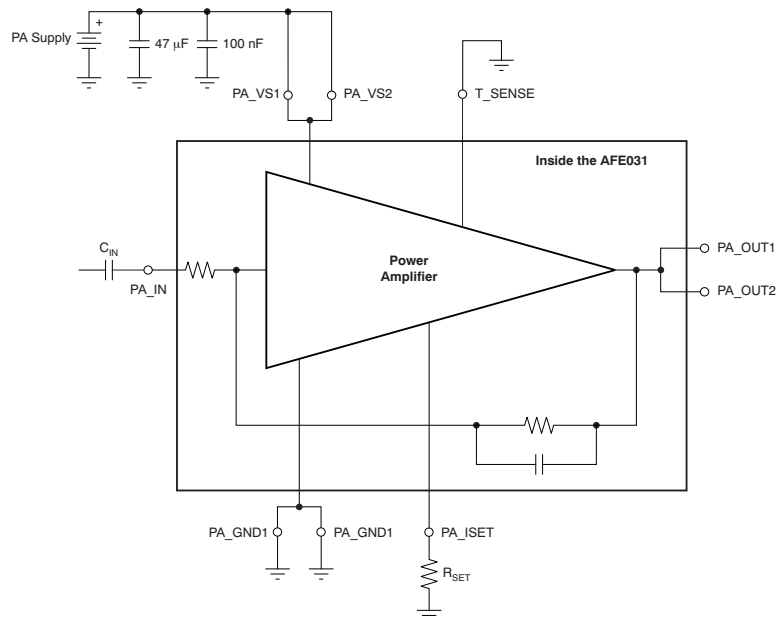


Figure 26. Typical Connections to the PA

The external capacitor, C_{IN} , introduces a single-pole, high-pass characteristic to the PA transfer function; combined with the inherent low-pass transfer function, this characteristic results in a passband response. The value of the high-pass cutoff frequency is determined by C_{IN} reacting with the input resistance of the PA circuit, and can be found from [Equation 1](#):

$$C_{IN} = \frac{1}{(2 \cdot \pi \cdot 20 \text{ k}\Omega \cdot f_{HP})} \quad (1)$$

Where:

- C_{IN} = external input capacitor
- f_{HP} = desired high-pass cutoff frequency

For example, setting C_{IN} to 3.3 nF results in a high-pass cutoff frequency of 2.4 kHz. The voltage rating for C_{IN} should be determined to withstand operation up to the PA power-supply voltage.

When the transmitter is not in use, the output can be disabled and placed into a high-impedance state by writing a '0' to the PA-OUT bit in the [Enable2 Register](#). Additional power savings can be realized by shutting down the PA when not in use. Shutting down the PA for power savings is accomplished by writing a '0' to the PA bit in the [Enable1 Register](#). Shutting down the PA also results in the PA output entering a high-impedance state. When the PA shuts down, it consumes only 2 mW of power.

The PA_ISET pin (pin 46) provides a resistor-programmable output current limit for the PA block. [Equation 2](#) determines the value of the external R_{SET} resistor attached to this pin.

$$R_{SET} = \left(20 \text{ k}\Omega \cdot \frac{1.2 \text{ V}}{I_{LIM}} \right) - 5 \text{ k}\Omega \quad (2)$$

Where:

- R_{SET} = the value of the external resistor connected between pin 46 and ground.
- I_{LIM} = the value of the desired current limit for the PA.

Note that to ensure proper design margin with respect to manufacturing and temperature variations, a 30% decrease of the value used in [Equation 2](#) for I_{LIM} over the nominal value of I_{LIM} is recommended. See [Figure 20](#), *PA Current Limit vs R_{SET}* .

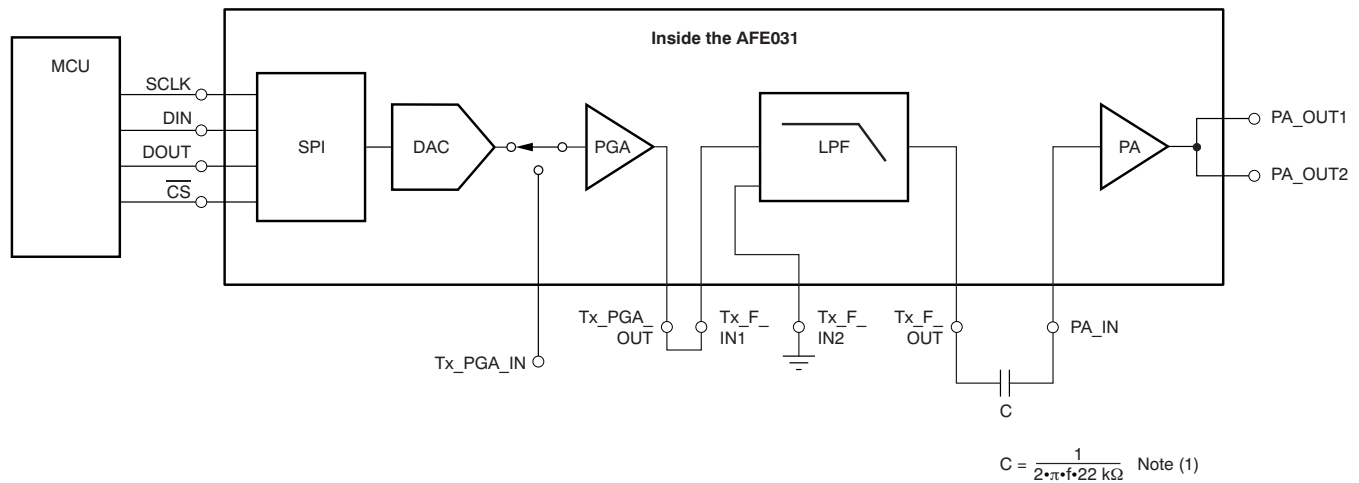
Tx Block

The Tx block consists of the Tx PGA and Tx Filter. The Tx PGA is a low-noise, high-performance, programmable gain amplifier. In DAC mode (where pin 7 is a logical '1' and [Enable1 Register](#) bit location 5 is a logical '1'), the Tx PGA operates as the internal digital-to-analog converter (DAC) output buffer with programmable gain. In PWM mode (where pin 7 is a logical '0' and [Enable1 Register](#) bit location 5 is a logical '0'), the Tx PGA operates as a stand-alone programmable gain amplifier. The Tx PGA gain is programmed through the serial interface. The Tx PGA gain settings are 0.25 V/V, 0.5 V/V, 0.707 V/V, and 1 V/V.

The Tx Filter is a unity-gain, fourth-order low-pass filter. The Tx Filter cutoff frequency is selectable between CENELEC A or CENELEC B, C, and D modes. The [Control1 Register](#) bit location 3 setting (CA CBCD) determines the cutoff frequency. Setting Control1 Register bit location 3 to '0' selects the CENELEC A band; setting Control1 Register bit location 3 to '1' selects CENELEC B, C, and D bands.

The AFE031 supports both DAC inputs or PWM inputs for the Tx signal path. DAC mode is recommended for best performance. In DAC mode, no external components in the Tx signal path are required to meet regulatory signal emissions requirements. When in DAC mode, the AFE031 accepts serial data from the microprocessor and writes that data to the internal DAC registers. When in DAC mode (where pin 7 is a logical '1' and [Enable1 Register](#) bit location 5 is a logical '1'), the Tx PGA output must be directly coupled to the Tx_FIN1 input and the unused Tx_FIN2 input must be grounded.

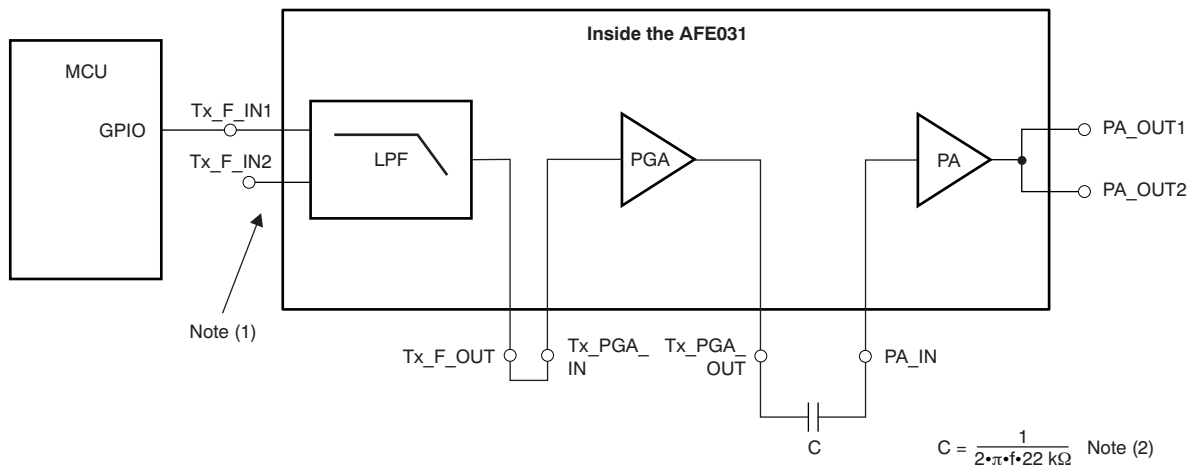
The proper connections for the Tx signal path for DAC mode operation are shown in [Figure 27](#). Operating in DAC mode results in the lowest distortion signal injected onto the ac mains. No additional external filtering components are required to meet CENELEC requirements for A, B, C or D bands when operating in DAC mode.



- (1) For capacitor value C, f is the desired lower cutoff frequency and 22 kΩ is the PA input resistance.

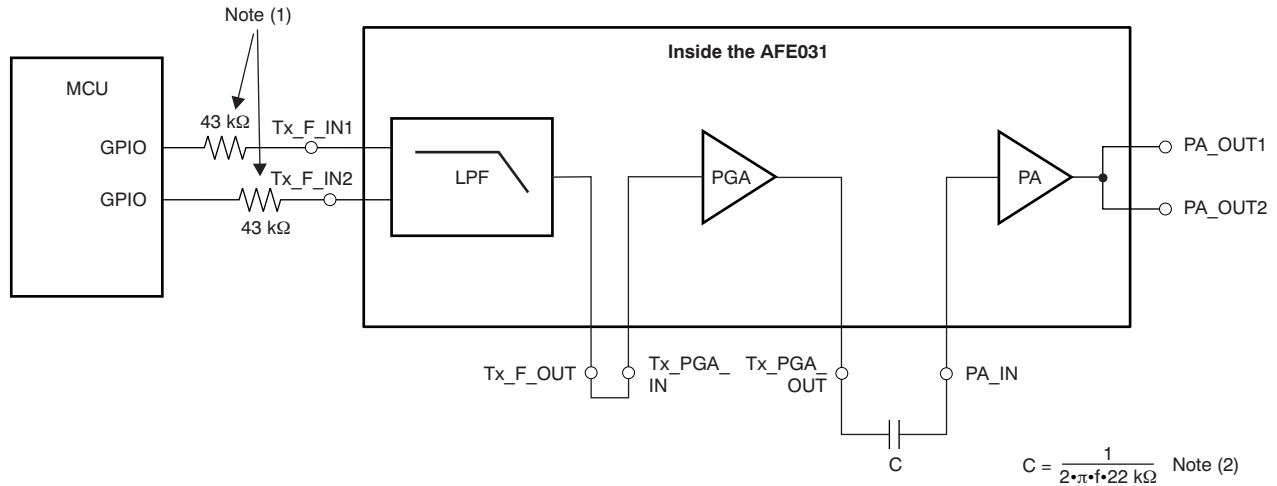
Figure 27. Recommended Tx Signal Chain Connections Using DAC Mode

In PWM mode (where pin 7 is a logical '0' and [Enable1 Register](#) bit location 5 is a logical '0'), the microprocessor general-purpose input/output (GPIO) can be connected directly to either one of the Tx Filter inputs; the unused input should remain unconnected. A lower distortion PWM signal generated from two PWM signals shifted in phase by 90 degrees can be also be input to the Tx Filter through the use of both inputs. [Figure 28](#) and [Figure 29](#) show the proper connections for single PWM and dual PWM operating modes, respectively.



- (1) Leave unused Tx Filter input unconnected.
 (2) For capacitor value C, f is the desired lower cutoff frequency and 22 kΩ is the PA input resistance.

Figure 28. Recommended Tx Signal Chain Connections in PWM Mode Using One PWM Signal

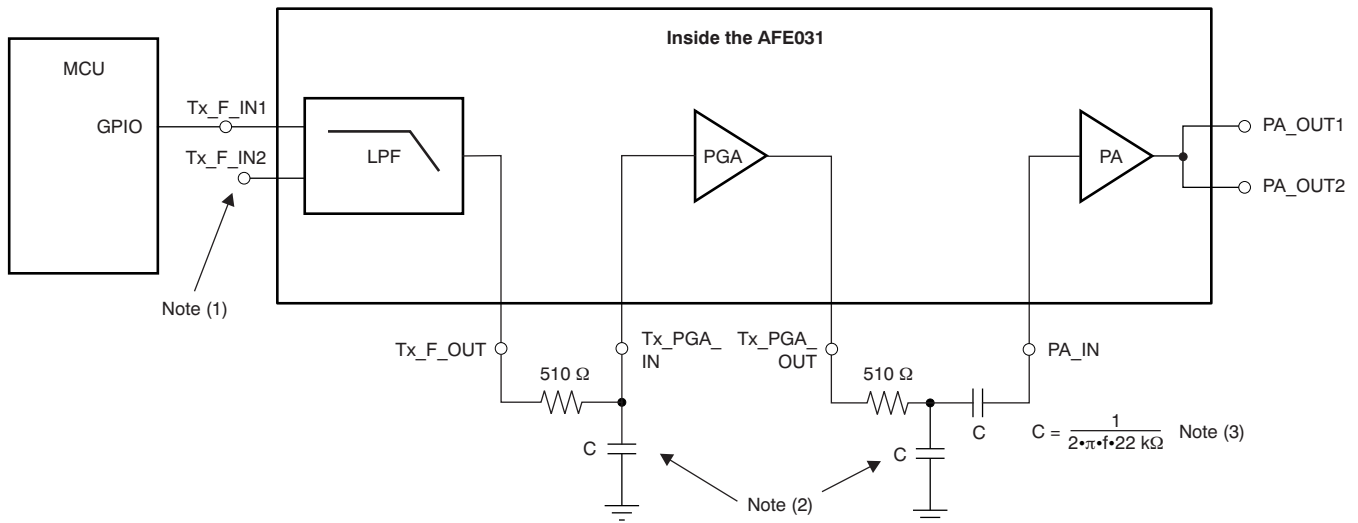


- (1) When using both Tx Filter inputs, use 43-kΩ resistors to match the input resistance for best frequency response.
- (2) For capacitor value C , f is the desired lower cutoff frequency and 22 kΩ is the PA input resistance.

$$C = \frac{1}{2 \cdot \pi \cdot f \cdot 22 \text{ k}\Omega} \text{ Note (2)}$$

Figure 29. Recommended Tx Signal Chain Connections in PWM Mode Using Two PWM Signals

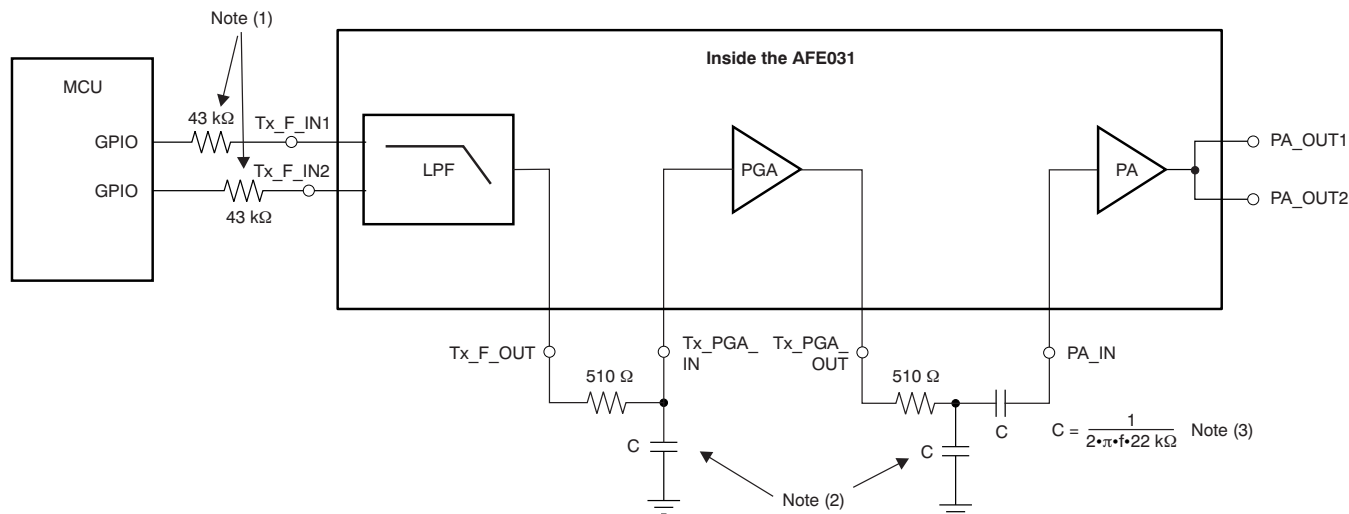
In PWM mode, there is inherently more distortion from the PWM signal than from the internal DAC. To achieve the best results in PWM mode, add passive RC filters to increase the low-pass filtering. Figure 30 and Figure 31 illustrate the recommended locations of these RC filters.



- (1) Leave unused Tx Filter input unconnected.
- (2) Refer to Table 2.
- (3) For capacitor value C , f is the desired lower cutoff frequency and 22 kΩ is the PA input resistance.

$$C = \frac{1}{2 \cdot \pi \cdot f \cdot 22 \text{ k}\Omega} \text{ Note (3)}$$

Figure 30. Recommended Tx Signal Chain Connections in PWM Mode Using One PWM Signal and Additional RC Filters



- (1) When using both Tx Filter inputs, use 43-kΩ resistors to match the input resistance for best frequency response.
- (2) Refer to [Table 2](#).
- (3) For capacitor value C, *f* is the desired lower cutoff frequency and 22 kΩ is the PA input resistance.

Figure 31. Recommended Tx Signal Chain Connections in PWM Mode Using Two PWM Signals and Additional RC Filters

For the capacitors listed in [Table 2](#), it is recommended that these components be rated to withstand the full AV_{DD} power-supply voltage.

Table 2. Recommended External R and C Values to Increase Tx Filter Response Order in PWM Applications

FREQUENCY BAND	R (Ω)	C (nF)
SFSK: 63 kHz, 74 kHz	510	2.7
CENELEC A	510	1.5
CENELEC B, C, D	510	1

The Tx PGA and Tx Filter each have the inputs and outputs externally available in order to provide maximum system design flexibility. Care should be taken when laying out the PCB traces from the inputs or outputs to avoid excessive capacitive loading. Keeping the PCB capacitance from the inputs to ground, or from the outputs to ground, less than 100 pF is recommended.

Rx Block

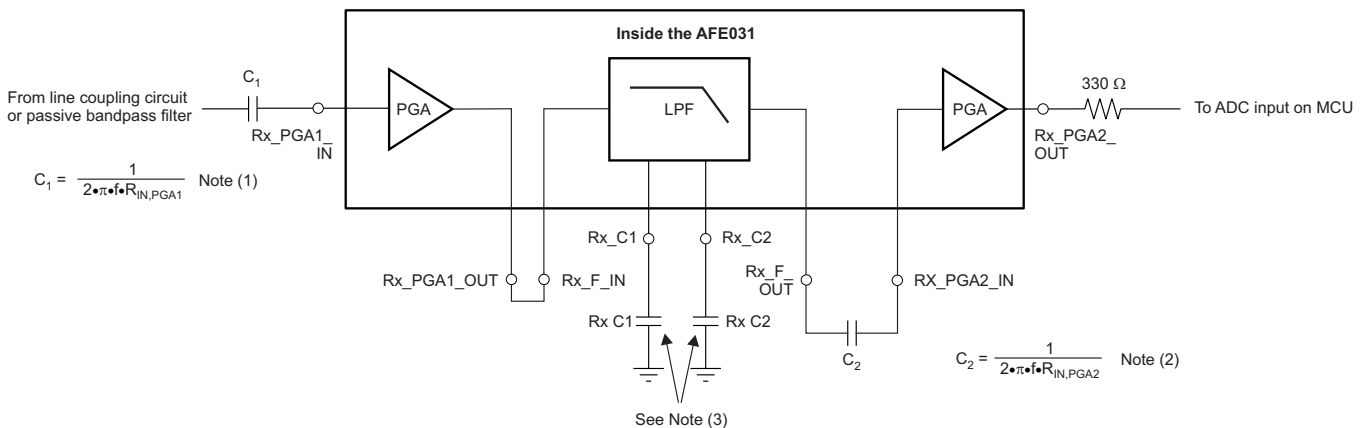
The Rx block consists of Rx PGA1, the Rx Filter, and Rx PGA2. Both Rx PGA1 and Rx PGA2 are high-performance programmable gain amplifiers. Rx PGA1 can be configured through the SPI to operate as either an attenuator or in gain. The gain steps of the Rx PGA1 are 0.25 V/V, 0.5 V/V, 1 V/V, and 2 V/V. The gain steps of the Rx PGA2 are 1 V/V, 4 V/V, 16 V/V, and 64 V/V. Configuring the Rx PGA1 as an attenuator (at gains less than 1 V/V) is useful for applications where the presence of large interference signals are present within the signal band. Attenuating the large interference allows these signals to pass through the analog Rx signal chain without causing an overload; the interference signal can then be processed and removed within the microprocessor as necessary.

The Rx Filter is a very low noise, unity-gain, fourth-order low-pass filter. The Rx Filter cutoff frequency is selectable between CENELEC A or CENELEC B, C, and D modes. The [Control1 Register](#) bit location 3 setting (CA CBCD) determines the cutoff frequency. Setting [Control1 Register](#) bit location 3 to '0' selects the CENELEC A band; setting [Control1 Register](#) bit location 3 to '1' selects the CENELEC B, C, and D bands. Because the Rx Filter is a very low noise analog filter, two external capacitors are required to properly configure the Rx Filter. [Table 3](#) shows the proper capacitance values for CENELEC A, B, C, and D bands. Capacitor Rx C1 is connected between pin 24 and ground, and Rx C2 is connected between pin 23 and ground. For the capacitors shown, it is recommended that these components be rated to withstand the full AV_{DD} power-supply voltage

Table 3. Recommended External Capacitors Required for Rx Filter

FREQUENCY BAND	Rx C1, PIN 24	Rx C2, PIN 23	CUTOFF FREQUENCY (kHz)
CENELEC A	680 pF	680 pF	90
CENELEC B, C, D	270 pF	560 pF	145

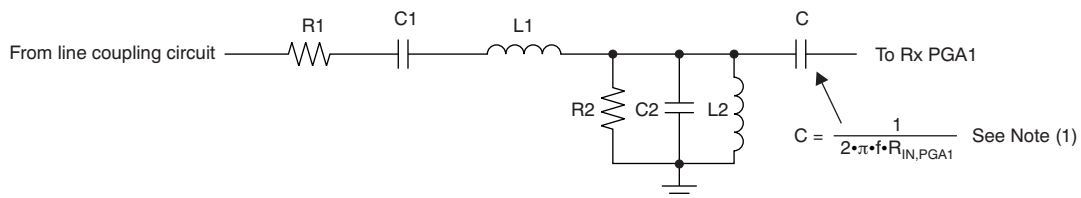
[Figure 32](#) illustrates the recommended connections for the Rx signal chain.



- (1) For capacitor value C_1 , f is the desired lower cutoff frequency and $R_{IN,PGA1}$ is the input resistance of Rx PGA1.
- (2) For capacitor value C_2 , f is the desired lower cutoff frequency and $R_{IN,PGA2}$ is the input resistance of Rx PGA2.
- (3) Refer to [Table 3](#).

Figure 32. Recommended Connections for Rx Signal Chain

As [Figure 33](#) shows, a fourth-order passive passband filter is optional but recommended for applications where high performance is required. The external passive passband filter removes any unwanted, out-of-band signals from the signal path, and prevents them from reaching the active internal filters within the AFE031.



- (1) For capacitor value C , f is the desired lower cutoff frequency and $R_{IN,PGA1}$ is the input resistance of Rx PGA1. Refer to [Table 3](#).

Figure 33. Passive Bandpass Rx Filter

The following steps can be used to quickly design the passive passband filter. (Note that these steps produce an approximate result.)

1. Choose the filter characteristic impedance, Z_C :
 - For –6-dB passband attenuation: $R_1 = R_2 = Z_C$
 - For 0-dB passband attenuation: $R_1 = Z_C$, $R_2 = 10 \bullet Z_C$
2. Calculate values for C_1 , C_2 , L_1 , and L_2 using the following equations:

$$C_1 = \frac{1}{(2 \bullet \pi \bullet f_1 \bullet Z_C)}$$

$$C_2 = \frac{1}{(2 \bullet \pi \bullet f_2 \bullet Z_C)}$$

$$L_1 = \frac{Z_C}{(2 \bullet \pi \bullet f_2)}$$

$$L_2 = \frac{Z_C}{(2 \bullet \pi \bullet f_1)}$$

Table 4 and Table 5 shows standard values for common applications.

Table 4. Recommended Component Values for Fourth-Order Passive Bandpass Filter (0-dB Passband Attenuation)

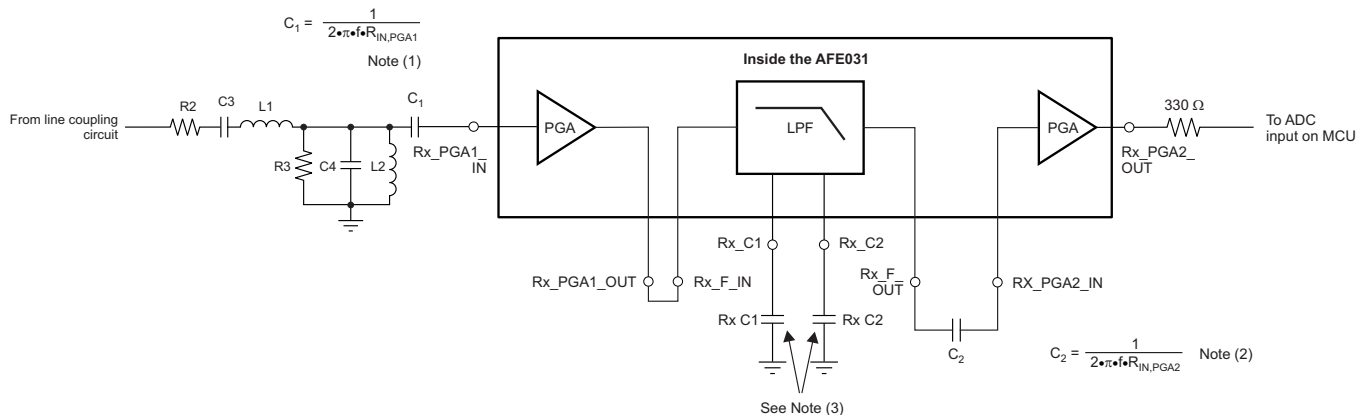
FREQUENCY BAND	FREQUENCY RANGE (kHz)	CHARACTERISTIC IMPEDANCE (Ω)	R1 (Ω)	R2 (Ω)	C1 (nF)	C2 (nF)	L1 (μ H)	L2 (μ H)
CENELEC A	35 to 95	1k	1k	10k	4.7	1.5	1500	4700
CENELEC B, C, D	95 to 150	1k	1k	10k	1.7	1	1200	1500
SFSK	63 to 74	1k	1k	10k	2.7	2.2	2200	2200

Table 5. Recommended Component Values for Fourth-Order Passive Bandpass Filter (–6-dB Passband Attenuation)

FREQUENCY BAND	FREQUENCY RANGE (kHz)	CHARACTERISTIC IMPEDANCE (Ω)	R1 (Ω)	R2 (Ω)	C1 (nF)	C2 (nF)	L1 (μ H)	L2 (μ H)
CENELEC A	35 to 95	1k	1k	1k	4.7	1.5	1500	4700
CENELEC B, C, D	95 to 150	1k	1k	1k	1.7	1	1200	1500
SFSK	63 to 74	1k	1k	1k	2.7	2.2	2200	2200

The Rx PGA1, Rx Filter, and Rx PGA2 components have all inputs and outputs externally available to provide maximum system design flexibility. Care should be taken when laying out the PCB traces from the inputs or outputs to avoid excessive capacitive loading. Keeping the PCB capacitance from the inputs to ground, or outputs to ground, below 100 pF is recommended.

Figure 34 shows the complete Rx signal path, including the optional passive passband filter.



- (1) For capacitor value C_1 , f is the desired lower cutoff frequency and $R_{IN,PGA1}$ is the input resistance of Rx PGA1.
- (2) For capacitor value C_2 , f is the desired lower cutoff frequency and $R_{IN,PGA2}$ is the input resistance of Rx PGA2.
- (3) Refer to [Table 3](#).

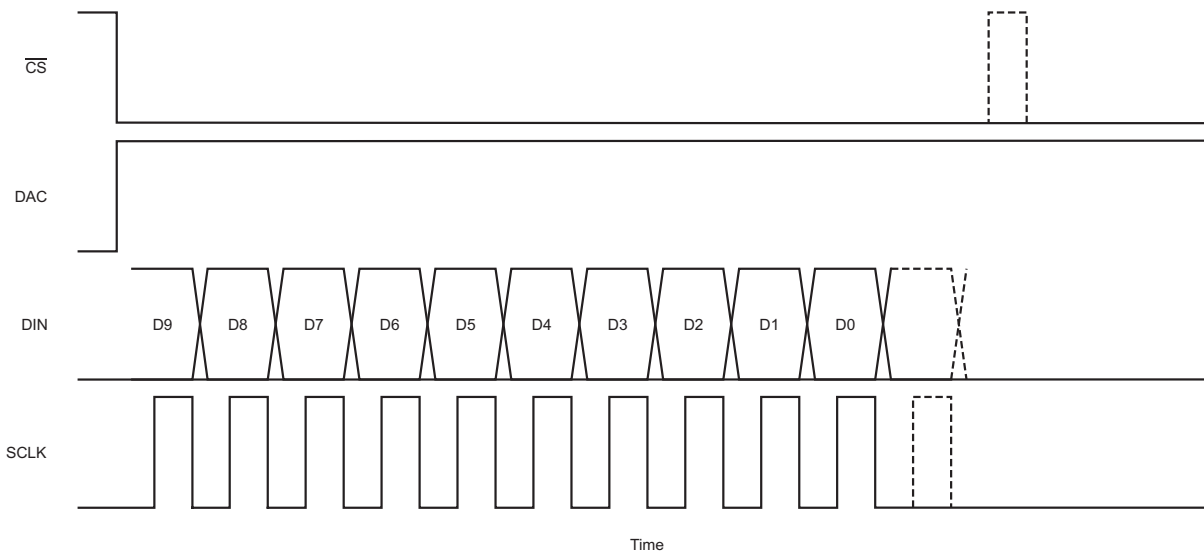
Figure 34. Complete Rx Signal Path (with Optional Bandpass Filter)

DAC Block

The DAC block consists only of the 10-bit DAC. The use of the DAC is recommended for best performance. The serial interface is used to write directly to the DAC registers when the DAC pin (pin 7) is driven high. Placing the DAC pin into a high state configures the SPI for direct serial interface to the DAC. Use the following sequence to write to the DAC:

- Set \overline{CS} low.
- Set the DAC pin (pin 7) high.
- Write a 10-bit word to DIN. The DAC register is left-justified and truncates more than 10 bits.
- \overline{CS} high updates the DAC.

Refer to [Figure 35](#) for an illustration of this sequence.



NOTE: Dashed lines indicate optional additional clocks (data are ignored).

Figure 35. Writing to the DAC Register

Table 6 lists the DAC Register configurations.

Table 6. DAC Registers

DAC PIN HIGH: DAC REGISTER <15:0>	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
DAC<0>	0	--	W	Truncated
DAC<1>	1	--	W	Truncated
DAC<2>	2	--	W	Truncated
DAC<3>	3	--	W	Truncated
DAC<4>	4	--	W	Truncated
DAC<5>	5	--	W	Truncated
DAC<6>	6	--	W	DAC bit 0 = DAC LSB
DAC<7>	7	--	W	DAC bit 1
DAC<8>	8	--	W	DAC bit 2
DAC<9>	9	--	W	DAC bit 3
DAC<10>	10	--	W	DAC bit 4
DAC<11>	11	--	W	DAC bit 5
DAC<12>	12	--	W	DAC bit 6
DAC<13>	13	--	W	DAC bit 7
DAC<14>	14	--	W	DAC bit 8
DAC<15>	15	--	W	DAC bit 9 = DAC MSB

REF1 and REF2 Blocks

The REF1 and REF2 blocks create midscale power-supply biasing points used internally to the AFE031. Each reference divides its respective power-supply voltage in half with a precision resistive voltage divider. REF1 provides a $PA_V_S/2$ voltage used for the PA, while REF2 provides an $AV_{DD}/2$ voltage used for the Tx PGA, Tx Filter, Rx PGA1, Rx Filter, and Rx PGA2. Each REF block has its output brought out to an external pin that can be used for filtering and noise reduction. Figure 36 and Figure 37 show the proper connections of the external noise-reducing capacitors. These capacitors are optional, but are recommended for best performance.

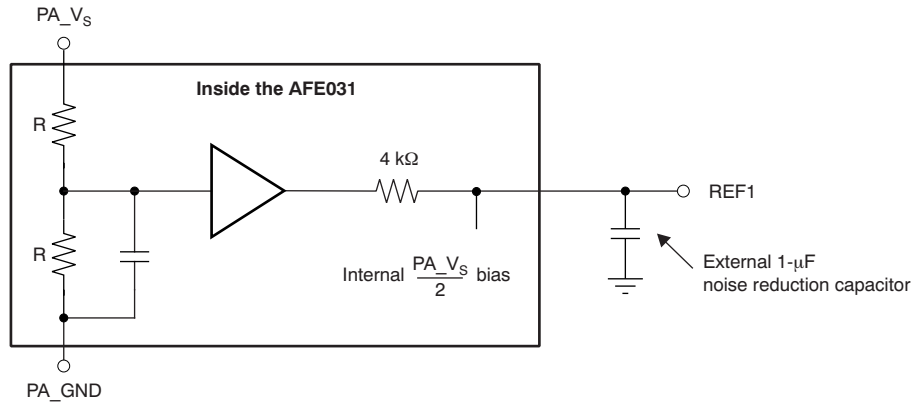


Figure 36. REF1 Functional Diagram

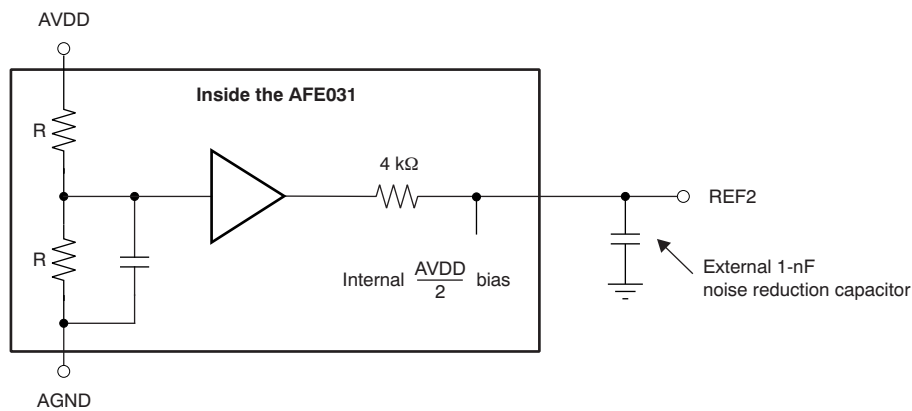


Figure 37. REF2 Functional Diagram

Zero Crossing Detector Block

The AFE031 includes two zero crossing detectors. Zero crossing detectors can be used to synchronize communications signals to the ac line or sources of noise. Typically, in single-phase applications, only a single zero crossing detector is used. In three-phase applications, both zero crossing detectors can be used; one component detects phase A, and one detects phase B. Phase C zero crossings can then be inferred from the data gathered from the other phases. [Figure 38](#) shows the AFE031 configured for non-isolated zero crossing detection.

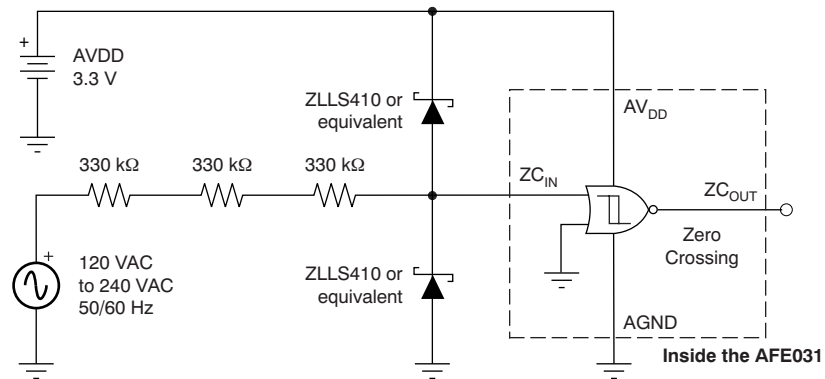


Figure 38. Non-Isolated Zero Crossing Detection Using the AFE031

Non-isolated zero crossing waveforms are shown in [Figure 39](#).

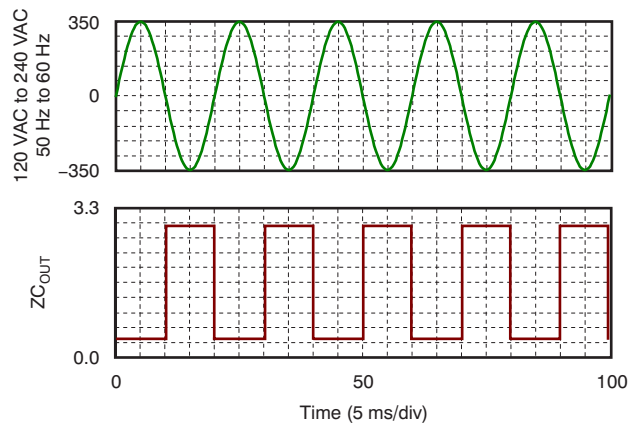


Figure 39. Non-Isolated Zero Crossing Waveforms

For maximum protection of the AFE031 against line transients, it is recommended to use Schottky diodes as indicated in [Figure 38](#). These diodes should limit the ZC_IN pins (pins 38 and 39) to within the maximum rating of $(AV_{DD} + 0.4\text{ V})$ and $(AGND - 0.4\text{ V})$. Some applications may require an isolated zero crossing detection circuit. With a minimal amount of components, the AFE031 can be configured for isolated zero crossing detection, as [Figure 40](#) shows.

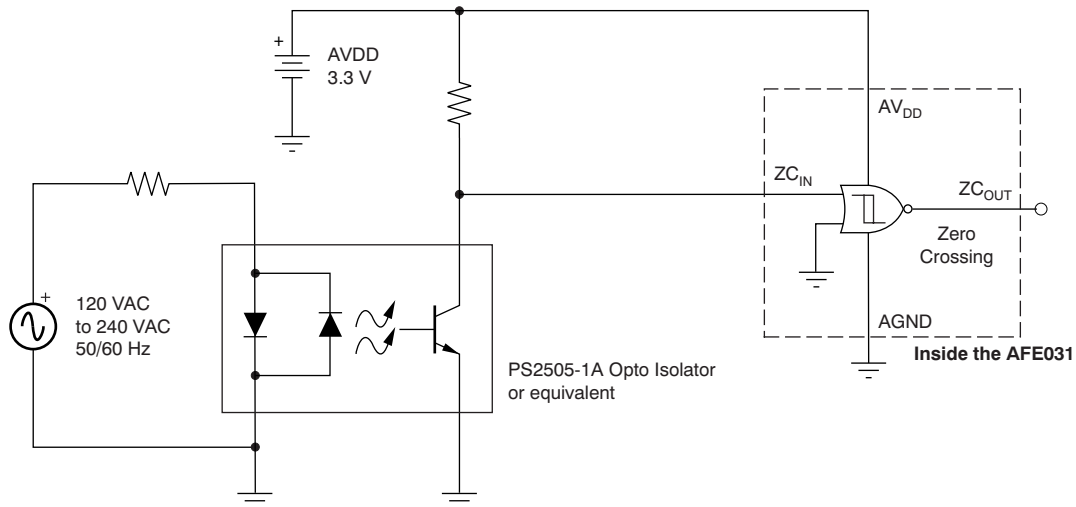


Figure 40. Isolated Zero Crossing Detection Using the AFE031

Isolated zero crossing waveforms are shown in [Figure 41](#).

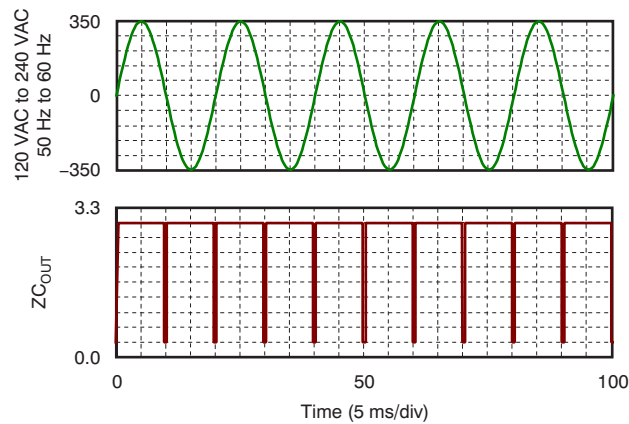


Figure 41. Isolated Zero Crossing Waveforms

ETx and ERx Blocks

The AFE031 contains a two-wire transmitter block, ETx, and a two-wire receiver block, ERx. These blocks support communications that use amplitude shift keying (ASK) with on-off keying (OOK) modulation.

The ETx block is a gated driver that allows for transmission of a carrier input signal and modulating input signal. For typical applications, a 50-kHz square wave carrier signal is applied to E_Tx_Clk while the modulating signal is applied to E_Tx_In. The output (E_Tx_Out) is then in a high-impedance state when E_Tx_In is '1'. Figure 42 shows the relationship between E_Tx_Clk, E_Tx_In, and E_Tx_Out.

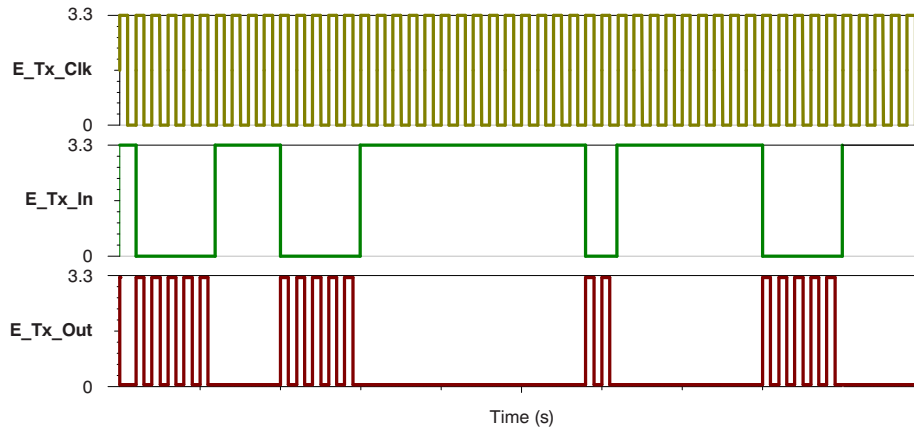


Figure 42. ETx Block Transfer Function

The ERx Block consists of a low-pass analog filter configured in an inverting gain of -4.5 db. This block, along with an external capacitor, can be used to create a passband filter response as shown in Figure 43.

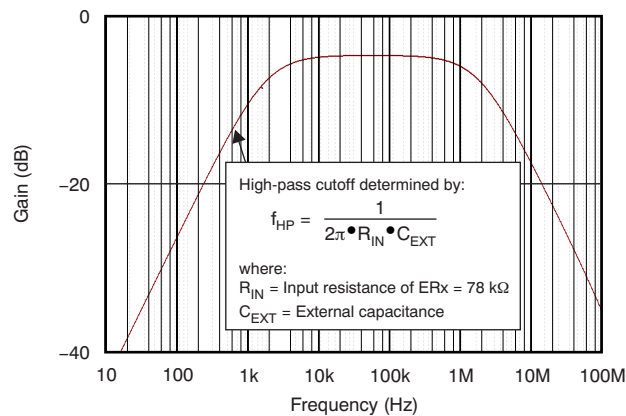


Figure 43. ERx Block Frequency Response

The E_Rx_Out pin can be directly connected to either an available analog-to-digital converter (ADC) input or GPIO on the host microcontroller. Figure 44 illustrates a typical two-wire application for ETx and ERx.

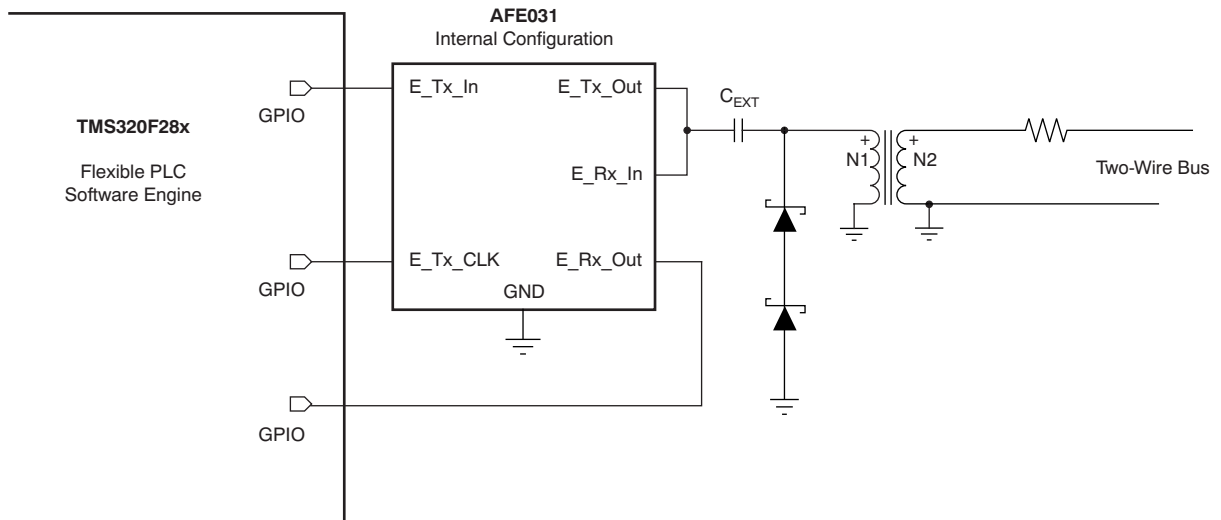


Figure 44. Typical Two-Wire Application for ETx and ERx

SERIAL INTERFACE

The AFE031 is controlled through a serial interface that allows read/write access to the control and data registers. A host SPI frame consists of a R/W bit, a 6-bit register address, and eight data bits. Data are shifted out on the falling edge of SCLK and latched on the rising edge of SCLK. Refer to the [Timing Diagrams](#) for a valid host SPI communications protocol. [Table 7](#) through [Table 16](#) show the complete register information.

Table 7. Data Register

REGISTER	ADDRESS	DEFAULT	FUNCTION
ENABLE1	0x01	0x00	Block enable or disable
GAIN SELECT	0x02	0x32	Rx and Tx gain select
ENABLE2	0x03	0x00	Block enable or disable
CONTROL1	0x04	0x00	Frequency select and calibration, Tx and Rx status
CONTROL2	0x05	0x01	Interrupt enable
RESET	0x09	0x00	Interrupt status and device reset
DIE_ID	0x0A	0x00	Die name
REVISION	0x0B	0x02	Die revision

Table 8. Command Register

BIT NAME	LOCATION (15 = MSB)	R/W	FUNCTION
ADDR8	8	W	Register address bit
ADDR9	9	W	Register address bit
ADDR10	10	W	Register address bit
ADDR11	11	W	Register address bit
ADDR12	12	W	Register address bit
ADDR13	13	W	Register address bit
ADDR14	14	W	Register address bit
R/W	15	W	Read/write: read = 1, write = 0

**Table 9. Enable1 Register: Address 0x01
Default: 0x00**

Enable1 Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
PA	0	0	R/W	This bit is used to enable/disable the PA Block. 0 = disabled, 1 = enabled.
TX	1	0	R/W	This bit is used to enable/disable the Tx Block. 0 = disabled, 1 = enabled.
RX	2	0	R/W	This bit is used to enable/disable the Rx Block. 0 = disabled, 1 = enabled.
ERX	3	0	R/W	This bit is used to enable/disable the ERx Block. 0 = disabled, 1 = enabled.
ETX	4	0	R/W	This bit is used to enable/disable the ETx Block. 0 = disabled, 1 = enabled.
DAC	5	0	R/W	This bit is used to enable/disable the DAC Block. 0 = DAC disabled; switch is connected to Tx_PGA_IN pin. 1 = DAC enabled; switch is connected to DAC output.
--	6	0	--	Reserved
--	7	0	--	Reserved

**Table 10. Gain Select Register: Address 0x02
Default: 0x32**

Gain Select Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
RX1G-0, RX1G-1	0, 1	0, 1	R/W	This bit is used to set the gain of the Rx PGA1. 00 = 0.25 V/V 01 = 0.5 V/V 10 = 1 V/V 11 = 2 V/V
RX2G-0, RX2G-1	2, 3	0, 0	R/W	This bit is used to set the gain of the Rx PGA2. 00 = 1 V/V 01 = 4 V/V 10 = 16 V/V 11 = 64 V/V
TXG-0, TXG-1	4, 5	1, 1	R/W	This bit is used to set the gain of the Tx PGA. 00 = 0.25 V/V 01 = 0.5 V/V 10 = 0.707 V/V 11 = 1 V/V
--	6	0	--	Reserved
--	7	0	--	Reserved

**Table 11. Enable2 Register: Address 0x03
Default: 0x00**

Enable2 Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
ZC	0	0	R/W	This bit is used to enable/disable the ZC Block. 0 = disabled, 1 = enabled.
REF1	1	0	R/W	This bit is used to enable/disable the REF1 Block. 0 = disabled, 1 = enabled.
REF2	2	0	R/W	This bit is used to enable/disable the REF2 Block. 0 = disabled, 1 = enabled.
PA_OUT	3	0	R/W	This bit is used to enable/disable the PA output stage. When the PA output stage is enabled it functions normally with a low output impedance, capable of driving heavy loads. When the PA output stage is disabled it is placed into a high impedance state. 0 = disabled, 1 = enabled.
--	4	0	--	Reserved
--	5	0	--	Reserved
--	6	0	--	Reserved
--	7	0	--	Reserved

**Table 12. Control1 Register: Address 0x04
Default: 0x00**

Control1 Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
TX_CAL	0	0	R/W	This bit is used to enable/disable the TX calibration mode. 0 = disabled, 1 = enabled.
RX_CAL	1	0	R/W	This bit is used to enable/disable the RX calibration mode. 0 = disabled, 1 = enabled.
TX_PGA_CAL	2	0	R/W	This bit is used to enable/disable the TX PGA calibration mode. 0 = disabled, 1 = enabled.
CA_CBCD	3	0	R/W	This bit is used to select the frequency response of the Tx Filter and Rx Filter. 0 = CENELEC A 1 = CENELEC B, C, D
--	4	0	--	Reserved
--	5	0	--	Reserved
TX_FLAG	6	0	R	This bit is used to indicate the status of the Tx Block. 0 = Tx Block is not ready for transmission. 1 = Tx Block is ready for transmission.
RX_FLAG	7	0	R	This bit is used to indicate the status of the Rx Block. 0 = Rx Block is not ready for reception. 1 = Rx Block is ready for reception.

**Table 13. Control2 Register: Address 0x05
Default: 0x01**

Control2 Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
--	0	0	--	Reserved
--	1	0	--	Reserved
--	2	0	--	Reserved
--	3	0	--	Reserved
--	4	0	--	Reserved
T_FLAG_EN	5	0	R/W	This bit is used to enable/disable the T_flag bit in the RESET Register. 0 = disabled, 1 = enabled.
I_FLAG_EN	6	0	R/W	This bit is used to enable/disable the I_flag bit in the RESET Register. 0 = disabled, 1 = enabled.
--	7	X	--	Reserved

**Table 14. RESET Register: Address 0x09
Default: 0x00**

Reset Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
--	0	0	--	Reserved
--	1	0	--	Reserved
SOFTRST0, SOFTRST1, SOFTRST2	2, 3, 4	0, 0, 0	W	These bits are used to perform a software reset of the ENABLE1, ENABLE2, CONTROL2, CONTROL3, and GAIN SELECT registers. Writing '101' to these registers performs a software reset.
T_FLAG	5	0	R/W	This bit is used to indicate the status of a PA thermal overload. 0 = On read, indicates that no thermal overload has occurred since the last reset. 0 = On write, resets this bit. 1 = On read, indicates that a thermal overload has occurred since the last reset. Remains latched until reset.
I_FLAG	6	0	R/W	This bit is used to indicate the status of a PA output current overload. 0 = On read indicates that no current overload has occurred since the last reset. 0 = On write, resets this bit. 1 = On read indicates that a current overload has occurred since the last reset. Remains latched until reset.
--	7	0	--	Reserved

**Table 15. DieID Register: Address 0x0A
Default: 0x00**

DieID Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
DIE ID<0>	0	0	R	The Die ID register is hard-wired.
DIE ID<1>	1	0	R	The Die ID register is hard-wired.
DIE ID<2>	2	0	R	The Die ID register is hard-wired.
DIE ID<3>	3	0	R	The Die ID register is hard-wired.
DIE ID<4>	4	0	R	The Die ID register is hard-wired.
DIE ID<5>	5	0	R	The Die ID register is hard-wired.
DIE ID<6>	6	0	R	The Die ID register is hard-wired.
DIE ID<7>	7	0	R	The Die ID register is hard-wired.

**Table 16. Revision Register: Address 0x0B
Default: 0x02**

Revision Register <7:0>				
BIT NAME	LOCATION (0 = LSB)	DEFAULT	R/W	FUNCTION
REVISION ID<0>	0	0	R	The revision register is hard-wired.
REVISION ID<1>	1	1	R	The revision register is hard-wired.
REVISION ID<2>	2	0	R	The revision register is hard-wired.
REVISION ID<3>	3	0	R	The revision register is hard-wired.
REVISION ID<4>	4	0	R	The revision register is hard-wired.
REVISION ID<5>	5	0	R	The revision register is hard-wired.
REVISION ID<6>	6	0	R	The revision register is hard-wired.
REVISION ID<7>	7	0	R	The revision register is hard-wired.

POWER SUPPLIES

The AFE031 has two low-voltage analog power-supply pins and one low-voltage digital supply pin. Internally, the two analog supply pins are connected to each other through back-to-back electrostatic discharge (ESD) protection diodes. These pins must be connected to each other on the application printed circuit board (PCB). It is also recommended to connect the digital supply pin and the two analog supply pins together on the PCB. Both low-voltage analog ground pins are also connected internally through back-to-back ESD protection diodes. These ground pins should also be connected to the digital ground pin on the PCB. It is recommended to bypass the low-voltage power supplies with a parallel combination of a 10- μ f and 100-nf capacitor. The PA block is biased separately from a high-voltage, high-current supply.

Two PA power supply pins and two PA ground pins are available to provide a path for the high currents associated with driving the low impedance of the ac mains. Connecting the two PA supply pins together is recommended. It is also recommended to place a bypass capacitor of 47 μ F to 100 μ F in parallel with 100 nF as close as possible to the AFE031. Care must be taken when routing the high current ground lines on the PCB to avoid creating voltage drops in the PCB ground that may vary with changes in load current.

The AFE031 has many options to enable or disable the functional blocks to allow for flexible power-savings modes. [Table 17](#) shows the specific power supply that each functional block draws power from, as well as the typical amount of power drawn from the associated power supplies for both the enabled and disabled states. For additional information on power-supply requirements refer to Application Report [SBOA130](#), *Analog Front-End Design for a Narrowband Power-Line Communications Modem Using the AFE031* (available for download at www.ti.com).

Table 17. Power Consumption with Enable and Disable Times (Typical)

BLOCK	STATUS	ENABLE TIME	DISABLE TIME	AVDD SUPPLY CURRENT	DVDD SUPPLY CURRENT	PA SUPPLY CURRENT
PA	On	10 μ s	–	–	–	61 mA
	Off	–	10 μ s	–	–	70 μ A
Tx	On	10 μ s	–	3.7 mA	–	–
	Off	–	10 μ s	1 μ A	–	–
Rx	On	10 μ s	–	5.3 mA	–	–
	Off	–	10 μ s	1 μ A	–	–
ERx	On	10 μ s	–	900 μ A	–	–
	Off	–	10 μ s	1 μ A	–	–
ETx	On	10 μ s	–	1.2 mA	–	–
	Off	–	10 μ s	1 μ A	–	–
DAC	On	10 μ s	–	–	16 μ A	–
	Off	–	10 μ s	–	1 μ A	–
ZC	On	10 μ s	–	25 μ A	–	–
	Off	–	10 μ s	1 μ A	–	–
REF1	On	10 μ s	–	–	–	26 μ A
	Off	–	10 μ s	–	–	8 μ A
REF2	On	10 μ s	–	25 μ A	–	–
	Off	–	10 μ s	4 μ A	–	–

PIN DESCRIPTIONS

DAC (Pin 7)

The DAC pin is used to configure the SPI to either read or write data to the Command and Data Registers, or to write data to the DAC register. Setting the DAC pin high allows access to the DAC register. Setting the DAC pin low allows access to the Command and Data Registers.

SD (Pin 8)

The Shutdown pin (SD) can be used to shut down the entire AFE031 for maximum power savings. When the SD pin is low, normal operation of the AFE031 occurs. When the SD pin is high, all circuit blocks within the AFE031, including the serial interface, are placed into the lowest-power operating modes. In this condition, the entire AFE031 draws only 95 μ A of current. All register contents at the time the AFE031 is placed into shutdown mode are saved; upon re-enabling the AFE031, the register contents retain the respective saved values.

INT Pin (9)

The Interrupt pin (INT) can be used to signal the microprocessor of an unusual operating condition that results from an anomaly on the ac mains. The INT pin can be triggered by two external circuit conditions, depending upon the Enable Register settings. The AFE031 can be programmed to issue an interrupt on these conditions:

- Current Overload
- Thermal Overload

Current Overload

The maximum output current allowed from the Power Amplifier can be programmed with the external R_{SET} resistor connected between PA_ISET (pin 46) and ground. If a fault condition should occur and cause an overcurrent event for the PA, the PA goes into current limit and the I_FLAG bit (location 6 in the [RESET Register](#)) is set to a '1' if the I_Flag_EN bit (location 6 in the [Control2 Register](#)) is enabled. This configuration results in an interrupt signal at the INT pin. The I_FLAG bit remains set to '1' even after the device returns to normal operation. The I_FLAG bit remains at '1' until it is reset by the microprocessor.

If the I_FLAG_EN bit (location 6 in the [Control2 Register](#)) is disabled and a current overload condition occurs, the PA goes into current-limit mode to protect the AFE031; however, the contents of the I_FLAG bit (location 6 in the [RESET Register](#)) remain at the respective previous values (presumably '0' for normal operation), and the AFE031 does not issue an interrupt at the INT pin.

Thermal Overload

The AFE031 contains internal protection circuitry that automatically disables the PA output stage if the junction temperature exceeds +150°C. If a fault condition occurs that causes a thermal overload, and if the T_FLAG_EN bit (location 5 in the [Control2 Register](#)) is enabled, the T_FLAG bit (location 5 in the [RESET Register](#)) is set to a '1'. This configuration results in an interrupt signal at the INT pin. The AFE031 includes a thermal hysteresis and allows the PA to resume normal operation when the junction temperature reduces to +135°C. The T_FLAG bit remains set to a '1' even after the device returns to normal operation. The T_FLAG bit remains '1' until it is reset by the microprocessor.

If the T_FLAG_EN bit (location 5 in the [Control2 Register](#)) is disabled and a thermal overload condition occurs, the PA continues to go into thermal limit and protect the AFE031, but the contents of the T_FLAG bit (location 5 in the [RESET Register](#)) remain at the previous value (presumably '0' for normal operation), and the AFE031 does not issue an interrupt at the INT pin.

Once an interrupt is signaled (that is, INT goes low), the contents of the I_FLAG and T_FLAG bits can be read by the microprocessor to determine the type of interrupt that occurred. Using the [Control2 Register](#), each interrupt type (current or thermal) can be individually enabled or disabled, allowing full user customization of the INT function. For proper operation of the interrupt pin it is recommended to configure the interrupt enable registers in the [Control2 Register](#) by writing to bit locations 5, 6, and 7 following the information in [Table 18](#) after each time the AFE031 is powered on. Failure to properly configure bit locations 5, 6, and 7 after power on may result in unexpected interrupt signals.

Table 18 lists the register contents associated with each interrupt condition.

Table 18. Register Contents to Configure the Interrupt Pin

FUNCTION	CONTROL2 REGISTER CONTENTS: DETERMINE INTERRUPT PIN FUNCTIONALITY		
	D7	I_FLAG_EN (CURRENT OVERLOAD)	T_FLAG_EN (THERMAL OVERLOAD)
		D6	D5
POR (default values)	undefined	0	0
No interrupt	0	0	0
Interrupt on thermal overload only	0	0	1
Interrupt on current overload only	0	1	0
Interrupt on thermal or current overload	0	1	1

TSENSE Pin (10)

The TSENSE pin is internally connected to the anode of a temperature-sensing diode located within the PA output stage. Figure 45 shows a remote junction temperature sensor circuit that can be used to measure the junction temperature of AFE031. Measuring the junction temperature of the AFE031 is optional and not required.

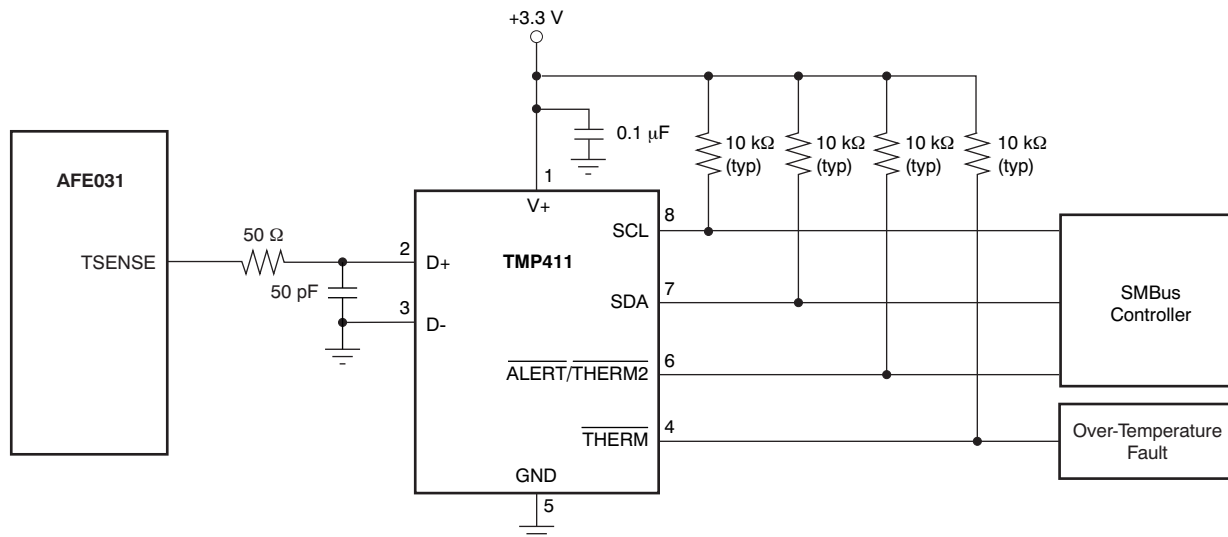


Figure 45. Interfacing the TMP411 to the AFE031

Tx_FLAG (Pin 47)

The Tx_FLAG pin is an open drain output that indicates the readiness of the Tx signal path for transmission. When the Tx_FLAG pin is high, the transmit signal path is enabled and ready for transmission. When the Tx_FLAG pin is low, the transmit path is not ready for transmission.

Rx_FLAG (Pin 48)

The Rx_FLAG pin is an open drain output that indicates the readiness of the Rx signal path for transmission. When the Rx_FLAG pin is high, the transmit signal path is enabled and ready for transmission. When the Rx_FLAG pin is low, the transmit path is not ready for transmission.

CALIBRATION MODES

The AFE031 can be configured for three different calibration modes: Tx Calibration, Rx Calibration, and Tx PGA Calibration. Calibration values can be determined during the calibration process and stored in system memory. A one-time calibration can be performed the first time that the system powers on; this calibration remains valid over the full temperature range and operating life of the AFE031, independent of the number of power-on/power-off cycles, as long as the calibration factors remain in the system memory. Calibration mode is accessed through the [Control1 Register](#). Note that calibration is not required.

Tx Calibration Mode

The Tx PGA + Tx Filter ac gain can be calibrated in Tx Calibration Mode. [Figure 46](#) shows the signal path during Tx Calibration mode.

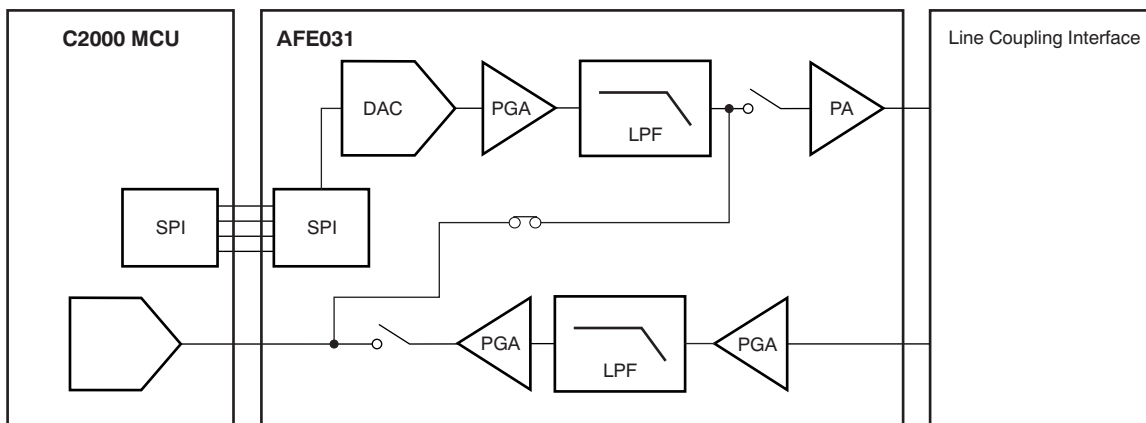


Figure 46. Tx Calibration Mode Configuration

Rx Calibration Mode

The Tx PGA + Rx PGA1 + Rx Filter + Rx PGA2 ac gain can be calibrated in Rx Calibration mode. [Figure 47](#) shows the signal path during Rx Calibration mode.

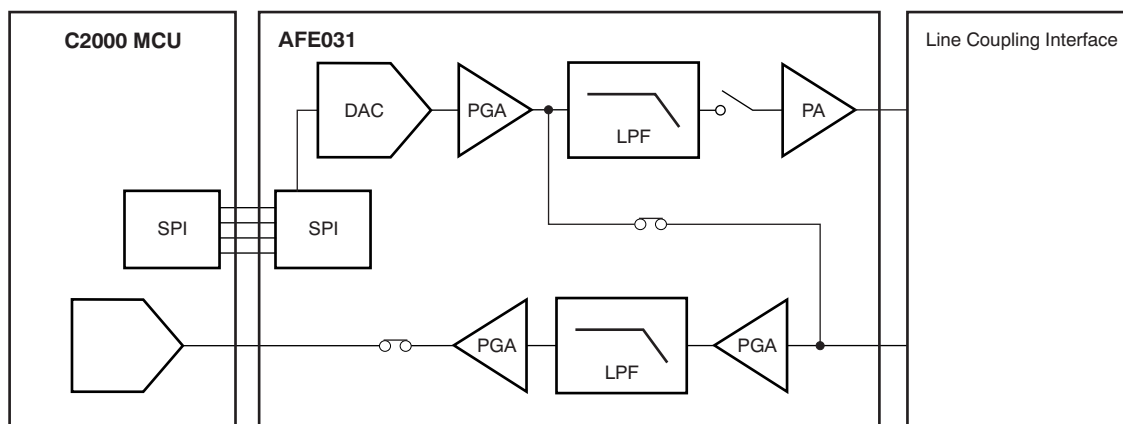


Figure 47. Rx Calibration Mode Configuration

Tx PGA Calibration Mode

The Tx PGA ac gain can be calibrated in Tx PGA Calibration mode. Figure 48 shows the signal path during Tx PGA Calibration mode.

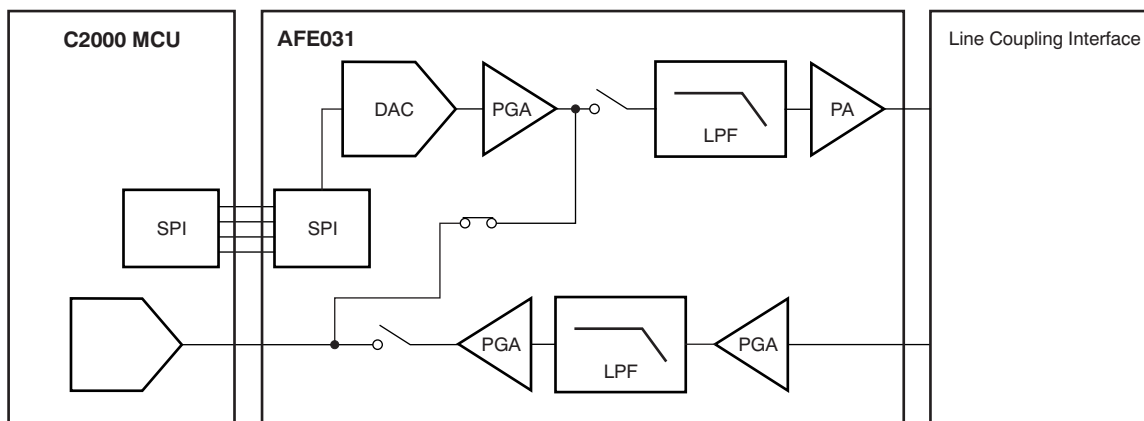
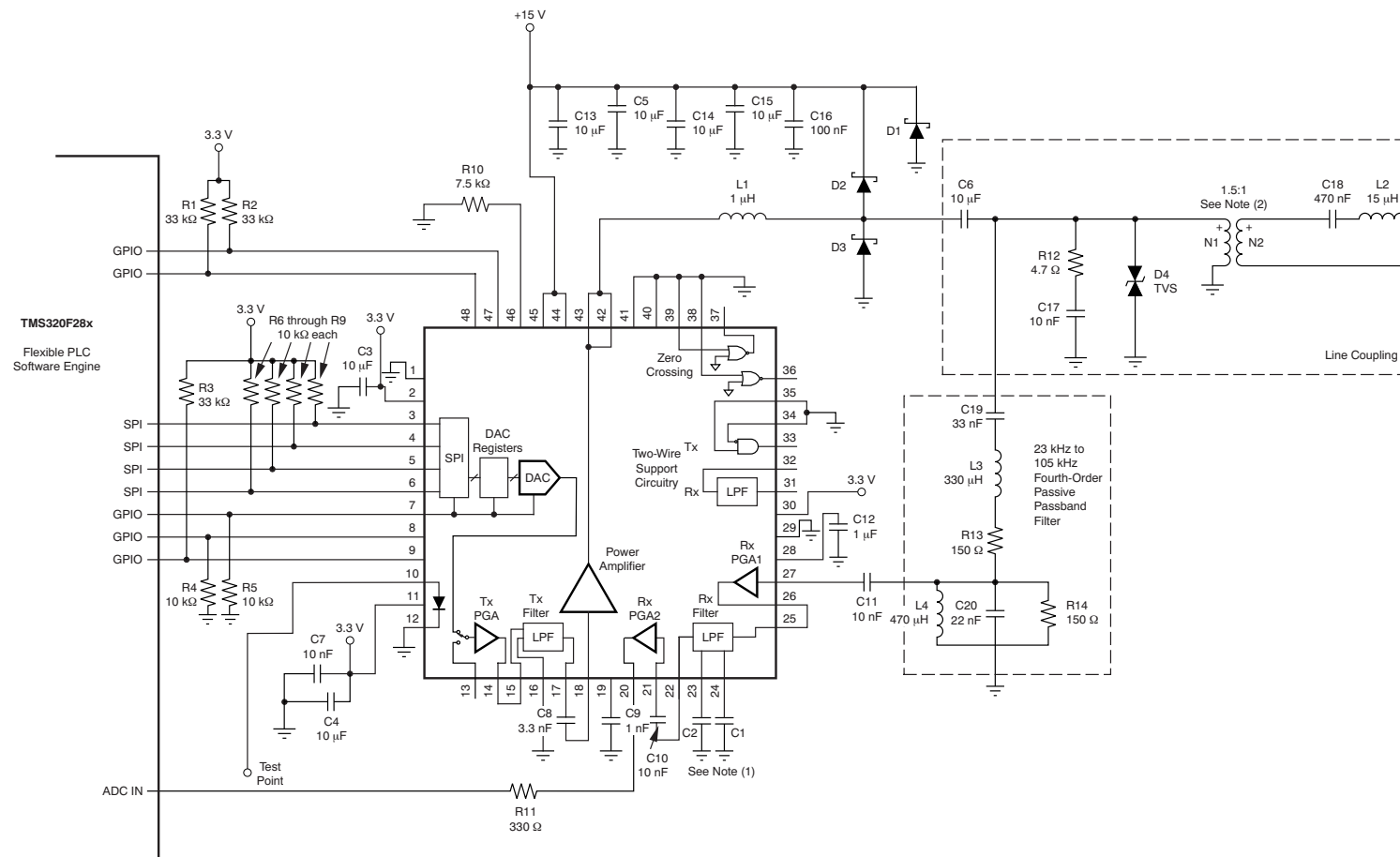


Figure 48. Tx PGA Calibration Mode Configuration

BASIC CONFIGURATION

Figure 49 shows the AFE031 configured in a typical PLC analog front-end application. The schematic shows the connections to the microprocessor and ac line. The values of the passive components in Figure 49 are suitable for a single-phase powerline communications application in the CENELEC A band, connected to a 120-VAC or 240-VAC, 50-Hz or 60-Hz ac line.



(1) Recommended values for C1 and C2:

1. C1:
 - CENELEC A: 680 pF
 - CENELEC B, C, D: 270 pF
2. C2:
 - CENELEC A: 680 pF
 - CENELEC B, C, D: 560 pF

Figure 49. Typical Powerline Communications Modem Application

LINE-COUPLING CIRCUIT

The line-coupling circuit is one of the most critical circuits in a powerline modem. The line-coupling circuit has two primary functions: first, to block the low-frequency signal of the mains (commonly 50 Hz or 60 Hz) from damaging the low-voltage modem circuitry; second, to couple the modem signal to and from the ac mains. A typical line-coupling circuit is shown in Figure 50.

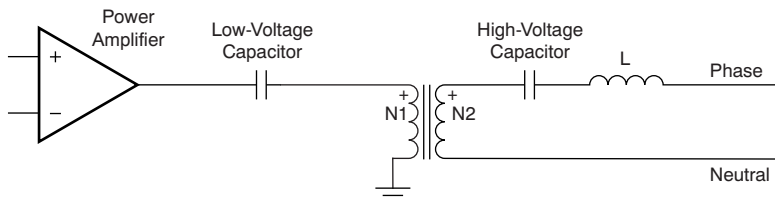


Figure 50. Simplified Line Coupling Circuit

For additional information on line-coupling interfaces with the AFE031, refer to Application Report [SBOA130, Analog Front-End Design for a Narrowband Power-Line Communications Modem Using the AFE031](#) (available for download at [www.ti.com](#)).

CIRCUIT PROTECTION

Powerline communications are often located in operating environments that are harsh for electrical components connected to the ac line. Noise or surges from electrical anomalies such as lightning, capacitor bank switching, inductive switching, or other grid fault conditions can damage high-performance integrated circuits if they are not properly protected. The AFE031 can survive even the harshest conditions if several recommendations are followed.

First, dissipate as much of the electrical disturbance before it reaches the AFE031 with a multi-layer approach using metal-oxide varistors (MOVs), transient voltage suppression diodes (TVSs), Schottky diodes, and a Zener diode. Figure 51 shows the recommended strategy for transient overvoltage protection.

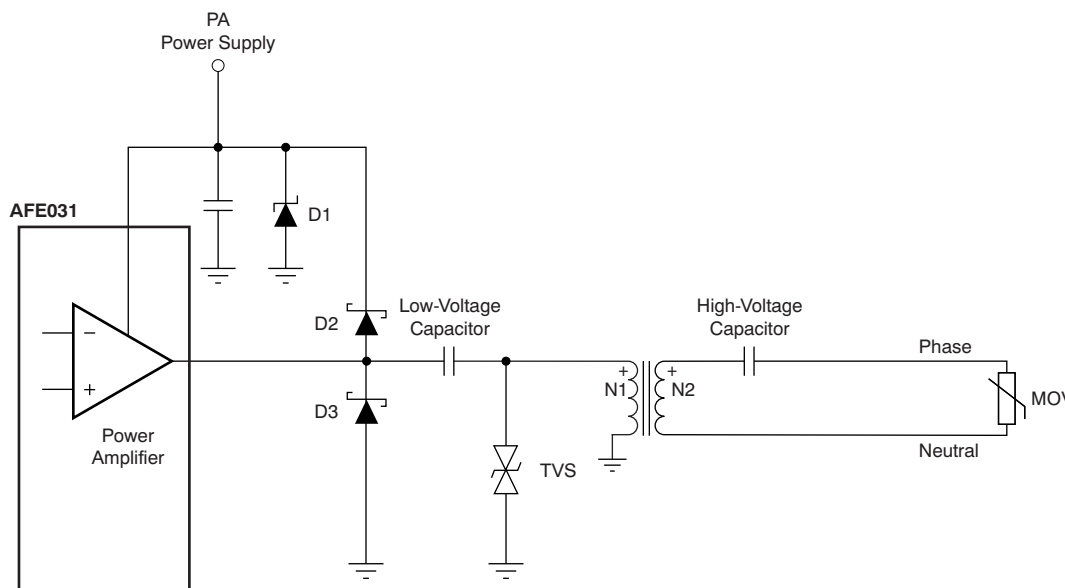


Figure 51. Transient Overvoltage Protection for AFE031

Note that the high-voltage coupling capacitor must be able to withstand pulses up to the clamping protection provided by the MOV. A metalized polypropylene capacitor, such as the 474MKP275KA from Illinois Capacitor, Inc., is rated for 50 Hz to 60 Hz, 250 VAC to 310 VAC, and can withstand 24 impulses of 2.5 kV.

Table 19 lists several recommended transient protection components.

Table 19. Recommended Transient Protection Devices

COMPONENT	120 VAC, 60 Hz		
	DESCRIPTION	MANUFACTURER	MFR PART NO (OR EQUIVALENT)
D1	Zener diode	Diodes, Inc.	1SMB59xxB ⁽¹⁾
D2, D3	Schottky diode	Diodes, Inc.	1N5819HW
TVS	Transient voltage suppressor	Diodec Semiconductor	P6SMBJxxC ⁽²⁾
MOV	Varistor	LittleFuse	TMOV20RP140E
HV Cap	High-voltage capacitor	Illinois Capacitor, Inc	474MKP275KA ⁽³⁾
COMPONENT	240 VAC, 50 Hz		
	DESCRIPTION	MANUFACTURER	MFR PART NO (OR EQUIVALENT)
D1	Zener diode	Diodes, Inc.	1SMB59xxB ⁽¹⁾
D2, D3	Schottky diode	Diodes, Inc.	1N5819HW
TVS	Transient voltage suppressor	Diodec Semiconductor	P6SMBJxxC ⁽²⁾
MOV	Varistor	LittleFuse	TMOV20RP300E
HV Cap	High-voltage capacitor	Illinois Capacitor, Inc	474MKP275KA ⁽³⁾

- (1) Select the Zener breakdown voltage at the lowest available rating beyond the normal power-supply operating range.
- (2) Select the TVS breakdown voltage at or slightly greater than $(0.5 \bullet PA_{VS})$.
- (3) A common value for the high-voltage capacitor is 470 nF. Other values may be substituted depending on the requirements of the application. Note that when making a substitution, it is important in terms of reliability that the capacitor be selected from the same family or equivalent family of capacitors rated to withstand high-voltage surges.

THERMAL CONSIDERATIONS

In a typical powerline communications application, the AFE031 dissipates 2 W of power when transmitting into the low impedance of the ac line. This amount of power dissipation can increase the junction temperature, which in turn can lead to a thermal overload that results in signal transmission interruptions if the proper thermal design of the PCB has not been performed. Proper management of heat flow from the AFE031 as well as good PCB design and construction are required to ensure proper device temperature, maximize performance, and extend device operating life.

The AFE031 is assembled into a 7-mm² x 7-mm², 48-lead, QFN package. As Figure 52 shows, this QFN package has a large area exposed thermal pad on the underside that is used to conduct heat away from the AFE031 and into the underlying PCB.

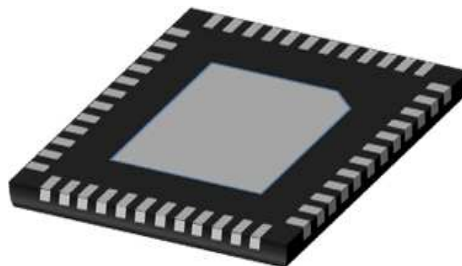


Figure 52. QFN Package with Large Area Exposed Thermal Pad

Some heat is conducted from the silicon die surface through the plastic packaging material and is transferred into the ambient environment. Because plastic is a relatively poor conductor of heat, however, this route is not the primary thermal path for heat flow. Heat also flows across the silicon die surface to the bond pads, through the wire bonds, into the package leads, and finally into the top layer of the PCB. While both of these paths for heat flow are important, the majority (nearly 80%) of the heat flows downward, through the silicon die, into the thermally-conductive die attach epoxy, and into the exposed thermal pad on the underside of the package (see Figure 53). Minimizing the thermal resistance of this downward path to the ambient environment maximizes the life and performance of the device.

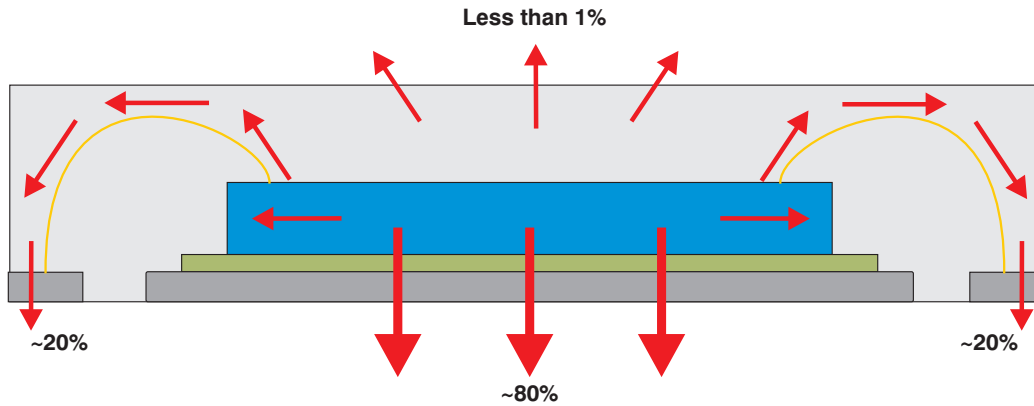


Figure 53. Heat Flow in the QFN Package

The exposed thermal pad must be soldered to the PCB thermal pad. The thermal pad on the PCB should be the same size as the exposed thermal pad on the underside of the QFN package. Refer to Application Report, *QFN/SON PCB Attachment*, literature number [SLUA271A](#), for recommendations on attaching the thermal pad to the PCB. Figure 54 illustrates the direction of heat spreading into the PCB from the device.

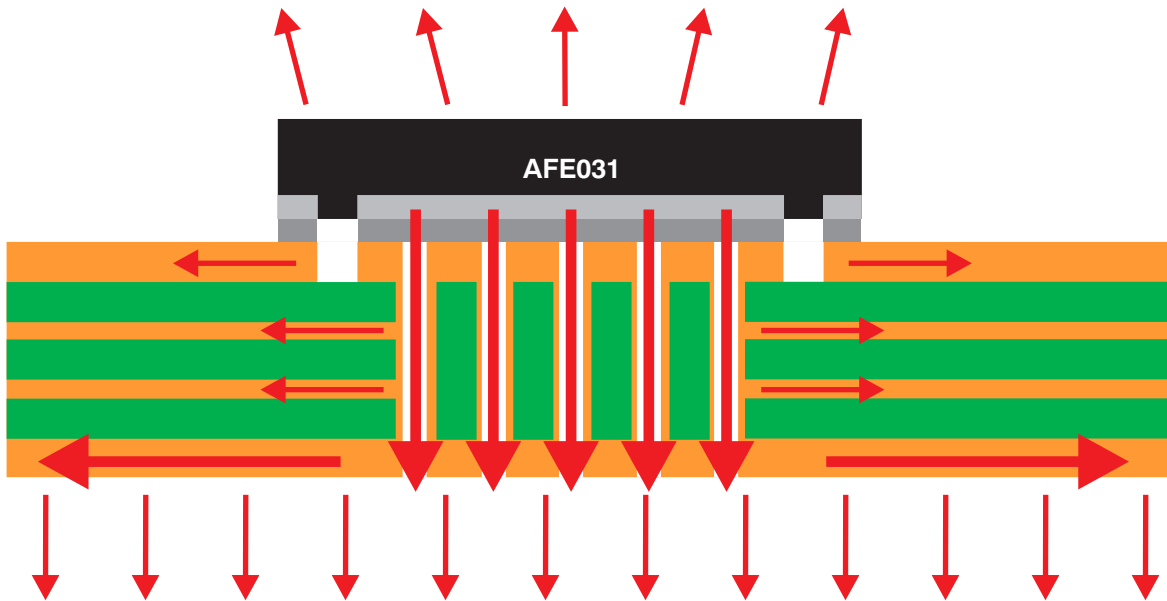


Figure 54. Heat Spreading into PCB

The heat spreading into the PCB is maximized if the thermal path is uninterrupted. Best results are achieved if the heat-spreading surfaces are filled with copper to the greatest extent possible, maximizing the percent area covered on each layer. As an example, a thermally robust, multilayer PCB design may consist of four layers with copper (Cu) coverage of 60% in the top layer, 85% and 90% in the inner layers, respectively, and 95% on the bottom layer.

Increasing the number of layers in the PCB, using thicker copper, and increasing the PCB area are all factors that improve the spread of heat. Figure 55 through Figure 57, respectively, show thermal resistance performance as a function of each of these factors.

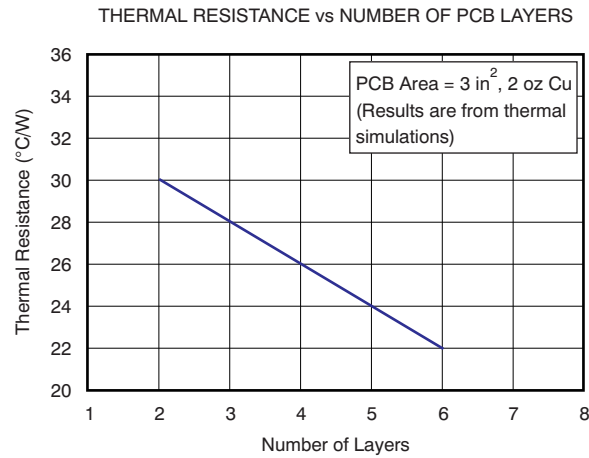


Figure 55. Thermal Resistance as a Function of the Number of Layers in the PCB

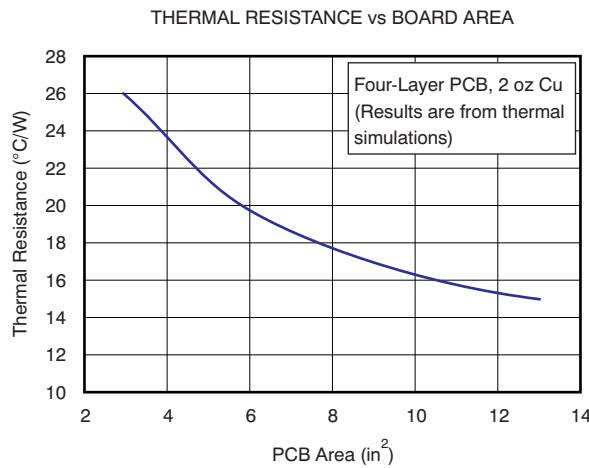


Figure 56. Thermal Resistance as a Function of PCB Area

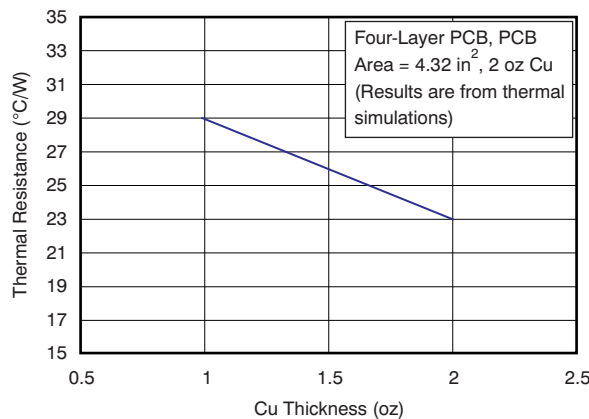


Figure 57. Thermal Resistance as a Function of Copper Thickness

For additional information on thermal PCB design using exposed thermal pad packages, refer to Application Report [SBOA130](#), *Analog Front-End Design for a Narrowband Power-Line Communications Modem Using the AFE031* and Application Report [SLMA002E](#), *PowerPAD™ Thermally-Enhanced Package* (both available for download at www.ti.com).

Powerline Communications Developer's Kit

A PLC developer's kit ([TMDSPCKIT-V3](#)) is available to order at www.ti.com/plc. This kit offers complete hardware and software solutions for introducing flexible, efficient, and reliable networking capabilities to a wide variety of applications. With unique modular hardware architecture and flexible software framework, TI's PLC solutions are the only PLC-based technology capable of supporting multiple protocol standards and modulation schemes with a single platform. This technology enables designers to leverage product lines across global markets. The flexibility of the platform also allows developers to optimize hardware and software performance for specific environmental operating conditions while simplifying end-to-end product design. Based on TI's powerful C2000™ microcontroller architecture and the AFE031, developers can select the correct blend of processing capacity and peripherals to either add powerline communications to an existing design or implement a complete application with PLC communications.

The C2000 Powerline Modem Developer's Kit enables easy development of software-based PLC modems. The kit includes two PLC modems based on the C2000 TMS320F28069 controlCARD and the AFE031. The included PLC SUITE software supports several communication techniques, including OFDM (PRIME/G3 and FlexOFDM) and SFSK. The kit also includes onboard USB JTAG emulation and Code Composer Studio.

PACKAGING/MECHANICALS

Complete mechanical drawings and packaging information are appended to the end of this data sheet.

REVISION HISTORY

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision C (March 2012) to Revision D	Page
• Updated Figure 32	26
• Updated Figure 34	28

Changes from Revision B (September 2011) to Revision C	Page
• Changed transmit power amplifier operating range description in <i>Description</i> section	1
• Added cross-reference to footnote 2 to <i>Output short-circuit</i> parameter in Absolute Maximum Ratings table	2
• Changed Frequency Response, <i>Passband frequency</i> (B/C/D Modes) parameter minimum and typical specifications in Electrical Characteristics: Receiver (Rx)	6
• Deleted Digital Outputs (INT, Tx_Flag, Rx_Flag), <i>INT pin high</i> , <i>INT pin low</i> , <i>Tx_Flag high</i> , <i>Tx_Flag low</i> , <i>Rx_Flag high</i> , and <i>Rx_Flag low</i> parameter units from Electrical Characteristics: Digital	8
• Changed Digital Outputs (INT, Tx_Flag, Rx_Flag), <i>Tx_Flag high</i> , <i>Tx_Flag low</i> , <i>Rx_Flag high</i> , and <i>Rx_Flag low</i> parameter specification descriptions in Electrical Characteristics: Digital	8
• Changed Operating Supply Range, <i>Power amplifier supply voltage</i> parameter maximum specification in Electrical Characteristics: Power Supply	10
• Changed title of Figure 20	18
• Changed description of PA operating range in <i>PA Block</i> section	21
• Updated Equation 2	22
• Changed proper design margin note in <i>PA Block</i> section	22
• Updated Figure 35	29
• Changed description of <i>REF1 and REF2 Blocks</i> section	30
• Changed title of Table 9	35
• Changed second paragraph of <i>Power Supplies</i> section	39

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	Eco Plan ⁽²⁾	Lead/ Ball Finish	MSL Peak Temp ⁽³⁾	Samples (Requires Login)
AFE031AIRGZR	ACTIVE	VQFN	RGZ	48	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
AFE031AIRGZT	ACTIVE	VQFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	
COMBOSOLAR	ACTIVE			0		TBD	Call TI	Call TI	

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

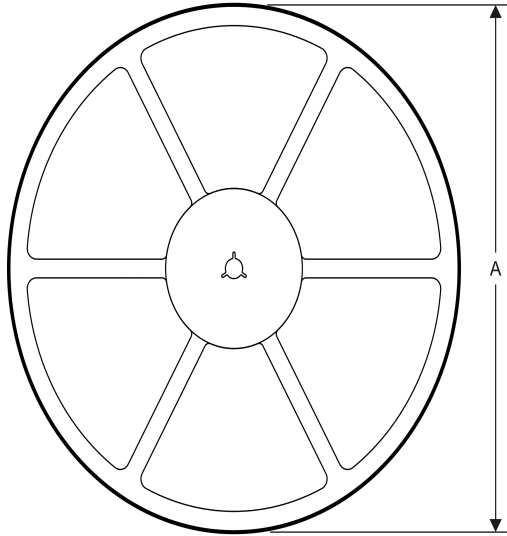
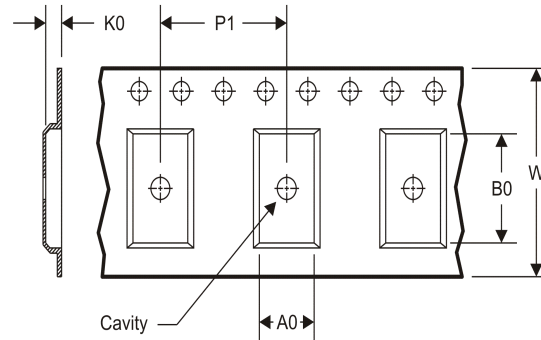
Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION
REEL DIMENSIONS

TAPE DIMENSIONS


A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

TAPE AND REEL INFORMATION

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
AFE031AIRGZR	VQFN	RGZ	48	2500	330.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
AFE031AIRGZT	VQFN	RGZ	48	250	180.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2

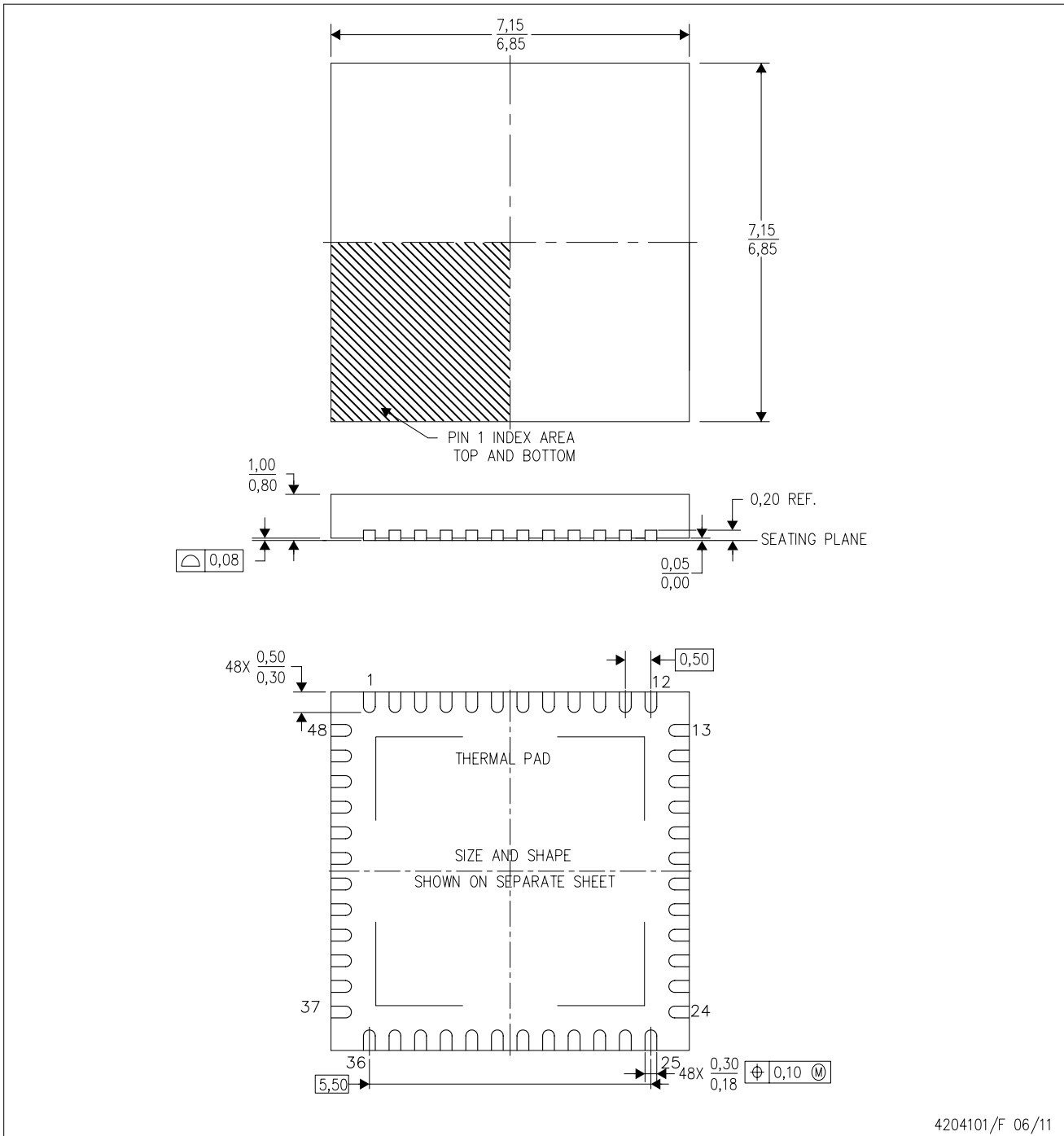
TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
AFE031AIRGZR	VQFN	RGZ	48	2500	367.0	367.0	38.0
AFE031AIRGZT	VQFN	RGZ	48	250	210.0	185.0	35.0

RGZ (S-PVQFN-N48)

PLASTIC QUAD FLATPACK NO-LEAD



- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - B. This drawing is subject to change without notice.
 - C. Quad Flatpack, No-leads (QFN) package configuration.
 - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
 - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
 - F. Falls within JEDEC MO-220.

THERMAL PAD MECHANICAL DATA

RGZ (S-PVQFN-N48)

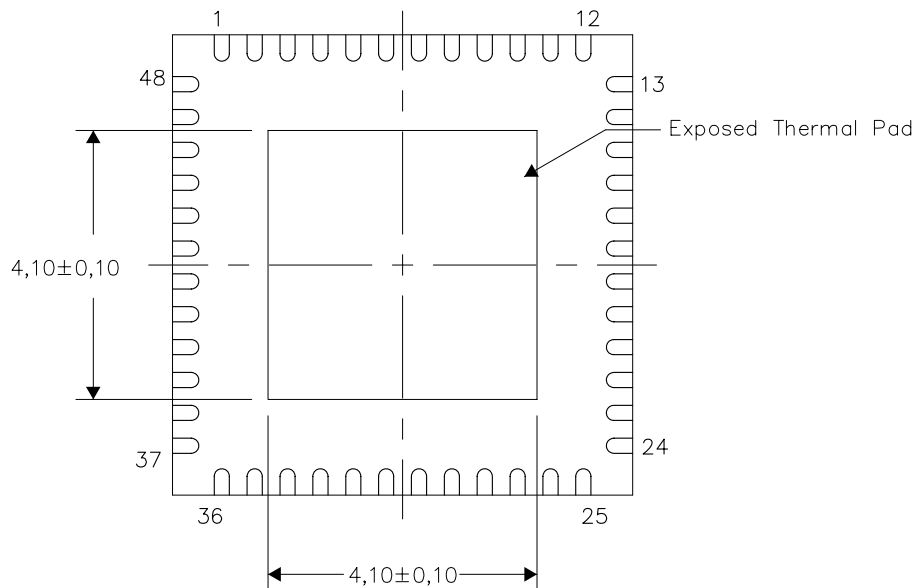
PLASTIC QUAD FLATPACK NO-LEAD

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



Bottom View

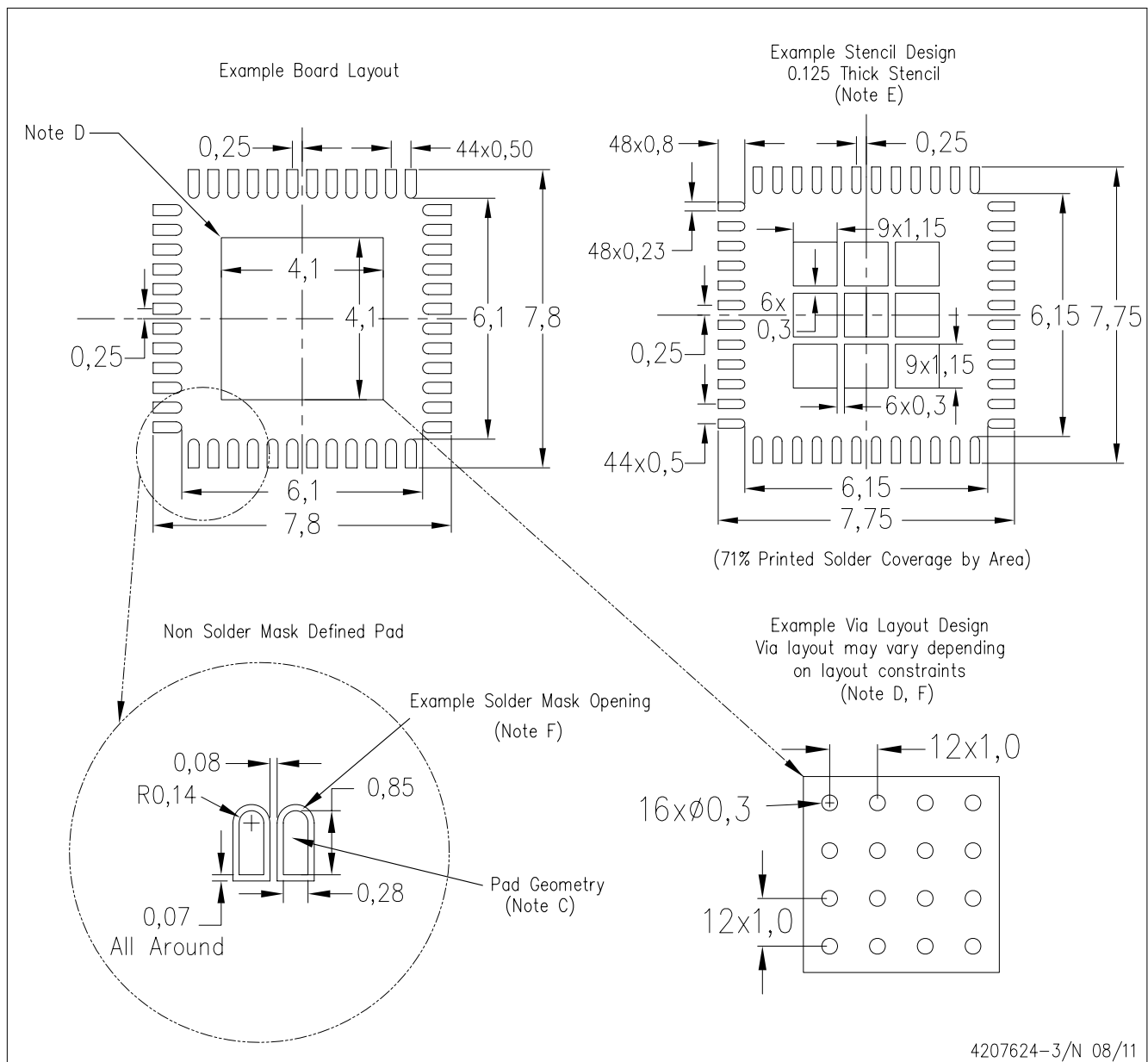
Exposed Thermal Pad Dimensions

4206354-3/R 08/11

NOTE: All linear dimensions are in millimeters

RGZ (S-PVQFN-N48)

PLASTIC QUAD FLATPACK NO-LEAD



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Publication IPC-7351 is recommended for alternate designs.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>.
 - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
 - Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46C and to discontinue any product or service per JESD48B. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have **not** been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components which meet ISO/TS16949 requirements, mainly for automotive use. Components which have not been so designated are neither designed nor intended for automotive use; and TI will not be responsible for any failure of such components to meet such requirements.

Products

Audio	www.ti.com/audio
Amplifiers	amplifier.ti.com
Data Converters	dataconverter.ti.com
DLP® Products	www.dlp.com
DSP	dsp.ti.com
Clocks and Timers	www.ti.com/clocks
Interface	interface.ti.com
Logic	logic.ti.com
Power Mgmt	power.ti.com
Microcontrollers	microcontroller.ti.com
RFID	www.ti-rfid.com
OMAP Mobile Processors	www.ti.com/omap
Wireless Connectivity	www.ti.com/wirelessconnectivity

Applications

Automotive and Transportation	www.ti.com/automotive
Communications and Telecom	www.ti.com/communications
Computers and Peripherals	www.ti.com/computers
Consumer Electronics	www.ti.com/consumer-apps
Energy and Lighting	www.ti.com/energy
Industrial	www.ti.com/industrial
Medical	www.ti.com/medical
Security	www.ti.com/security
Space, Avionics and Defense	www.ti.com/space-avionics-defense
Video and Imaging	www.ti.com/video

TI E2E Community e2e.ti.com